

## Single-channel high-side driver with analog current sense for automotive applications

### Features

Max supply voltage	V <sub>CC</sub>	41 V
Operating voltage range	V <sub>CC</sub>	4.5 V to 28 V
Typ. ON-state resistance	R <sub>ON</sub>	10 mΩ
Current limitation (typ)	I <sub>LIMH</sub>	85 A
OFF-state supply current	I <sub>S</sub>	2 μA <sup>(1)</sup>

1. Typical value with all loads connected.

#### ■ General

- Inrush current active management by power limitation
- Very low standby current
- 3 V CMOS compatible inputs
- Optimized electromagnetic emissions
- Very low electromagnetic susceptibility
- In compliance with the 2002/95/EC european directive
- Very low current sense leakage

#### ■ Diagnostic functions

- Proportional load current sense
- High current sense precision for wide current range
- Current sense disable
- Output short to ground indication
- Overload and short to ground (power limitation) indication
- Thermal shutdown indication

#### ■ Protections

- Undervoltage shutdown
- Overvoltage clamp
- Load current limitation
- Self limiting of fast thermal transients
- Protection against loss of ground and loss of V<sub>CC</sub>
- Overtemperature shutdown with autorestart (thermal shutdown)



- Reverse battery protection with self switch on of the Power MOSFET
- Electrostatic discharge protection

### Application

- All types of resistive, inductive and capacitive loads

### Description

The VN5E010MH-E is a single-channel high-side driver manufactured in the ST proprietary VIPower M0-5 technology and housed in the tiny HPAK package. The VN5E010MH-E is designed to drive 12 V automotive grounded loads delivering protection, diagnostics and easy 3 V and 5 V CMOS compatible interface with any microcontroller.

The device integrates advanced protective functions such as load current limitation, inrush and overload active management by power limitation, overtemperature shut-off with auto restart and overvoltage active clamp.

A dedicated analog current sense pin is associated with every output channel in order to provide enhanced diagnostic functions including fast detection of overload and short-circuit to ground through power limitation indication and overtemperature indication.

The current sensing and diagnostic feedback of the whole device can be disabled by pulling the CS\_DIS pin high to allow sharing of the external sense resistor with other similar devices.

## Contents

<b>1</b>	<b>Block diagram and pin configuration</b>	<b>5</b>
<b>2</b>	<b>Electrical specifications</b>	<b>7</b>
2.1	Absolute maximum ratings	7
2.2	Thermal data	8
2.3	Electrical characteristics	9
2.4	Waveforms	17
2.5	Electrical characteristics curves	19
2.6	Application information	22
2.7	Load dump protection	22
2.8	MCU I/Os protection	22
2.9	Current sense and diagnostic	23
2.10	Maximum demagnetization energy ( $V_{CC} = 13.5$ V)	24
<b>3</b>	<b>Package and PC board thermal data</b>	<b>25</b>
3.1	HPAK thermal data	25
<b>4</b>	<b>Package and packing information</b>	<b>28</b>
4.1	ECOPACK®	28
4.2	HPAK mechanical data	28
4.3	HPAK suggested land pattern	30
4.4	Packing information	31
<b>5</b>	<b>Order codes</b>	<b>32</b>
<b>6</b>	<b>Revision history</b>	<b>33</b>

## List of tables

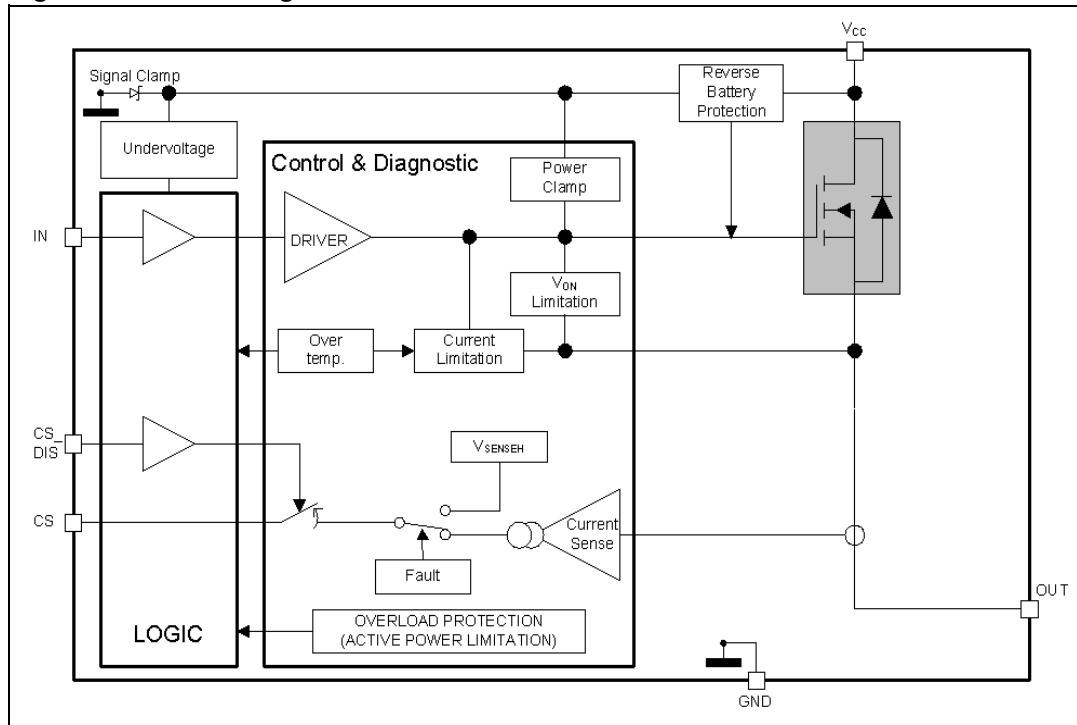
Table 1.	Pin functions . . . . .	5
Table 2.	Suggested connections for unused and not connected pins . . . . .	6
Table 3.	Absolute maximum ratings . . . . .	7
Table 4.	Thermal data. . . . .	8
Table 5.	Power section . . . . .	9
Table 6.	Switching ( $V_{CC} = 13\text{ V}$ , $T_j = 25\text{ }^\circ\text{C}$ ) . . . . .	9
Table 7.	Logic inputs. . . . .	10
Table 8.	Protection and diagnostics . . . . .	10
Table 9.	Current sense ( $8\text{ V} < V_{CC} < 18\text{ V}$ ). . . . .	11
Table 10.	Truth table. . . . .	15
Table 11.	Electrical transient requirements (part 1) . . . . .	16
Table 12.	Electrical transient requirements (part 2) . . . . .	16
Table 13.	Electrical transient requirements (part 3) . . . . .	16
Table 14.	Thermal parameter. . . . .	27
Table 15.	HPAK mechanical data. . . . .	29
Table 16.	Device summary. . . . .	32
Table 17.	Document revision history . . . . .	33

## List of figures

Figure 1.	Block diagram . . . . .	5
Figure 2.	Configuration diagram (top view) not in scale . . . . .	6
Figure 3.	Current and voltage conventions . . . . .	7
Figure 4.	Current sense delay characteristics . . . . .	12
Figure 5.	Switching characteristics . . . . .	13
Figure 6.	Delay response time between rising edge of output current and rising edge of current sense (CS enabled). . . . .	13
Figure 7.	Output voltage drop limitation . . . . .	14
Figure 8.	$I_{OUT}/I_{SENSE}$ vs. $I_{OUT}$ . . . . .	14
Figure 9.	Maximum current sense ratio drift vs. load current <sup>(1)</sup> . . . . .	15
Figure 10.	Normal operation . . . . .	17
Figure 11.	Overload or short to GND . . . . .	17
Figure 12.	Intermittent overload . . . . .	18
Figure 13.	$T_J$ evolution in overload or short to GND . . . . .	18
Figure 14.	OFF-state output current . . . . .	19
Figure 15.	High-level input current . . . . .	19
Figure 16.	Input clamp voltage . . . . .	19
Figure 17.	Low-level input voltage . . . . .	19
Figure 18.	High-level input voltage . . . . .	19
Figure 19.	Input hysteresis voltage . . . . .	19
Figure 20.	ON-state resistance vs. $T_{case}$ . . . . .	20
Figure 21.	ON-state resistance vs. $V_{CC}$ . . . . .	20
Figure 22.	Undervoltage shutdown . . . . .	20
Figure 23.	Turn-on voltage slope . . . . .	20
Figure 24.	$ILIMH$ vs. $T_{case}$ . . . . .	20
Figure 25.	Turn-off voltage slope . . . . .	20
Figure 26.	High-level CS_DIS voltage . . . . .	21
Figure 27.	CS_DIS clamp voltage . . . . .	21
Figure 28.	Low-level CS_DIS voltage . . . . .	21
Figure 29.	Application schematic . . . . .	22
Figure 30.	Current sense and diagnostic . . . . .	23
Figure 31.	Maximum turn-off current versus inductance <sup>(1)</sup> . . . . .	24
Figure 32.	PC board <sup>(1)</sup> . . . . .	25
Figure 33.	$R_{thj-amb}$ vs. PCB copper area in open box free air condition . . . . .	25
Figure 34.	HPAK thermal impedance junction ambient single pulse . . . . .	26
Figure 35.	Thermal fitting model of a single-channel HSD in HPAK <sup>(1)</sup> . . . . .	26
Figure 36.	HPAK package dimension . . . . .	28
Figure 37.	HPAK suggested pad layout <sup>(1)</sup> . . . . .	30
Figure 38.	HPAK tube shipment (no suffix) . . . . .	31
Figure 39.	HPAK tape and reel (suffix "TR") . . . . .	31

# 1 Block diagram and pin configuration

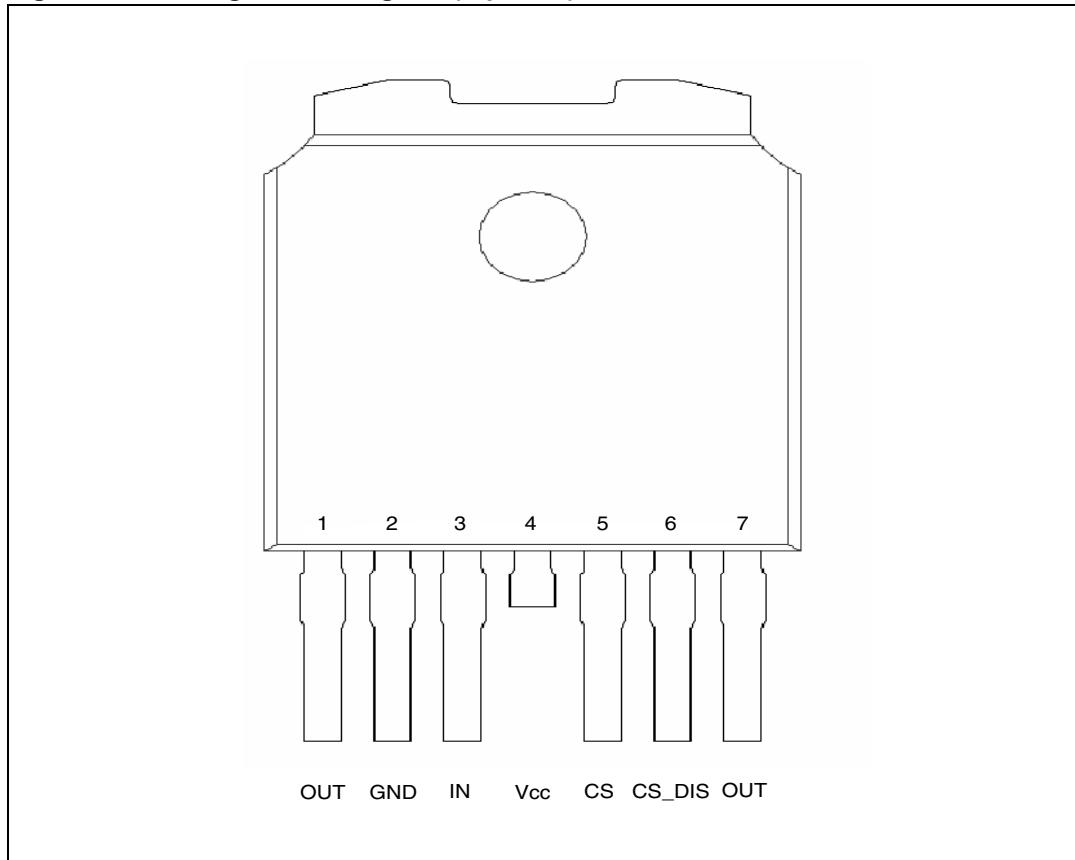
**Figure 1. Block diagram**



**Table 1. Pin functions**

Name	Function
V <sub>CC</sub>	Battery connection
OUT	Power output <sup>(1)</sup>
GND	Ground connection
IN	Voltage controlled input pin with hysteresis, CMOS compatible. Controls output switch state
CS	Analog current sense pin, delivers a current proportional to the load current
CS_DIS	Active high CMOS compatible pin, to disable the current sense pin

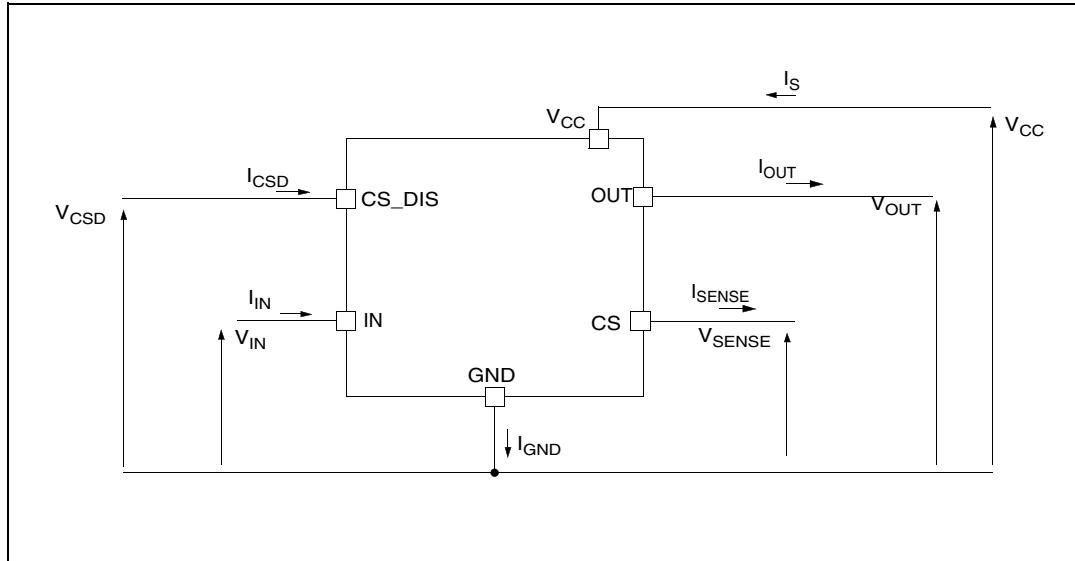
1. Pins 1 and 7 must be externally tied together.

**Figure 2. Configuration diagram (top view) not in scale****Table 2. Suggested connections for unused and not connected pins**

Connection / pin	CS	OUT	IN	CS_DIS
Floating	Not allowed	X	X	X
To ground	Through 1kΩ resistor	Through 22 kΩ resistor	Through 10 kΩ resistor	Through 10 kΩ resistor

## 2 Electrical specifications

**Figure 3.** Current and voltage conventions



### 2.1 Absolute maximum ratings

Stressing the device above the rating listed in the *Table 3: Absolute maximum ratings* may cause permanent damage to the device. These are stress ratings only and operation of the device at these or any other conditions above those indicated in the operating sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability. Refer also to the STMicroelectronics SURE program and other relevant quality document.

**Table 3.** Absolute maximum ratings

Symbol	Parameter	Value	Unit
V <sub>CC</sub>	DC supply voltage	41	V
-V <sub>CC</sub>	Reverse DC supply voltage	16	V
I <sub>OUT</sub>	DC output current	Internally limited	A
-I <sub>OUT</sub>	Reverse DC output current	20	A
I <sub>IN</sub>	DC input current	-1 to 10	mA
I <sub>CSD</sub>	DC current sense disable input current	-1 to 10	mA
V <sub>CSENSE</sub>	Current sense maximum voltage (V <sub>CC</sub> > 0)	V <sub>CC</sub> - 41 +V <sub>CC</sub>	V V
E <sub>MAX</sub>	Maximum switching energy (single pulse) (L = 2.2 mH; R <sub>L</sub> = 0 Ω; V <sub>BAT</sub> = 13.5 V; T <sub>jstart</sub> = 150 °C; I <sub>OUT</sub> = I <sub>limL</sub> (Typ.)	645	mJ

**Table 3. Absolute maximum ratings (continued)**

Symbol	Parameter	Value	Unit
$V_{ESD}$	Electrostatic discharge (human body model: $R = 1.5 \text{ k}\Omega$ ; $C = 100 \text{ pF}$ )		
	- IN	4000	V
	- CS	2000	V
	- CS_DIS	4000	V
	- OUT	5000	V
	- $V_{CC}$	5000	V
$V_{ESD}$	Charge device model (CDM-AEC-Q100-011)	750	V
$T_j$	Junction operating temperature	-40 to 150	°C
$T_{stg}$	Storage temperature	-55 to 150	°C

## 2.2 Thermal data

**Table 4. Thermal data**

Symbol	Parameter	Max. value	Unit
$R_{thj-case}$	Thermal resistance junction-case	0.55	°C/W
$R_{thj-amb}$	Thermal resistance junction-ambient	67.7	°C/W

## 2.3 Electrical characteristics

Values specified in this section are for  $8 \text{ V} < V_{CC} < 28 \text{ V}$ ,  $-40^\circ\text{C} < T_j < 150^\circ\text{C}$ , unless otherwise specified.

**Table 5. Power section**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$V_{CC}$	Operating supply voltage		4.5	13	28	V
$V_{USD}$	Undervoltage shutdown			3.5	4.5	V
$V_{USDhyst}$	Undervoltage shutdown hysteresis			0.5		V
$R_{ON}$	ON-state resistance	$I_{OUT} = 6 \text{ A}; T_j = 25^\circ\text{C}$		10		
		$I_{OUT} = 6 \text{ A}; T_j = 150^\circ\text{C}$			20	$\text{m}\Omega$
		$I_{OUT} = 6 \text{ A}; V_{CC} = 5 \text{ V}; T_j = 25^\circ\text{C}$			13	
$R_{ON-Rev}$	$R_{DS(ON)}$ in reverse battery condition	$V_{CC} = -13 \text{ V}; I_{OUT} = -6 \text{ A}; T_j = 25^\circ\text{C}$		10		$\text{m}\Omega$
$V_{clamp}$	Clamp voltage	$I_{CC} = 20 \text{ mA}; I_{OUT} = 0 \text{ A}$	41	46	52	V
$I_S$	Supply current	OFF-state: $V_{CC} = 13 \text{ V}; T_j = 25^\circ\text{C}; V_{IN} = V_{OUT} = V_{SENSE} = 0 \text{ V}$		2	5	$\mu\text{A}$
		ON-state: $V_{CC} = 13 \text{ V}; V_{IN} = 5 \text{ V}; I_{OUT} = 0 \text{ A}$		1.5	3	mA
$I_{L(off)}$	OFF-state output current	$V_{IN} = V_{OUT} = 0 \text{ V}; V_{CC} = 13 \text{ V}; T_j = 25^\circ\text{C}$	0	0.01	3	$\mu\text{A}$
		$V_{IN} = V_{OUT} = 0 \text{ V}; V_{CC} = 13 \text{ V}; T_j = 125^\circ\text{C}$	0		5	

**Table 6. Switching ( $V_{CC} = 13 \text{ V}, T_j = 25^\circ\text{C}$ )**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$t_{d(on)}$	Turn-on delay time	$R_L = 2.2 \Omega$ (see <a href="#">Figure 5</a> )	-	40	-	$\mu\text{s}$
$t_{d(off)}$	Turn-off delay time	$R_L = 2.2 \Omega$ (see <a href="#">Figure 5</a> )	-	28	-	$\mu\text{s}$
$(dV_{OUT}/dt)_{on}$	Turn-on voltage slope	$R_L = 2.2 \Omega$	-	(see <a href="#">Figure 23</a> )	-	$\text{V}/\mu\text{s}$
$(dV_{OUT}/dt)_{off}$	Turn-off voltage slope	$R_L = 2.2 \Omega$	-	(see <a href="#">Figure 25</a> )	-	$\text{V}/\mu\text{s}$
$W_{ON}$	Switching energy losses at turn-on ( $t_{won}$ )	$R_L = 2.2 \Omega$ (see <a href="#">Figure 5</a> )	-	2	-	$\text{mJ}$
$W_{OFF}$	Switching energy losses at turn-off ( $t_{woff}$ )	$R_L = 2.2 \Omega$ (see <a href="#">Figure 5</a> )	-	0.6	-	$\text{mJ}$

**Table 7. Logic inputs**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$V_{IL}$	Low-level input voltage				0.9	V
$I_{IL}$	Low-level input current	$V_{IN} = 0.9 \text{ V}$	1			$\mu\text{A}$
$V_{IH}$	High-level input voltage		2.1			V
$I_{IH}$	High-level input current	$V_{IN} = 2.1 \text{ V}$			10	$\mu\text{A}$
$V_{I(\text{hyst})}$	Input hysteresis voltage		0.25			V
$V_{ICL}$	Input clamp voltage	$I_{IN} = 1 \text{ mA}$	5.5		7	V
		$I_{IN} = -1 \text{ mA}$		-0.7		
$V_{CSDL}$	Low-level CS_DIS voltage				0.9	V
$I_{CSDL}$	Low-level CS_DIS current	$V_{CSD} = 0.9 \text{ V}$	1			$\mu\text{A}$
$V_{CSDH}$	High-level CS_DIS voltage		2.1			V
$I_{CSDH}$	High-level CS_DIS current	$V_{CSD} = 2.1 \text{ V}$			10	$\mu\text{A}$
$V_{CSD(\text{hyst})}$	CS_DIS hysteresis voltage		0.25			V
$V_{CSCL}$	CS_DIS clamp voltage	$I_{CSD} = 1 \text{ mA}$	5.5		7	V
		$I_{CSD} = -1 \text{ mA}$		-0.7		

**Table 8. Protection and diagnostics<sup>(1)</sup>**

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$I_{limH}$	Short-circuit current	$V_{CC} = 13 \text{ V}$	60	85	120	A
		$5 \text{ V} < V_{CC} < 28 \text{ V}$			120	
$I_{limL}$	Short-circuit current during thermal cycling	$V_{CC} = 13 \text{ V}; T_R < T_j < T_{TSD}$		21		A
$T_{TSD}$	Shutdown temperature		150	175	200	°C
$T_R$	Reset temperature		$T_{RS} + 1$	$T_{RS} + 5$		°C
$T_{RS}$	Thermal reset of status		135			°C
$T_{HYST}$	Thermal hysteresis ( $T_{TSD}-T_R$ )			7		°C
$V_{DEMAG}$	Turn-off output voltage clamp	$I_{OUT} = 2 \text{ A}; V_{IN} = 0; L = 6 \text{ mH}$	$V_{CC} - 41$	$V_{CC} - 46$	$V_{CC} - 52$	V
$V_{ON}$	Output voltage drop limitation	$I_{OUT} = 0.5 \text{ A}; T_j = -40 \text{ °C to } 150 \text{ °C}$		25		mV

- To ensure long term reliability under heavy overload or short-circuit conditions, protection and related diagnostic signals must be used together with a proper software strategy. If the device is subjected to abnormal conditions, this software must limit the duration and number of activation cycles.

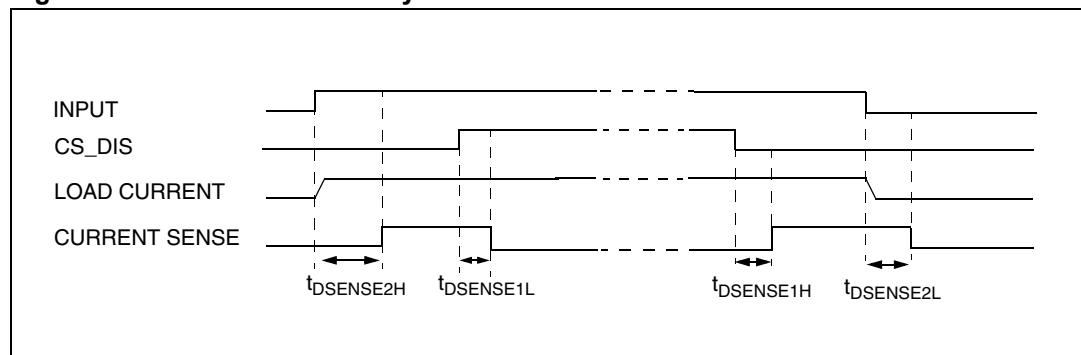
**Table 9. Current sense ( $8 \text{ V} < V_{CC} < 18 \text{ V}$ )**

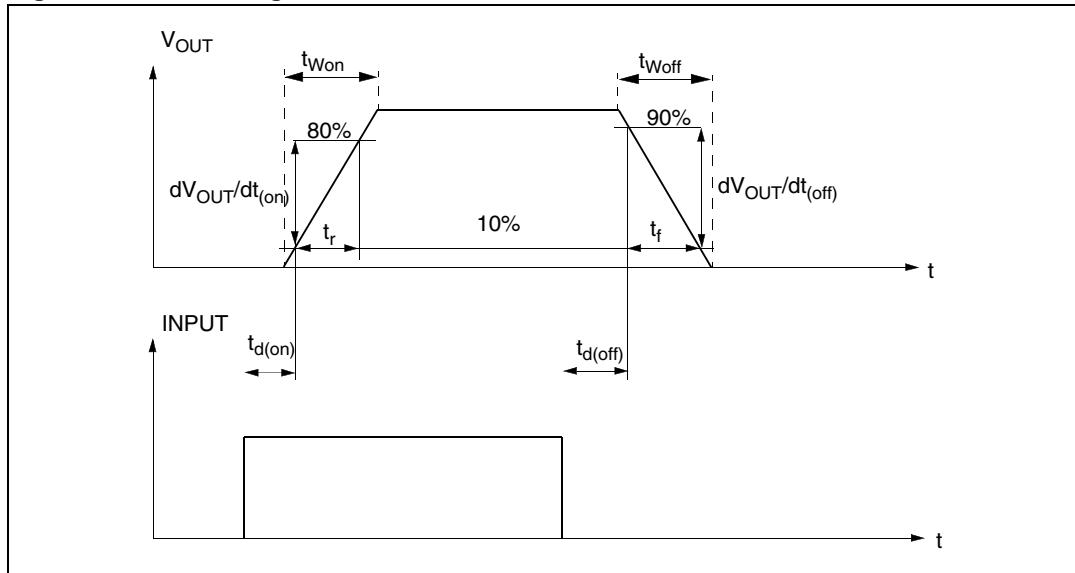
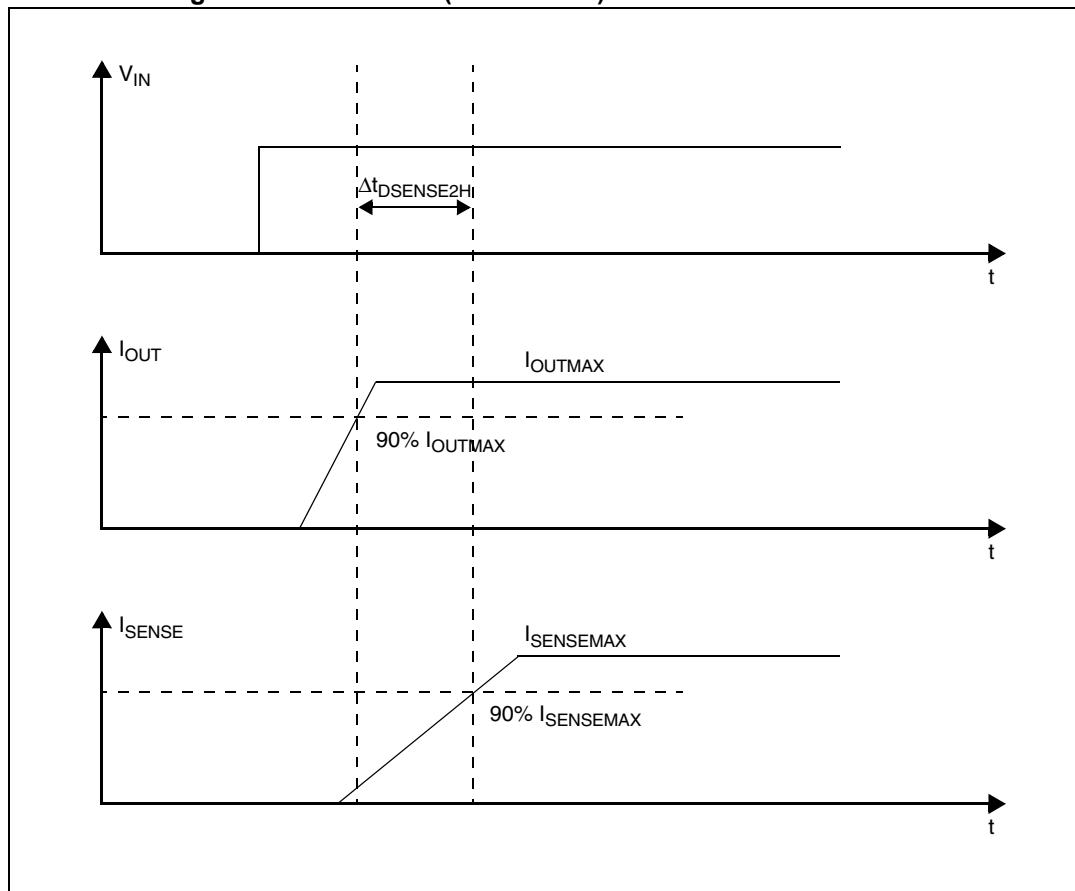
Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$K_0$	$I_{OUT}/I_{SENSE}$	$I_{OUT} = 0.25 \text{ A}; V_{SENSE} = 0.5 \text{ V}$ $T_j = -40^\circ\text{C} \text{ to } 150^\circ\text{C}$ $T_j = 25^\circ\text{C} \text{ to } 150^\circ\text{C}$	3000	7410	12000	
			3000	7410	11600	
$K_1$	$I_{OUT}/I_{SENSE}$	$I_{OUT} = 6 \text{ A}; V_{SENSE} = 0.5 \text{ V}$ $T_j = -40^\circ\text{C} \text{ to } 150^\circ\text{C}$ $T_j = 25^\circ\text{C} \text{ to } 150^\circ\text{C}$	5350	6740	8500	
			5510	6740	7745	
$dK_1/K_1^{(1)}$	Current sense ratio drift	$I_{OUT} = 6 \text{ A}; V_{SENSE} = 0.5 \text{ V};$ $V_{CSD} = 0 \text{ V};$ $T_j = -40^\circ\text{C} \text{ to } 150^\circ\text{C}$	-15		15	%
$K_2$	$I_{OUT}/I_{SENSE}$	$I_{OUT} = 10 \text{ A}; V_{SENSE} = 4 \text{ V}$ $T_j = -40^\circ\text{C} \text{ to } 150^\circ\text{C}$ $T_j = 25^\circ\text{C} \text{ to } 150^\circ\text{C}$	5850	6570	7690	
			5800	6570	7195	
$dK_2/K_2^{(1)}$	Current sense ratio drift	$I_{OUT} = 10 \text{ A}; V_{SENSE} = 4 \text{ V};$ $V_{CSD} = 0 \text{ V};$ $T_j = -40^\circ\text{C} \text{ to } 150^\circ\text{C}$	-11		11	%
$K_3$	$I_{OUT}/I_{SENSE}$	$I_{OUT} = 25 \text{ A}; V_{SENSE} = 4 \text{ V}$ $T_j = -40^\circ\text{C} \text{ to } 150^\circ\text{C}$ $T_j = 25^\circ\text{C} \text{ to } 150^\circ\text{C}$	5915	6420	7000	
			5850	6420	6755	
$dK_3/K_3^{(1)}$	Current sense ratio drift	$I_{OUT} = 25 \text{ A}; V_{SENSE} = 4 \text{ V};$ $V_{CSD} = 0 \text{ V};$ $T_j = -40^\circ\text{C} \text{ to } 150^\circ\text{C}$	-8		8	%
$I_{SENSE0}$	Analog sense leakage current	$I_{OUT} = 0 \text{ A}; V_{SENSE} = 0 \text{ V};$ $V_{CSD} = 5 \text{ V}; V_{IN} = 0 \text{ V};$ $T_j = -40^\circ\text{C} \text{ to } 150^\circ\text{C}$	0		1	$\mu\text{A}$
		$I_{OUT} = 0 \text{ A}; V_{SENSE} = 0 \text{ V};$ $V_{CSD} = 0 \text{ V}; V_{IN} = 5 \text{ V};$ $T_j = -40^\circ\text{C} \text{ to } 150^\circ\text{C}$	0		2	
		$I_{OUT} = 2 \text{ A}; V_{SENSE} = 0 \text{ V};$ $V_{CSD} = 5 \text{ V}; V_{IN} = 5 \text{ V};$ $T_j = -40^\circ\text{C} \text{ to } 150^\circ\text{C}$			1	
$I_{OL}$	Open load ON-state current detection threshold	$V_{IN} = 5 \text{ V}, 8 \text{ V} < V_{CC} < 18 \text{ V}$ $I_{SENSE} = 5 \mu\text{A}$	5		80	mA
$V_{SENSE}$	Max analog sense output voltage	$I_{OUT} = 18 \text{ A}; R_{SENSE} = 3.9 \text{ k}\Omega$	5			V
$V_{SENSEH}^{(2)}$	Analog sense output voltage in fault condition	$V_{CC} = 13 \text{ V}; R_{SENSE} = 3.9 \text{ k}\Omega$		8		V
$I_{SENSEH}^{(2)}$	Analog sense output current in fault condition	$V_{CC} = 13 \text{ V}; V_{SENSE} = 5 \text{ V}$		9		mA

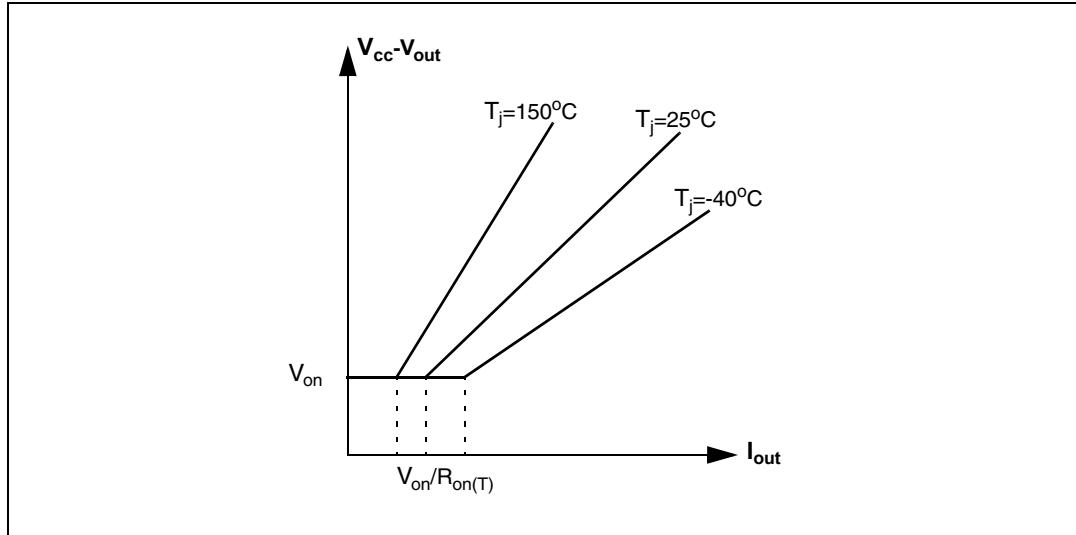
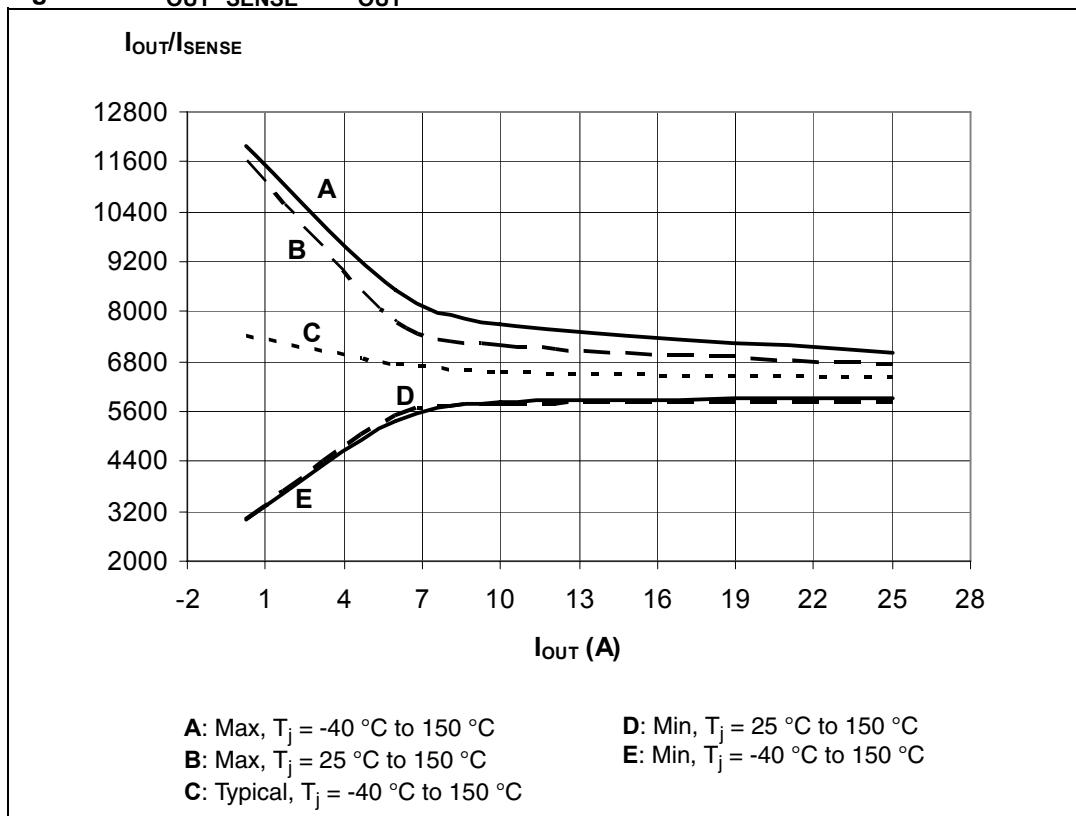
**Table 9. Current sense (8 V < V<sub>CC</sub> < 18 V) (continued)**

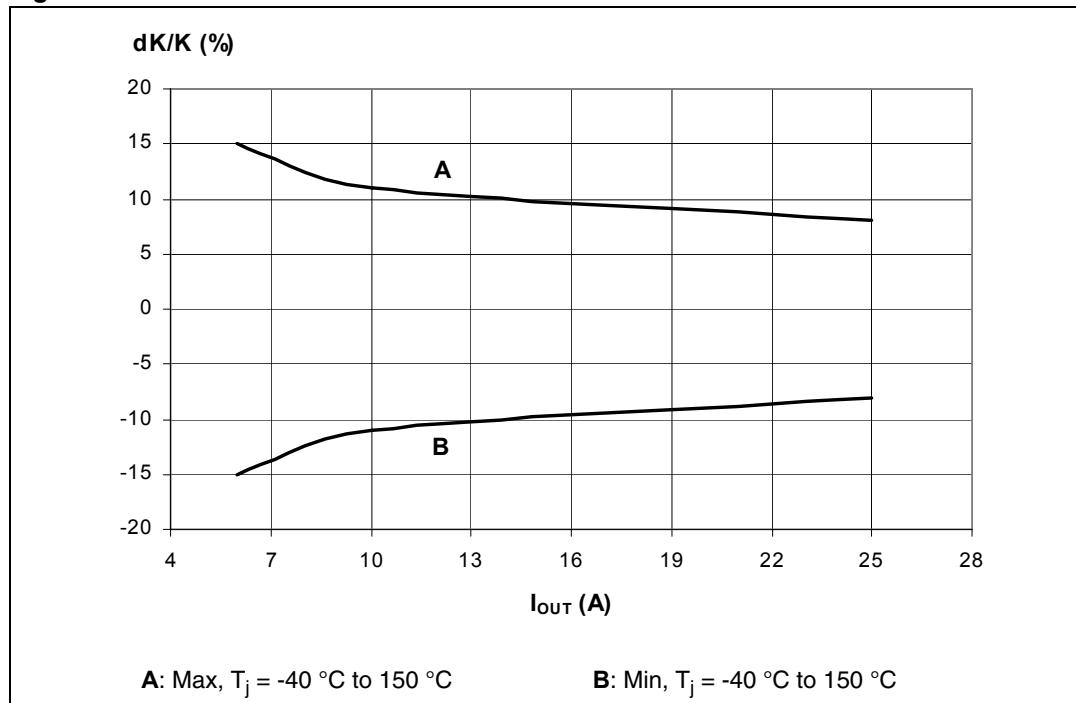
Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
t <sub>DSENSE1H</sub>	Delay response time from falling edge of CS_DIS pin	V <sub>SENSE</sub> < 4 V, 1.5 A < I <sub>OUT</sub> < 25 A I <sub>SENSE</sub> = 90% of I <sub>SENSE MAX</sub> (see <i>Figure 4</i> )		50	100	μs
t <sub>DSENSE1L</sub>	Delay response time from rising edge of CS_DIS pin	V <sub>SENSE</sub> < 4 V, 1.5 A < I <sub>OUT</sub> < 25 A I <sub>SENSE</sub> = 10% of I <sub>SENSE MAX</sub> (see <i>Figure 4</i> )		5	20	μs
t <sub>DSENSE2H</sub>	Delay response time from rising edge of IN pin	V <sub>SENSE</sub> < 4 V, 1.5 A < I <sub>OUT</sub> < 25 A I <sub>SENSE</sub> = 90% of I <sub>SENSE max</sub> (see <i>Figure 4</i> )		270	600	μs
Δt <sub>DSENSE2H</sub>	Delay response time between rising edge of output current and rising edge of current sense	V <sub>SENSE</sub> < 4V, I <sub>SENSE</sub> = 90% of I <sub>SENSEMAX</sub> , I <sub>OUT</sub> = 90% of I <sub>OUTMAX</sub> I <sub>OUTMAX</sub> = 3 A (see <i>Figure 6</i> )			310	μs
t <sub>DSENSE2L</sub>	Delay response time from falling edge of IN pin	V <sub>SENSE</sub> < 4 V, 1.5 A < I <sub>OUT</sub> < 25 A I <sub>SENSE</sub> = 10% of I <sub>SENSE max</sub> (see fig <i>Figure 4</i> )		100	250	μs

1. Parameter guaranteed by design, it is not tested.
2. Fault condition includes: power limitation and overtemperature.

**Figure 4. Current sense delay characteristics**

**Figure 5. Switching characteristics****Figure 6. Delay response time between rising edge of ouput current and rising edge of current sense (CS enabled)**

**Figure 7. Output voltage drop limitation****Figure 8.  $I_{OUT}/I_{SENSE}$  vs.  $I_{OUT}$** 

**Figure 9. Maximum current sense ratio drift vs. load current<sup>(1)</sup>**

1. Parameter guaranteed by design; it is not tested.

**Table 10. Truth table**

Conditions	Input	Output	SENSE ( $V_{CSD} = 0 \text{ V}$ ) <sup>(1)</sup>
Normal operation	L	L	0
	H	H	Nominal
Overtemperature	L	L	0
	H	L	$V_{SENSEH}$
Undervoltage	L	L	0
	H	L	0
Overload	H	X (no power limitation)	Nominal
	H	Cycling (power limitation)	$V_{SENSEH}$
Short-circuit to GND (power limitation)	L	L	0
	H	L	$V_{SENSEH}$
Negative output voltage clamp	L	L	0

1. If the  $V_{CSD}$  is high, the SENSE output is at a high-impedance, its potential depends on leakage currents and external circuit.

**Table 11. Electrical transient requirements (part 1)**

ISO 7637-2: 2004(E) Test pulse	Test levels <sup>(1)</sup>		Number of pulses or test times	Burst cycle/pulse repetition time		Delays and impedance
	III	IV		Min.	Max.	
1	-75 V	-100 V	5000 pulses	0.5 s	5 s	2 ms, 10 Ω
2a	+37 V	+50 V	5000 pulses	0.2 s	5 s	50 μs, 2 Ω
3a	-100 V	-150 V	1 h	90 ms	100 ms	0.1μs, 50 Ω
3b	+75 V	+100 V	1 h	90 ms	100 ms	0.1μs, 50 Ω
4	-6 V	-7 V	1 pulse			100 ms, 0.01 Ω
5b <sup>(2)</sup>	+65 V	+87 V	1 pulse			400 ms, 2 Ω

1. The above test levels must be considered referred to  $V_{CC} = 13.5$  V except for pulse 5b.

2. Valid in case of external load dump clamp: 40 V maximum referred to ground.

**Table 12. Electrical transient requirements (part 2)**

ISO 7637-2: 2004(E) Test pulse	Test level results	
	III	IV
1	C	C
2a	C	C
3a	C	C
3b	C	C
4	C	C
5b <sup>(1)</sup>	C	C

1. Valid in case of external load dump clamp: 40 V maximum referred to ground.

**Table 13. Electrical transient requirements (part 3)**

Class	Contents
C	All functions of the device are performed as designed after exposure to disturbance.
E	One or more functions of the device are not performed as designed after exposure to disturbance and cannot be returned to proper operation without replacing the device.

## 2.4 Waveforms

Figure 10. Normal operation

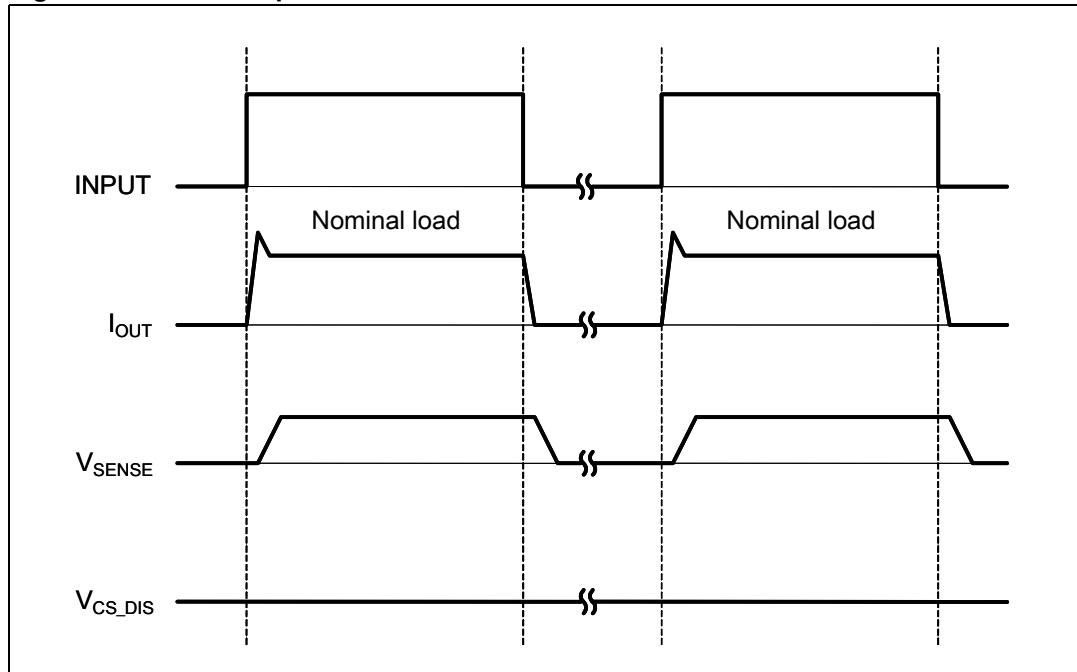


Figure 11. Overload or short to GND

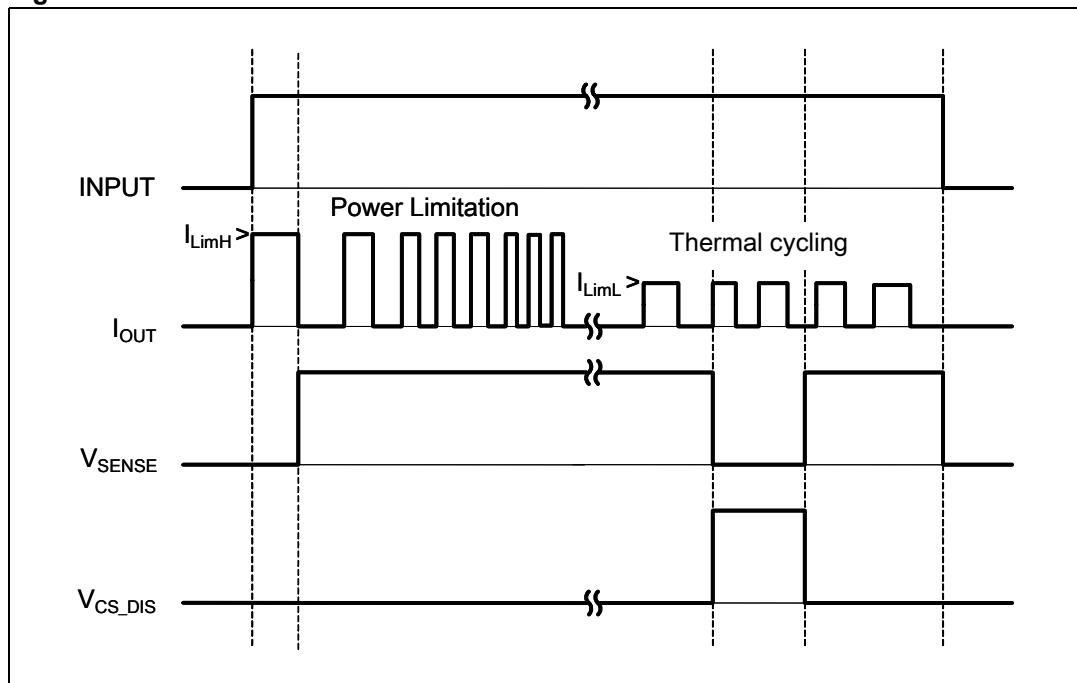
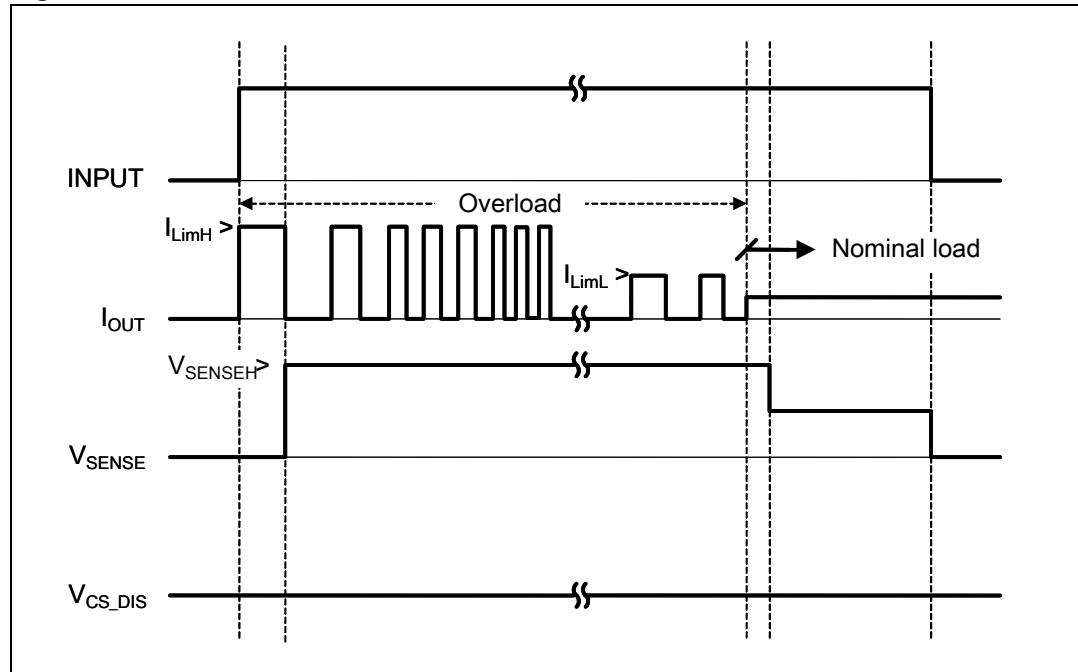
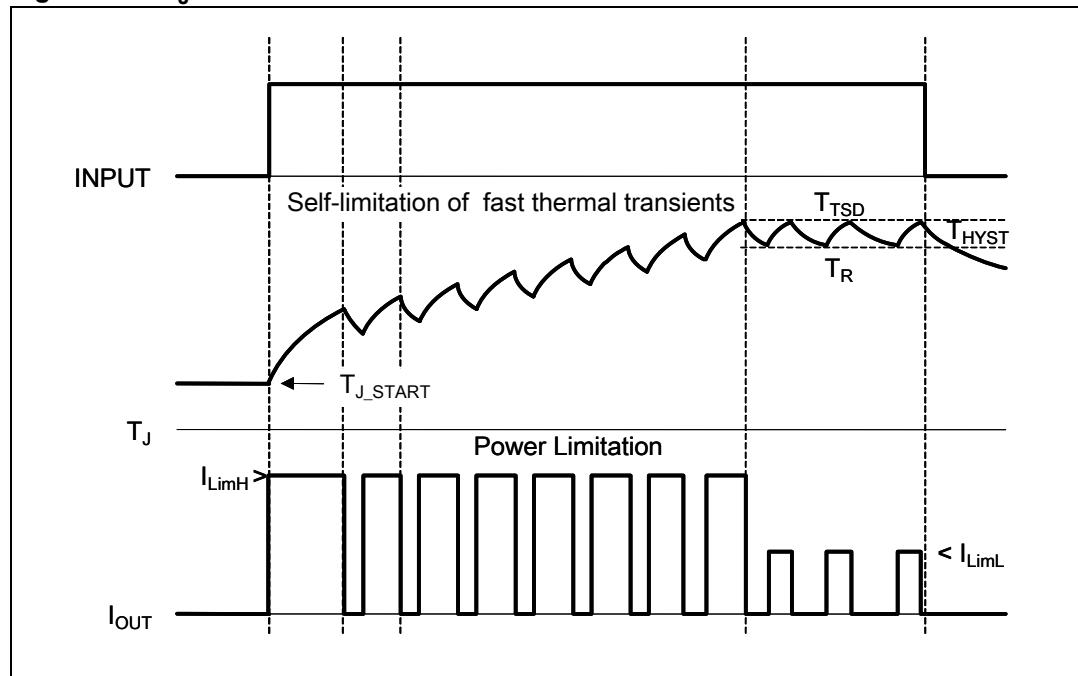


Figure 12. Intermittent overload

Figure 13.  $T_J$  evolution in overload or short to GND

## 2.5 Electrical characteristics curves

Figure 14. OFF-state output current

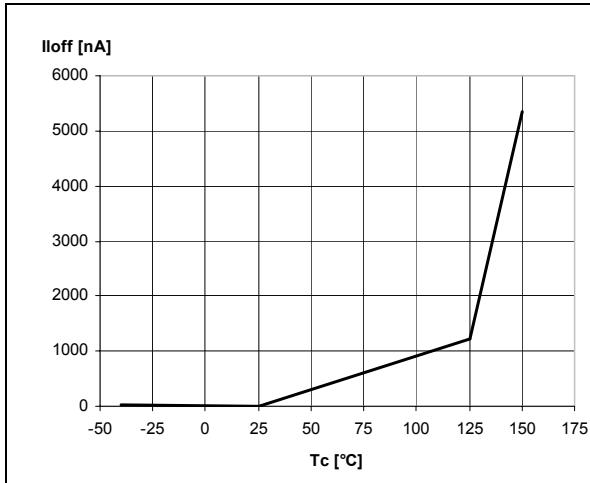


Figure 15. High-level input current

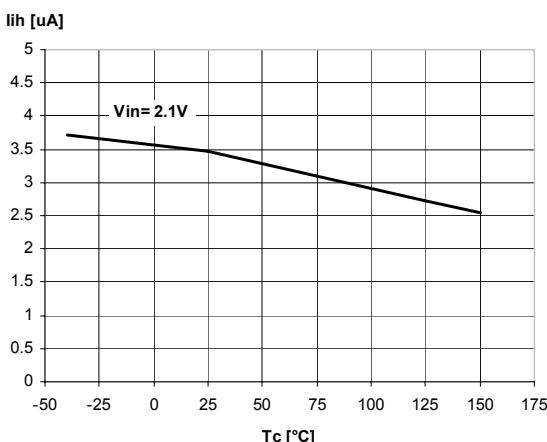


Figure 16. Input clamp voltage

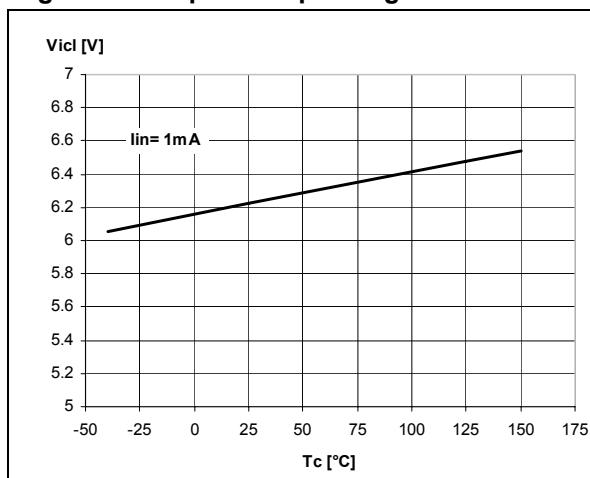


Figure 17. Low-level input voltage

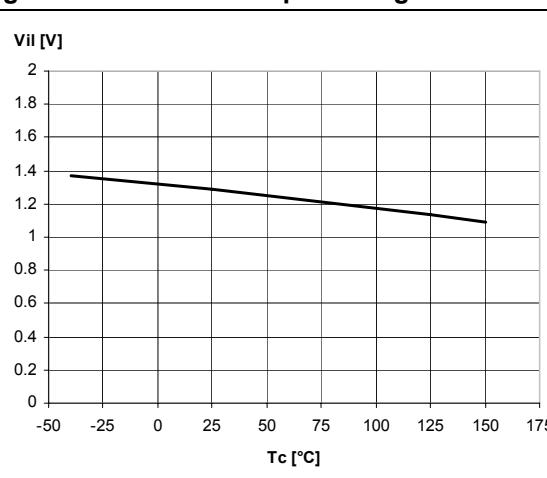


Figure 18. High-level input voltage

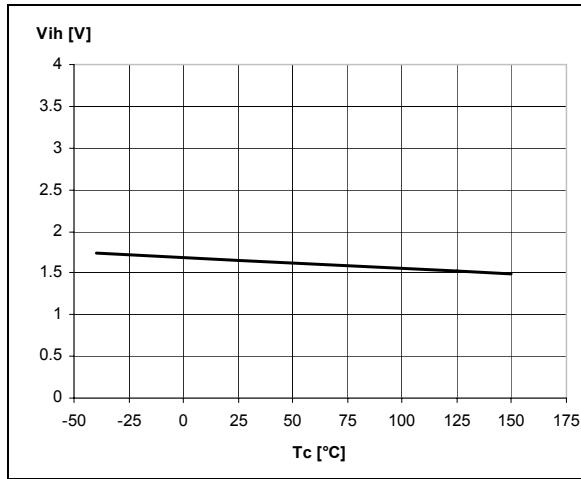
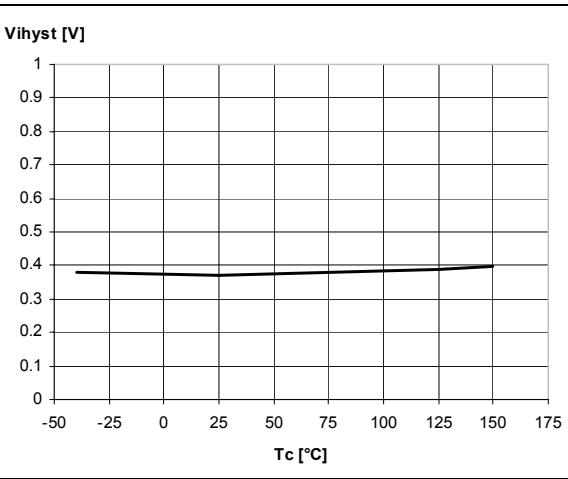
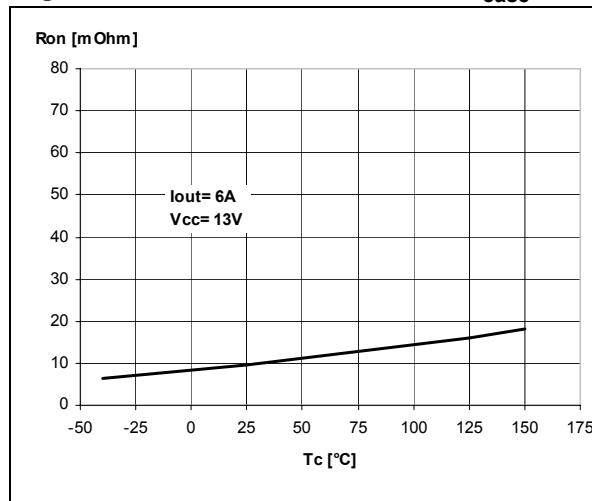
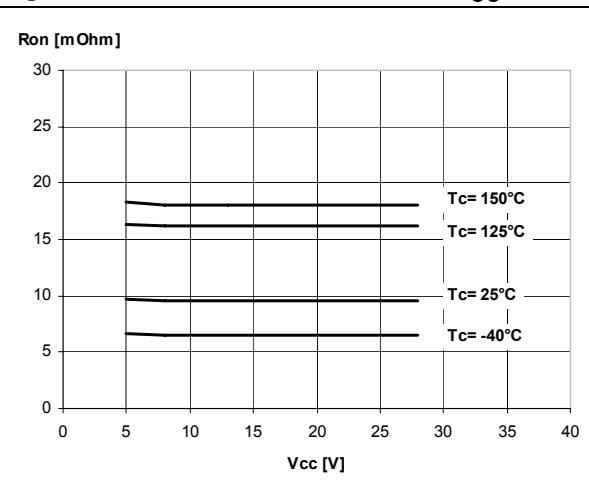
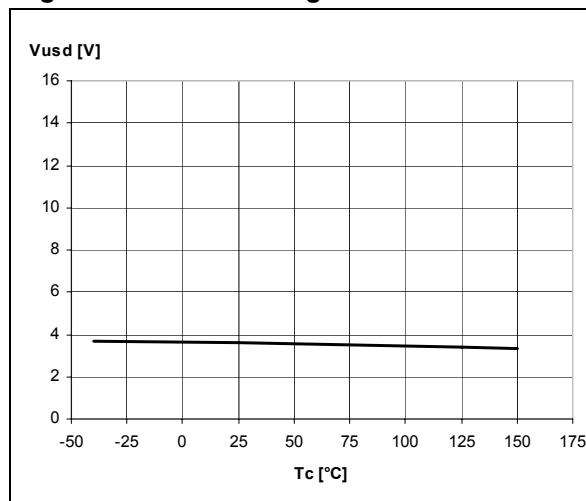
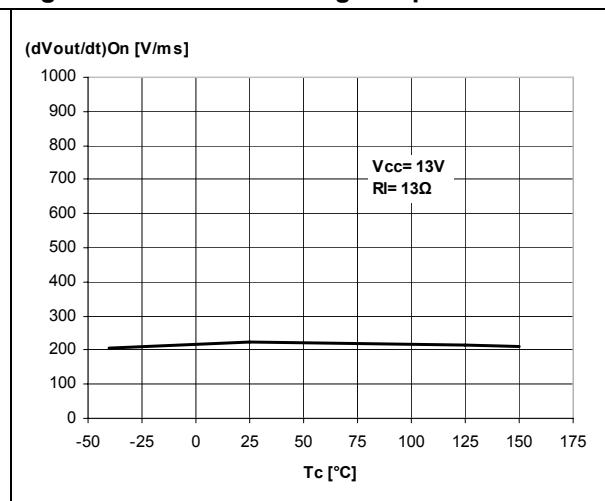
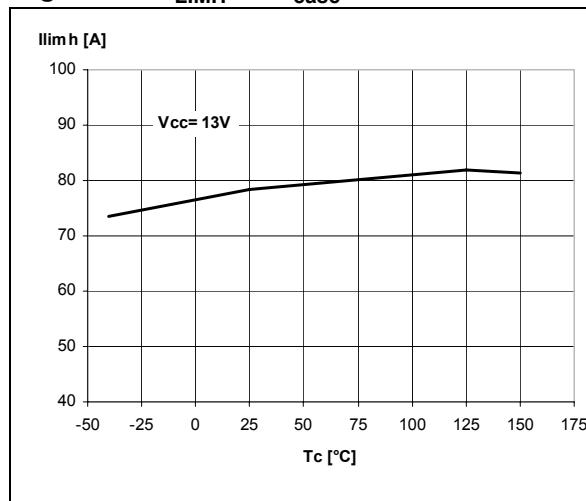
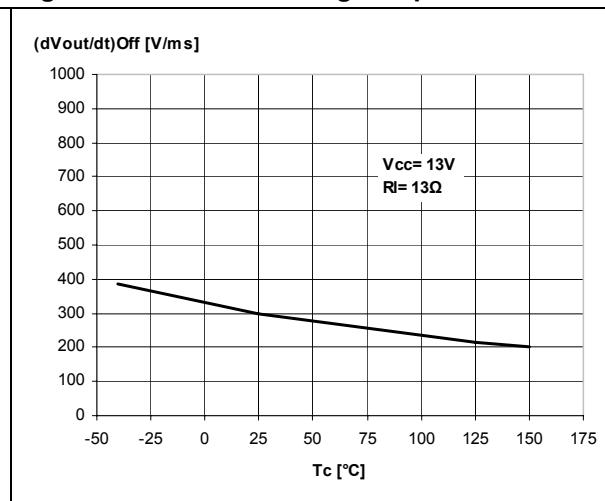
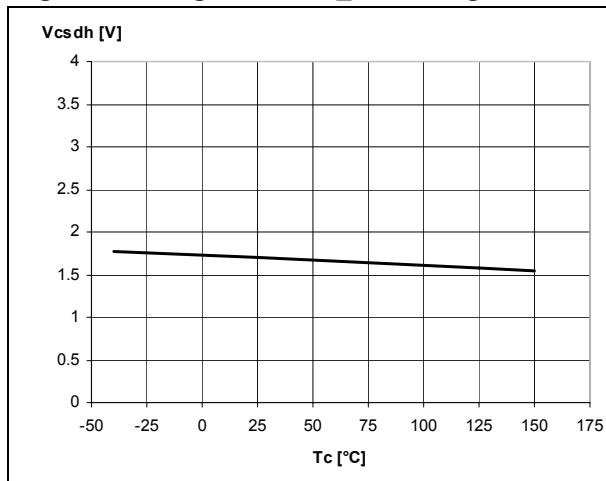
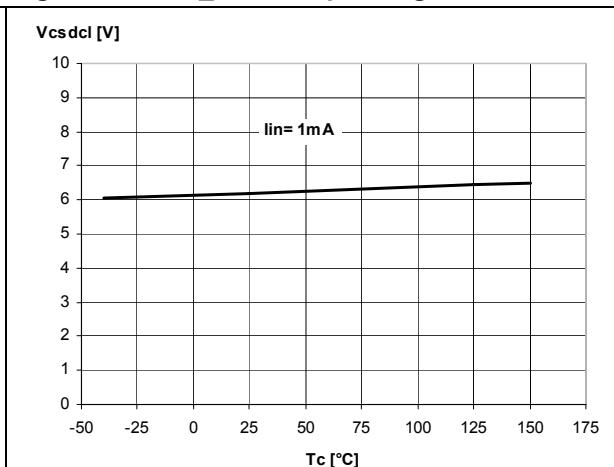
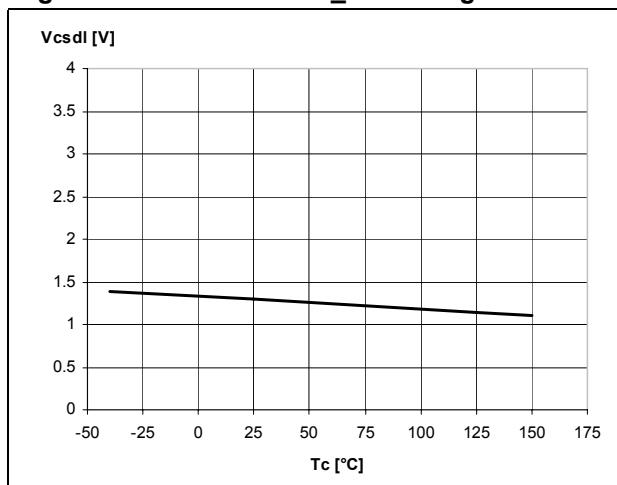


Figure 19. Input hysteresis voltage

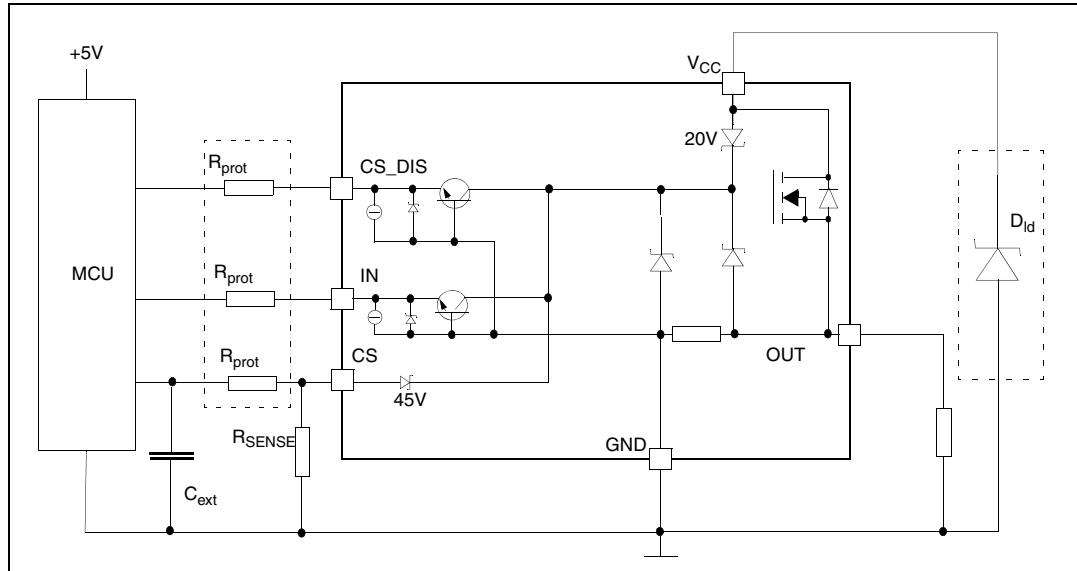


**Figure 20. ON-state resistance vs.  $T_{case}$** **Figure 21. ON-state resistance vs.  $V_{CC}$** **Figure 22. Undervoltage shutdown****Figure 23. Turn-on voltage slope****Figure 24.  $I_{LIMH}$  vs.  $T_{case}$** **Figure 25. Turn-off voltage slope**

**Figure 26. High-level CS\_DIS voltage****Figure 27. CS\_DIS clamp voltage****Figure 28. Low-level CS\_DIS voltage**

## 2.6 Application information

**Figure 29. Application schematic**



## 2.7 Load dump protection

$D_{Id}$  is necessary (voltage transient suppressor) if the load dump peak voltage exceeds the  $V_{CC}$  max DC rating. The same applies if the device is subject to transients on the  $V_{CC}$  line that are greater than the ones shown in the ISO 7637-2 2004 (E) table.

## 2.8 MCU I/Os protection

When negative transients are present on the  $V_{CC}$  line, the control pins are pulled negative to approximately -1.5 V. ST suggests to insert a resistor ( $R_{prot}$ ) in line to prevent the microcontroller I/Os pins to latch-up.

The value of these resistors is a compromise between the leakage current of microcontroller and the current required by the HSD I/Os (input levels compatibility) with the latch-up limit of microcontroller I/Os.

### Equation 1

$$-V_{CCpeak} / I_{latchup} \leq R_{prot} \leq (V_{OH\mu C} - V_{IH}) / I_{IHmax}$$

Calculation example:

For  $V_{CCpeak} = -1.5$  V;  $I_{latchup} \geq 20$  mA;  $V_{OH\mu C} \geq 4.5$  V

$$75 \Omega \leq R_{prot} \leq 240 \text{ k}\Omega$$

Recommended values:  $R_{prot} = 10 \text{ k}\Omega$ ,  $C_{EXT} = 10 \text{ nF}$ .

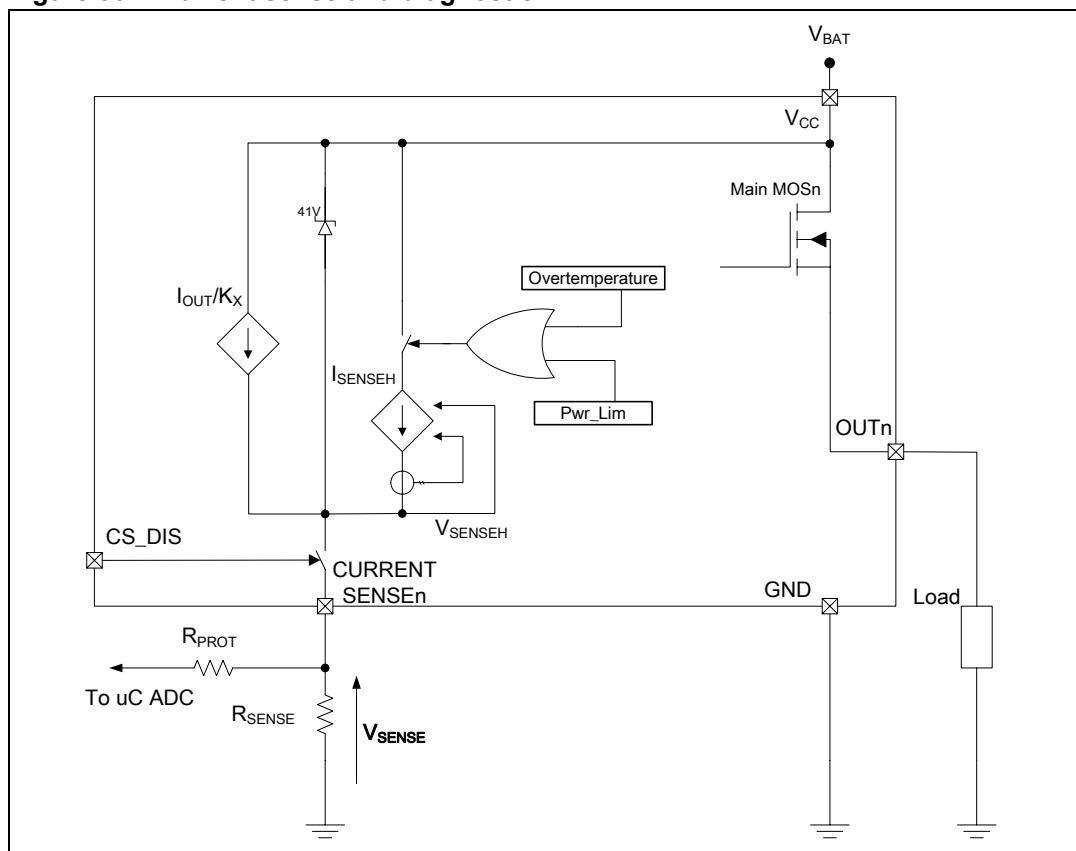
## 2.9 Current sense and diagnostic

The current sense pin performs a double function (see [Figure 30: Current sense and diagnostic](#)):

- **Current mirror of the load current in normal operation**, delivering a current proportional to the load one according to a know ratio  $K_X$ .  
The current  $I_{SENSE}$  can be easily converted to a voltage  $V_{SENSE}$  by means of an external resistor  $R_{SENSE}$ . Linearity between  $I_{OUT}$  and  $V_{SENSE}$  is ensured up to 5 V minimum (see parameter  $V_{SENSE}$  in [Table 9: Current sense \(8 V <  \$V\_{CC}\$  < 18 V\)](#)). The current sense accuracy depends on the output current (refer to current sense electrical characteristics [Table 9: Current sense \(8 V <  \$V\_{CC}\$  < 18 V\)](#)).
- **Diagnostic flag in fault conditions**, delivering a fixed voltage  $V_{SENSEH}$  up to a maximum current  $I_{SENSEH}$  in case of the following fault conditions (refer to [Table 10: Truth table](#)):
  - Power limitation activation
  - Overtemperature

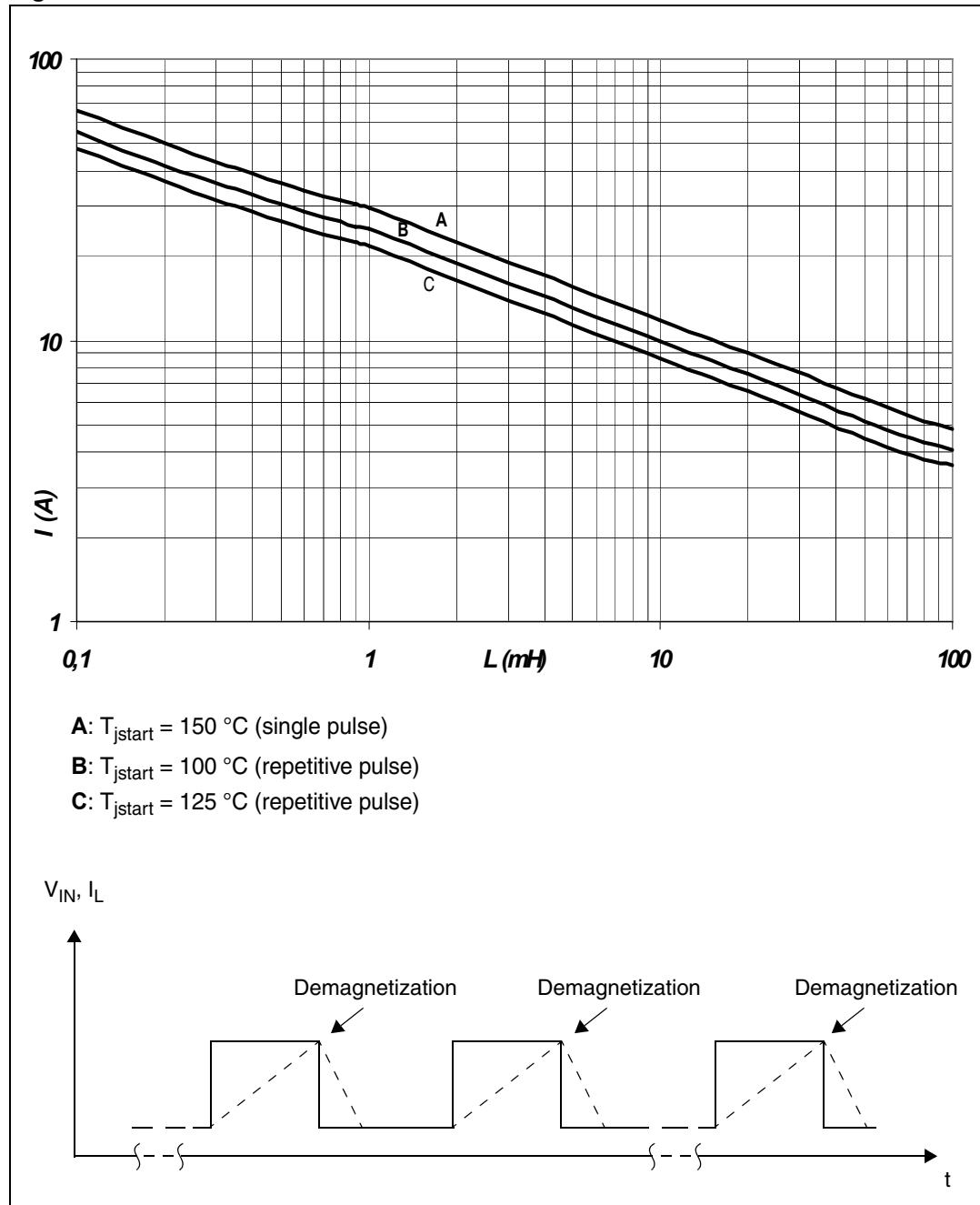
A logic level high on CS\_DIS pin sets at the same time all the current sense pins of the device in a high-impedance state, thus disabling the current monitoring and diagnostic detection. This feature allows multiplexing of the microcontroller analog inputs by sharing of sense resistance and ADC line among different devices.

**Figure 30. Current sense and diagnostic**



## 2.10 Maximum demagnetization energy ( $V_{CC} = 13.5$ V)

Figure 31. Maximum turn-off current versus inductance<sup>(1)</sup>



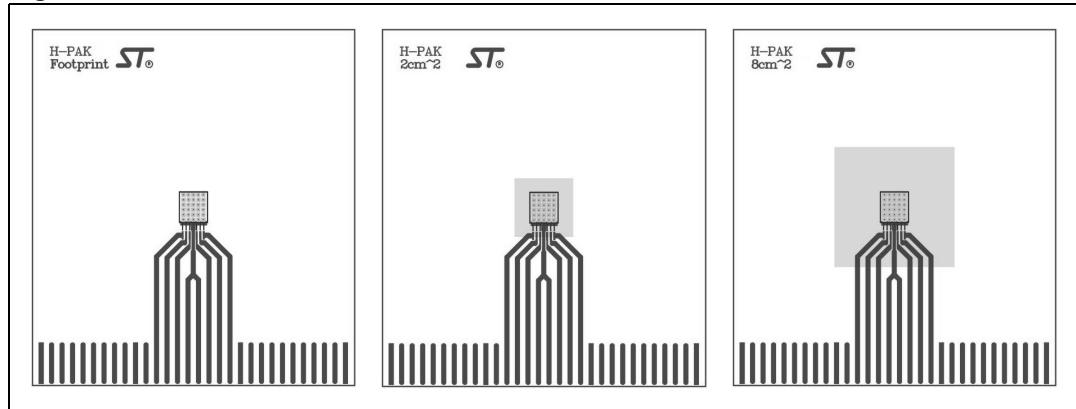
1. Values are generated with  $R_L = 0 \Omega$ .

In case of repetitive pulses,  $T_{jstart}$  (at beginning of each demagnetization) of every pulse must not exceed the temperature specified above for curves A and B.

### 3 Package and PC board thermal data

#### 3.1 HPAK thermal data

Figure 32. PC board<sup>(1)</sup>



1. Layout condition of R<sub>th</sub> and Z<sub>th</sub> measurements (PCB FR4 area = 58 mm x 58 mm, PCB thickness = 1.8 mm, Cu thickness = 70 µm, Copper areas: from minimum pad lay-out to 8 cm<sup>2</sup>).

Figure 33. R<sub>thj\_amb</sub> vs. PCB copper area in open box free air condition

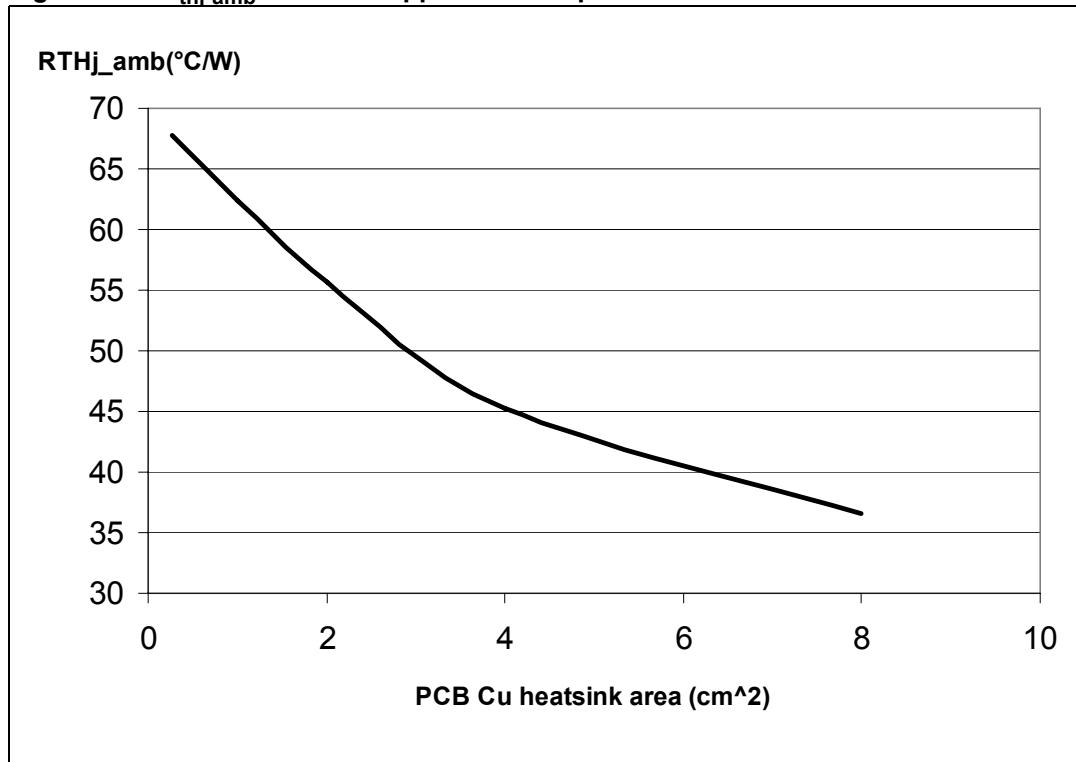
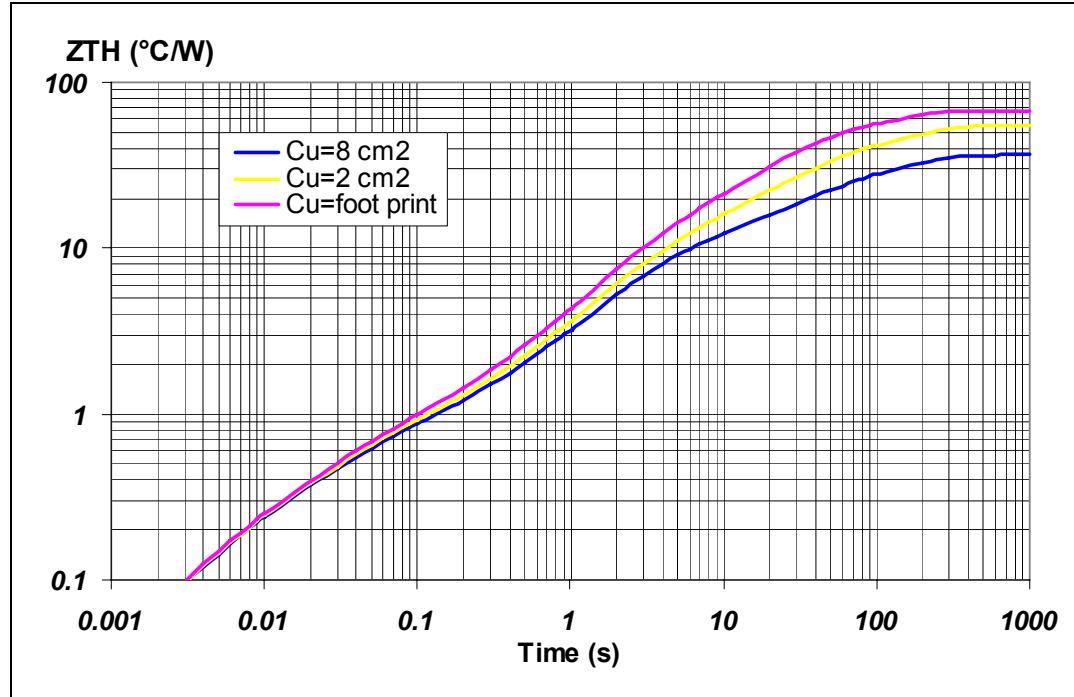
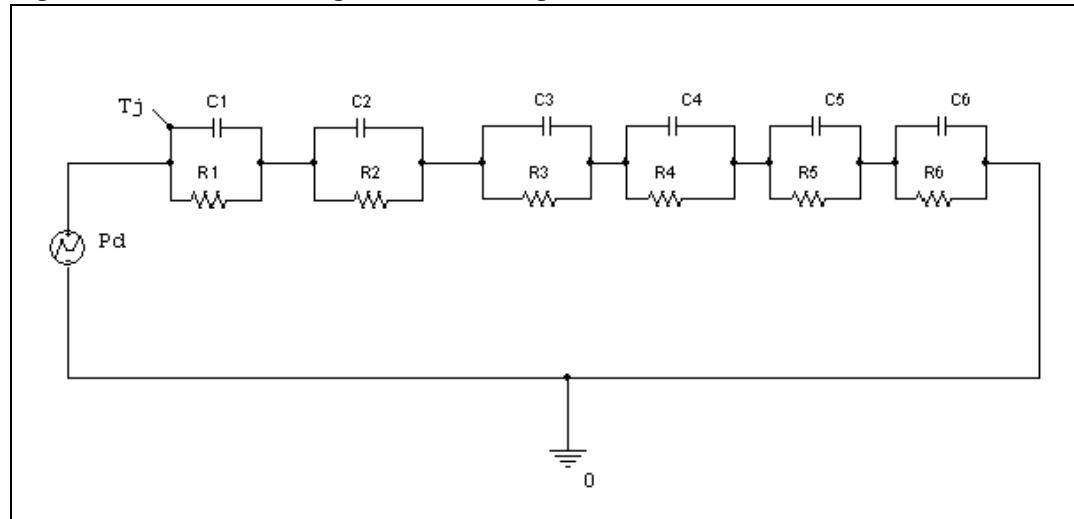


Figure 34. HPAK thermal impedance junction ambient single pulse

Figure 35. Thermal fitting model of a single-channel HSD in HPAK<sup>(1)</sup>

1. The fitting model is a simplified thermal tool and is valid for transient evolutions where the embedded protections (power limitation or thermal cycling during thermal shutdown) are not triggered.

#### Equation 2: pulse calculation formula

$$Z_{TH\delta} = R_{TH} \cdot \delta + Z_{THtp}(1 - \delta)$$

where  $\delta = t_p/T$

**Table 14. Thermal parameter**

Area/island (cm <sup>2</sup> )	Footprint	4	8
R1 (°C/W)	0.01		
R2 (°C/W)	0.15		
R3 (°C/W)	0.5		
R4 (°C/W)	8		
R5 (°C/W)	28	22	12
R6 (°C/W)	31	25	16
C1 (W.s/°C)	0.005		
C2 (W.s/°C)	0.05		
C3 (W.s/°C)	0.1		
C4 (W.s/°C)	0.4		
C5 (W.s/°C)	0.8	1.4	3
C6 (W.s/°C)	3	6	9

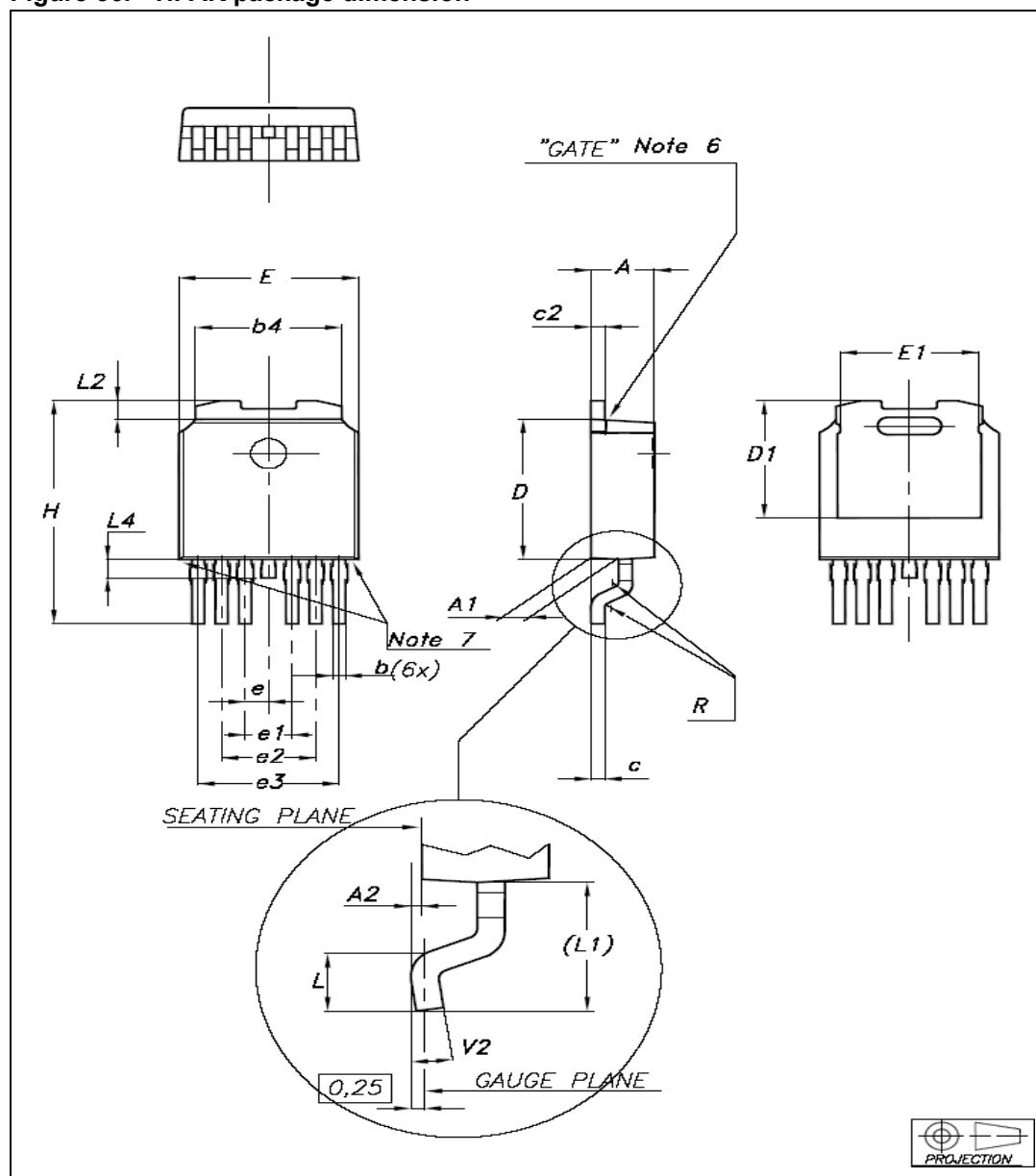
## 4 Package and packing information

### 4.1 ECOPACK®

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK® packages, depending on their level of environmental compliance. ECOPACK® specifications, grade definitions and product status are available at: [www.st.com](http://www.st.com).  
ECOPACK® is an ST trademark.

### 4.2 HPAK mechanical data

Figure 36. HPAK package dimension

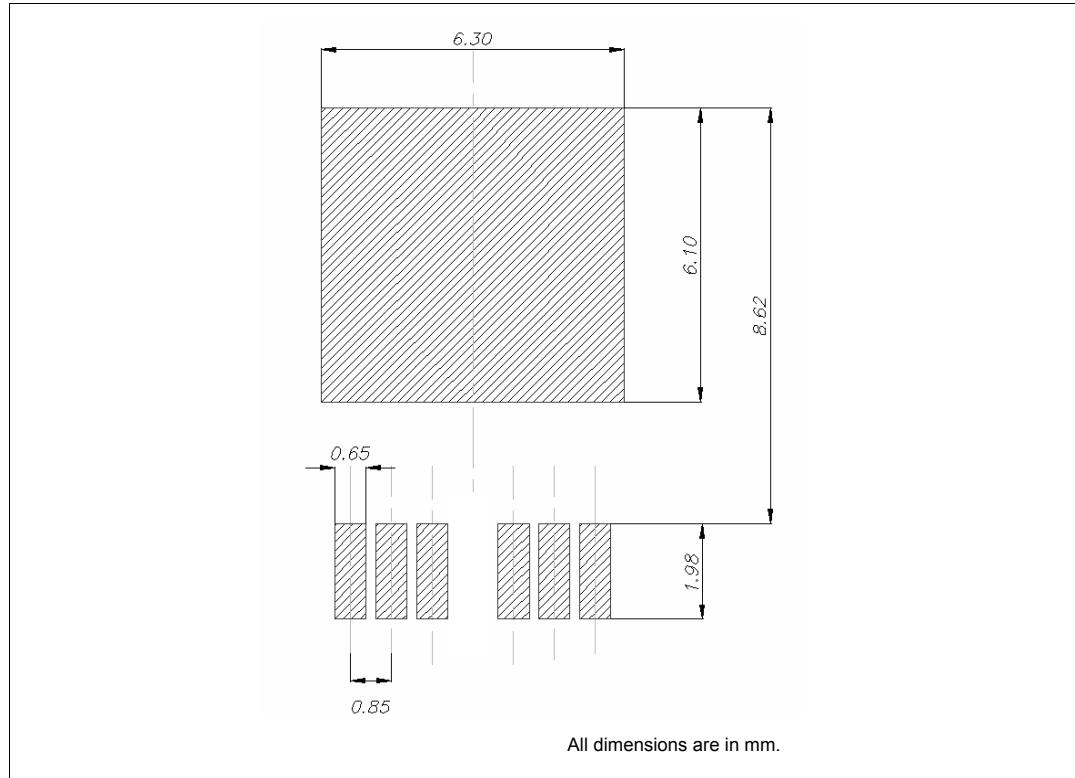


**Table 15. HPAK mechanical data**

Ref. dim	Data book mm		
	Nom.	Min.	Max.
A		2.20	2.40
A1		0.90	1.10
A2		0.03	0.23
b		0.45	0.60
b4		5.20	5.40
c		0.45	0.60
c2		0.48	0.60
D		6.00	6.20
D1	5.10		
E		6.40	6.60
E1	5.20		
e	0.85		
e1		1.60	1.80
e2		3.30	3.50
e3		5.00	5.20
H		9.35	10.10
L		1	
(L1)	2.80		
L2	0.80		
L4		0.60	1.00
R	0.20		
V2		0°	8°

### 4.3 HPAK suggested land pattern

Figure 37. HPAK suggested pad layout<sup>(1)</sup>

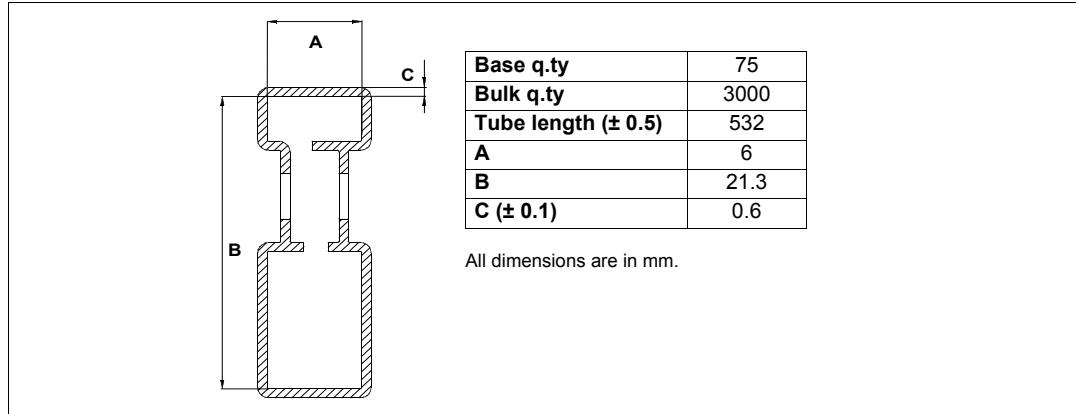


1. The land pattern proposed is not intended to overrule User's PCB design, manufacturing and soldering process rules

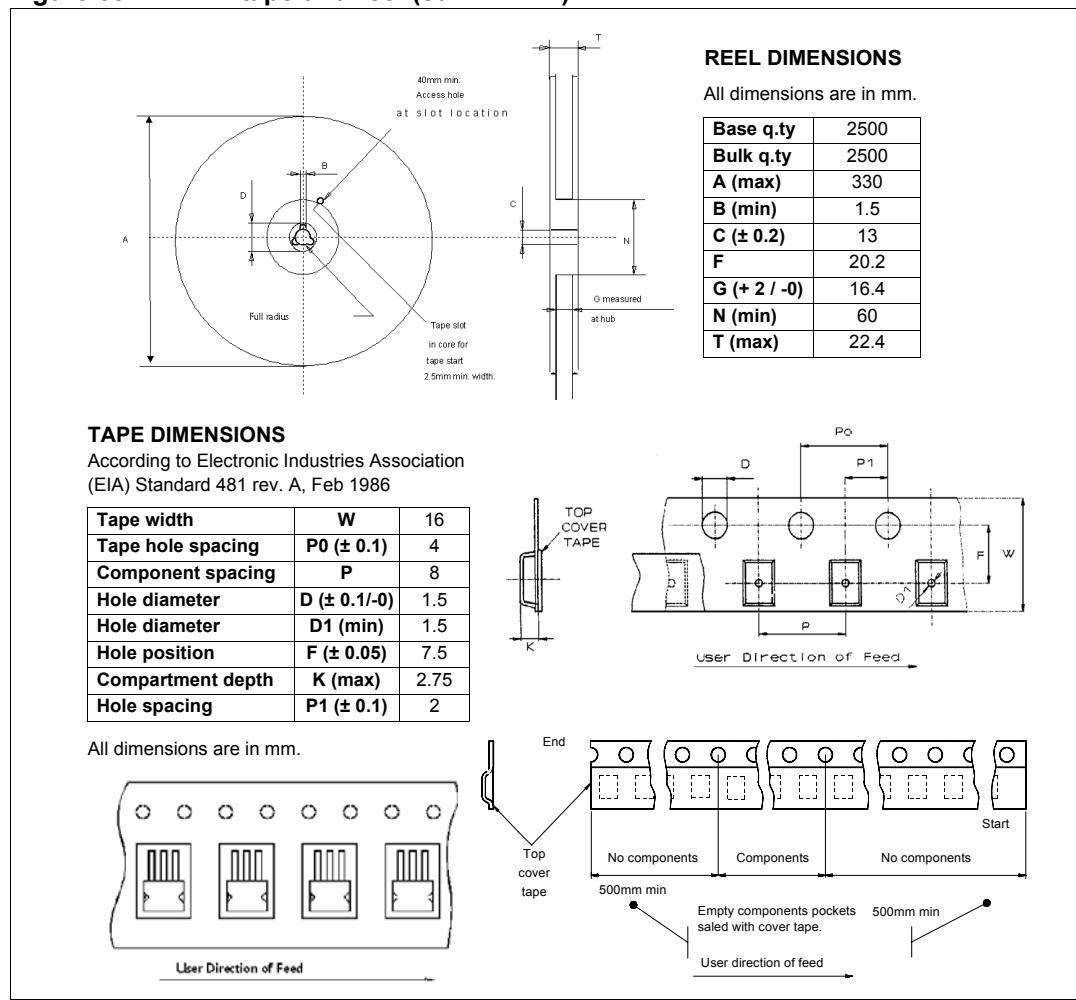
## 4.4 Packing information

The devices can be packed in tube or tape and reel shipments (see [Table 16: Device summary](#)).

**Figure 38. HPAK tube shipment (no suffix)**



**Figure 39. HPAK tape and reel (suffix "TR")**



## 5 Order codes

**Table 16. Device summary**

<b>Package</b>	<b>Order codes</b>	
	<b>Tube</b>	<b>Tape and reel</b>
6 pins HPAK	VN5E010MH-E	VN5E010MHTR-E

## 6 Revision history

**Table 17. Document revision history**

Date	Revision	Changes
28-May-2009	1	Initial release.
18-Jun-2009	2	<i>Figure 32: PC board<sup>(1)</sup></i> – Changed footnote
15-Dec-2009	3	Updated <i>Table 7: Logic inputs</i>
25-Jan-2010	4	Updated <i>Table 9: Current sense (8 V &lt; V<sub>CC</sub> &lt; 18 V)</i>
27-May-2010	5	Updated <i>Table 15: HPAK mechanical data.</i>

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