# INTEGRATED CIRCUITS



Preliminary specification

2001 Apr 06





## P87C51MB2/P87C51MC2

## **GENERAL DESCRIPTION**

The P87C51Mx2 represents the first microcontroller based on Philips Semiconductors' new 51MX core. The P87C51MC2 features 96 Kbytes of OTP program memory and 3 Kbytes of data SRAM, while the P87C51MB2 has 64 Kbytes of OTP and 2 Kbytes of RAM. In addition, both devices are equipped with a Programmable Counter Array (PCA), a watchdog timer that can be configured to different time ranges through SFR bits, as well as two enhanced UARTs or one enhanced UART and an SPI.

Philips Semiconductors' 51MX (Memory eXtension) core is an accelerated 80C51 architecture that executes instructions at twice the rate of standard 80C51 devices. The linear address range of the 51MX has been expanded to support up to 8 Mbytes of program memory and 8Mbytes of data memory. It retains full program code compatibility to enable design engineers to re-use 80C51 development tools, eliminating the need to move to a new, unfamiliar architecture. The 51MX core also retains 80C51 bus compatibility to allow for the continued use of 80C51-interfaced peripherals and Application Specific Integrated Circuits (ASICs).

The P87C51Mx2 provides greater functionality, increased performance and overall lower system cost. By offering an embedded memory solution combined with the enhancements to manage the memory extension, the P87C51Mx2 eliminates the need for software work-arounds. The increased program memory enables design engineers to develop more complex programs in a high-level language like C, for example, without struggling to contain the program within the traditional 64 Kbytes of program memory. These enhancements also greatly improve C Language efficiency for code size below 64 Kbytes.

The 51MX core is described in more details in the 51MX Architecture Reference.

#### **KEY FEATURES**

- Extended features of the 51MX Core:
  - 23-bit program memory space and 23-bit data memory space linear program and data address range expanded to support up to 8 Mbytes each
  - Program counter expanded to 23 bits
  - Stack pointer extended to 16 bits enabling stack space beyond the 80C51 limitation
  - New 23-bit extended data pointer and two 24-bit universal pointers greatly improve C compiler code efficiency in using pointers to access variables in different spaces.
- 100% binary compatibility with the classic 80C51 so that existing code is completely reusable
- Up to 24 MHz CPU clock with 6 clock cycles per machine cycle
- 96 Kbytes or 64 Kbytes of on-chip OTP
- 3 Kbytes or 2 Kbytes of on-chip RAM
- Programmable Counter Array (PCA)
- Two full-duplex enhanced UARTs
- Industry-standard Serial Peripheral Interface (SPI)

#### **KEY BENEFITS**

- Increases program/data address range to 8 Mbytes each
- Enhances performance and efficiency for C programs
- Fully 80C51-compatible microcontroller
- · Provides seamless and compelling upgrade path from classic 80C51
- · Preserves 80C51 code base, investment/knowledge, and peripherals & ASICs
- Supported by 80C51 development and programming tools (Keil, Nohau, BP Micro, etc.)
- The P87C51Mx2 makes it possible to develop applications at a lower cost and with a reduced time-to-market

## P87C51MB2/P87C51MC2

#### **COMPLETE FEATURES**

- Fully static
- Up to 24 MHz CPU clock with 6 clock cycles per machine cycle
- 96 Kbytes or 64 Kbytes of on-chip OTP
- 3 Kbytes or 2 Kbytes of on-chip RAM
- 23-bit program memory space and 23-bit data memory space
- Four-level interrupt priority
- 34 I/O lines (5 ports)
- Three Timers: Timer0, Timer1 and Timer2
- Two full-duplex enhanced UARTs with baud rate generator
- Framing error detection
- Automatic address recognition
- Supports industry-standard Serial Peripheral Interface (SPI) with a baud rate up to 6 Mbits/sec
- · Power control modes
- · Clock can be stopped and resumed
- Idle mode
- Power down mode
- Second DPTR register
- · Asynchronous port reset
- Programmable Counter Array (PCA) (compatible with 8xC51Rx+) with five Capture/Compare modules
- Low EMI (inhibit ALE)
- Watchdog timer with programmable prescaler for different time ranges (compatible with 8xC66x with added prescaler)

#### **ORDERING INFORMATION**

			IORY	TEMPERATURE		LTAGE	FREQ			
	PART ORDER NUMBER	ОТР	RAM	RANGE AND PACKAGE	RANGE		V <sub>DD</sub> = 2.7-5.5V	V <sub>DD</sub> = 4.5-5.5V	DWG #	
1	P87C51MB2BA	64 KB	2048 B	0 to +70°C, PLCC44	2.7-5.5V	4.5-5.5V	0-12MHz	0-24MHz	SOT187-2	
2	P87C51MC2BA	96 KB	3072 B	0 to +70°C, PLCC44	2.7-5.5V	4.5-5.5V	0-12MHz	0-24MHz	SOT187-2	

## P87C51MB2/P87C51MC2

## LOGIC SYMBOL



# P87C51MB2/P87C51MC2

## **PIN CONFIGURATION**

	Pin	Function	Pin	Function
	1	(NC/V <sub>SS</sub> ) <sup>1</sup>	23	$(NC/V_{DD})^1$
PLCC44	2	P1.0/T2	24	P2.0/A8/A16
1 20044	3	P1.1/T2EX	25	P2.1/A9/A17
6 1 40	4	P1.2/ECI	26	P2.2/A10/A18
	5	P1.3/CEX0	27	P2.3/A11/A19
39	6	P1.4/CEX1/MOSI	28	P2.4/A12/A20
	7	P1.5/CEX2/SPICLK	29	P2.5/A13/A21
PLASTIC	8	P1.6/CEX3	30	P2.6/A14/A22
LEADED CHIP CARRIER	9	P1.7/CEX4	31	P2.7/A15
On OAKKIEK	10	RST	32	PSEN
	11	P3.0/RXD0	33	ALE
29	12	P4.0/RXD1/MISO <sup>1</sup>	34	P4.1/TXD1/ $\overline{SS}^1$
18 28	13	P3.1/TXD0	35	EA/Vpp
	14	P3.2/INTO	36	P0.7/AD7
	15	P3.3/INT1	37	P0.6/AD6
	16	P3.4/T0	38	P0.5/AD5
	17	P3.5/T1	39	P0.4/AD4
	18	P3.6/WR	40	P0.3/AD3
	19	P3.7/RD	41	P0.2/AD2
	20	XTAL2	42	P0.1/AD1
	21	XTAL1	43	P0.0/AD0
	22	V <sub>SS</sub>	44	V <sub>DD</sub>

1. Pins 1, 12, 23, 34 were not internally connected in some derivatives. Please refer to section on Pin Descriptions for details.

## P87C51MB2/P87C51MC2

## **BLOCK DIAGRAM**



## P87C51MB2/P87C51MC2

## **PIN DESCRIPTIONS**

MNEMONIC	PIN NO.	TYPE	NAME AN	D FUNCTIO	N
P0.0 - P0.7	43 - 36	I/O	them float a order addre application	and can be ess and data , it uses stro	en drain, bidirectional I/O port. Port 0 pins that have 1s written to used as high-impendance inputs. Port 0 is also the multiplexed low- a bus during accesses to external program and data memory. In this ong internal pull-ups when emitting 1s.
P1.0 - P1.7	2 - 9	I/O	that have 1 inputs. As i	s written to inputs, port I pull-ups. (N	bit bidirectional I/O port with internal pull-ups on all pins. Port 1 pins them are pulled high by the internal pull-ups and can be used as 1 pins that are externally pulled low will source current because of Note: When SFR bit SPEN (SPCTL.6) is '1', the pull-ups at P1.4 and
	2	I/O	P1.0	T2	Timer/Counter 2 external count input/Clockout
	3	I	P1.1	T2EX	Timer/Counter 2 Reload/Capture/Direction Control
	4	I	P1.2	ECI	External Clock Input to the PCA
	5	I/O	P1.3	CEX0	Capture/Compare External I/O for PCA module 0
	6	I/O	P1.4	CEX1	Capture/Compare External I/O for PCA module 1 (with pull-up on pin)
		I/O		MOSI	SPI Master Out/Slave In (Selected when SFR bit SPEN (SPCTL.6) is '1', in which case the pull-up for this pin is disabled)
	7	I/O	P1.5	CEX2	Capture/Compare External I/O for PCA module 2 (with pull-up on pin)
		I/O		SPICLK	SPI Clock (Selected when SFR bit SPEN (SPCTL.6) is '1', in which case the pull-up for this pin is disabled)
	8	I/O	P1.6	CEX3	Capture/Compare External I/O for PCA module 3
	9	I/O	P1.7	CEX4	Capture/Compare External I/O for PCA module 4
P2.0 - P2.7	24 - 31	1/0	written to th inputs, port internal put address by external da (MOVX @B 1s. During emits the c Note that w when ALE Address bi	hem are pul t 2 pins that Il-ups. (See te during fe ta memory EPTR, EMO accesses to ontents of th when 23-bit a is High, and t A15 is outp	t bidirectional I/O port with internal pull-ups. Port 2 pins that have 1s led high by the internal pull-ups and can be used as inputs. As are externally being pulled low will source current because of the DC Electrical Characteristics: $I_{IL}$ ). Port 2 emits the high-order tches from external program memory and during accesses to that use 16-bit addresses (MOVX @ DPTR) or 23-bit addresses (V). In this application, it uses strong internal pull-ups when emitting external data memory that use 8-bit addresses (MOV @ Ri), port2 he P2 Special Function Register. address is used, address bits A16-A22 will be output to P2.0-P2.6 I address bits A8-A14 are output to P2.0-P2.6 when ALE is Low. but on P2.7 regardless of ALE.
P3.0 - P3.7	11,13 -19	I/O	written to the	nem are pul	it bidirectional I/O port with internal pull-ups. Port 3 pins that have 1s led high by the internal pull-ups and can be used as inputs. As are externally pulled low will source current because of the internal
	11	I	P3.0	RXD0	Serial input port 0
	13	0	P3.1	TXD0	Serial output port 0
	14	I	P3.2	INT0	External interrupt 0
	15	I	P3.3	INT1	External interrupt 1
	16	I	P3.4	то	Timer0 external input
	17	I	P3.5	T1	Timer1 external input
	18	0	P3.6	WR	External data memory write strobe
	19	0	P3.7	RD	External data memory read strobe

MNEMONIC	PIN NO.	TYPE	NAME AN	D FUNCTI	ON
P4.0 - P4.1	12,34	I/O	that have ' inputs. As	ls written to inputs, por I pull-ups. (	-bit bidirectional I/O port with internal pull-ups on all pin. Port 4 pins o them are pulled high by the internal pull-ups and can be used as t 4 pins that are externally pulled low will source current because of (Note: When SFR bit SPEN (SPCTL.6) is '1', the pull-ups at these port
	12	Ι	P4.0	RXD1	Serial input port 1. (Note: This pin is a no connect pin on some derivatives.) (with pull-up on pin)
		I/O		MISO	SPI Master In/Slave Out (Selected when SFR bit SPEN (SPCTL.6) is '1', in which case the pull-up for this pin is disabled)
	34	0	P4.1	TXD1	Serial output port 1. (Note: This pin is a no connect pin on some derivatives.) (with pull-up on pin)
		Ι		SS	SPI Slave Select (Selected when SFR bit SPEN (SPCTL.6) is '1', in which case the pull-up for this pin is disabled)
RST	10	I		internal di	pin for two machine cycles while the oscillator is running, resets the ffused resistor to $V_{\mbox{\scriptsize SS}}$ permits a power-on reset using only an external
ALE	33	0	access to o the oscillat pulse is sk '0', ALE is	external mo or frequen ipped durir emitted at	<b>ble:</b> Output pulse for latching the low byte of the address during an emory. In normal operation, ALE is emitted at a constant rate of 1/6 cy, and can be used for external timing or clocking. Note that one ALE ng each access to external data memory. If SFR bit AO (AUXR.0) is the constant rate as indicated above. With this bit set to '1', ALE will a MOVX instruction.
PSEN	32	0	code from except tha	the e <u>xterna</u> t two PSEN	<b>ble:</b> The read strobe to external program memory. When executing al program memory, PSEN is activated twice each machine cycle, N activations are skipped during each access to external data t activated during fetches from internal program memory.
EA/Vpp	35	I	to enable t high, the d	he device evice exec	able/Programming Supply Voltage: EA must be externally held low to fetch code from external program memory locations. If EA is held sutes from internal program memory. The value on the EA pin is released and any subsequent changes have no effect.
XTAL1	21	Ι	Crystal 1: circuits.	Input to the	e inverting oscillator amplifier and input to the internal clock generator
XTAL2	20	0	Crystal 2:	Output fro	m the inverting oscillator amplifier.
V <sub>SS</sub>	22	I	Ground: C	V reference	e.
V <sub>DD</sub>	44	I	Power Su Power Dov		is the power supply voltage for normal operation as well as Idle and
(NC/V <sub>SS</sub> )	1	I	connected connected pins is not V <sub>DD</sub> pins to	to V <sub>SS</sub> on to the sam required. For improve p	<b>I:</b> This pin is a no connect pin on some derivatives, but is internally the P87C51Mx2. If connected externally, this pin must only be $V_{SS}$ as at pin 22. (Note: Connecting the second pair of $V_{SS}$ and $V_{DD}$ however, they may be connected in addition to the primary $V_{SS}$ and power distribution, reduce noise in output signals, and improve aracteristics.)
(NC/V <sub>DD</sub> )	23	I	internally c be connec V <sub>DD</sub> pins is and V <sub>DD</sub> p	connected to ted to the s s not requir ins to impre	<b>Supply:</b> This pin is a no connect pin on some derivatives, but is to $V_{DD}$ on the P87C51Mx2. If connected externally, this pin must only same $V_{DD}$ as at pin 44. (Note: Connecting the second pair of $V_{SS}$ and red. However, they may be connected in addition to the primary $V_{SS}$ ove power distribution, reduce noise in output signals, and improve aracteristics.)

## 80C51 8-bit microcontroller family with extended memory

64KB/96KB OTP with 2KB/3KB RAM

## P87C51MB2/P87C51MC2

## SPECIAL FUNCTION REGISTERS

#### Note: Special Function Register (SFR) accesses are restricted in the following ways:

1. User must NOT attempt to access any SFR locations not defined.

- 2. SFR bits labeled '-', '0' or '1' can ONLY be written and read as follows:
  - '-' MUST be written with '0', but can return any value when read (even if it was written with '0'). It is a reserved bit and may be used in future derivatives.
  - '0' MUST be written with '0', and will return a '0' when read.
  - '1' MUST be written with '1', and will return a '1' when read.

#### **Special Function Registers**

SYMBOL	DESCRIPTION	DIRECT ADDRESS	MSB	BIT ADD	RESS, SYI	MBOL, OR A	ALTERNAT	E PORT FL	INCTION	LSB	Reso Valu
			E7	E6	E5	E4	E3	E2	E1	E0	
ACC*	Accumulator	E0H									00F
AUXR#	Auxiliary Function Register	8EH	-	-	-	-	-	-	EXTRAM	AO	00H
AUXR1#	Auxiliary Function Register 1	A2H	-	-	-	LPEP	GF2	0	-	DPS	00H
			F7	F6	F5	F4	F3	F2	F1	F0	
3*	B Register	F0H									00F
BRGR0#§	Baud Rate Generator Rate Low	86H‡	BRATE11	BRATE10	BRATE9	BRATE8	BRATE7	BRATE6	BRATE5	BRATE4	00H
BRGR1#§	Baud Rate Generator Rate High	87H <sup>‡</sup>	BRATE3	BRATE2	BRATE1	BRATE0	-	-	-	-	00H
BRGCON#	Baud Rate Generator Control	85H <sup>‡</sup>	-	-	-	-	-	-	SOBRGS	BRGEN	00⊦
CCAP0H#	Module 0 Capture High	FAH									XX
CCAP1H#	Module 1 Capture High	FBH									XX
CCAP2H#	Module 2 Capture High	FCH									XX
CCAP3H#	Module 3 Capture High	FDH									XX
CCAP4H#	Module 4 Capture High	FEH									XX
CCAP0L#	Module 0 Capture Low	EAH									XX
CCAP1L#	Module 1 Capture Low	EBH									XX
CCAP2L#	Module 2 Capture Low	ECH									XX
CCAP3L#	Module 3 Capture Low	EDH									XX
CCAP4L#	Module 4 Capture Low	EEH									XX
CCAPM0#	Module 0 Mode	DAH	-	ECOM_0	CAPP_0	CAPN_0	MAT_0	TOG_0	PWM_0	ECCF_0	00⊦
CCAPM1#	Module 1 Mode	DBH	-	ECOM_1	CAPP_1	CAPN_1	MAT_1	TOG_1	PWM_1	ECCF_1	00
CCAPM2#	Module 2 Mode	DCH	-	ECOM_2	CAPP_2	CAPN_2	MAT_2	TOG_2	PWM_2	ECCF_2	00
CCAPM3#	Module 3 Mode	DDH	-	ECOM_3	CAPP_3	CAPN_3	MAT_3	TOG_3	PWM_3	ECCF_3	00⊢
CCAF IVIS#		1		ECOM_4	CAPP_4	CAPN_4	MAT_4	TOG_4			1

## P87C51MB2/P87C51MC2

## **Special Function Registers (Continued)**

SYMBOL	DESCRIPTION	DIRECT ADDRESS	MSB	BIT ADD	DRESS, SYN	IBOL, OR I	ALTERNAT	E PORT FU	INCTION	LSB	Rese Value
			DF	DE	DD	DC	DB	DA	D9	D8	
CCON#	PCA Counter Control	D8H	CF	CR	-	CCF4	CCF3	CCF2	CCF1	CCF0	00H <sup>%</sup>
H#	PCA Counter High	F9H									00H
CL#	PCA Counter Low	E9H									00H
MOD#	PCA Counter Mode	D9H	CIDL	WDTE	-	-	-	CPS1	CPS0	ECF	00H <sup>9</sup>
PTR	Data Pointer (2 bytes)										00H
DPH	Data Pointer High	83H									00H
DPL	Data Pointer Low	82H									00H
PL#	Extended Data Pointer Low	FCH <sup>‡</sup>									00H
PM#	Extended Data Pointer Middle	FDH <sup>‡</sup>									00H
PH#	Extended Data Pointer High	FEH <sup>‡</sup>									00H
			AF	AE	AD	AC	AB	AA	A9	A8	
EN0*	Interrupt Enable 0	A8H	EA	EC	ET2	ES0/ ES0R	ET1	EX1	ET0	EX0	00H
			EF	EE	ED	EC	EB	EA	E9	E8	
EN1*	Interrupt Enable 1	E8H	-	-	-	-	ESPI	ES1T	ESOT	ES1/ ES1R	00H <sup>9</sup>
			BF	BE	BD	BC	BB	BA	B9	B8	
P0*	Interrupt Priority	B8H	-	PPC	PT2	PS0/ PS0R	PT1	PX1	PT0	PX0	00H
						FOOR					
P0H	Interrupt Priority 0 High	B7H	-	PPCH	PT2H	PS0H/ PS0RH	PT1H	PX1H	PT0H	PX0H	00H
			FF	FE	FD	FC	FB	FA	F9	F8	
P1*	Interrupt Priority 1	F8H	-	-	-	-	PSPI	PS1T	PS0T	PS1/ PS1R	00H <sup>9</sup>
P1H	Interrupt Priority 1 High	F7H	-	-	-	-	PSPIH	PS1TH	PS0TH	PS1H/ PS1RH	00H <sup>9</sup>
		t		i	l i		1		50144	l	0.01.1 <sup>0</sup>
1XCON#	MX Control Register	FFH <sup>‡</sup>	-	-	-	-	-	EAM	ESMM	EIFM	00H <sup>9</sup>
0.*	Dort 0	0011	87	86	85	84	83	82	81	80	
90*	Port 0	80H	AD7	AD6	AD5	AD4	AD3	AD2	AD1	AD0	FFH
21*	Dort 1		97	96	95 CEX2/	94	93	92	91	90	
1.	Port 1	90H	CEX4	CEX3	CEX2/ SPICLK	CEX1/ MOSI	CEX0	ECI	T2EX	T2	FFH

## P87C51MB2/P87C51MC2

## **Special Function Registers (Continued)**

2 3 4 er Control Register ram Status Word er2 Capture High er2 Capture Low	АОН ВОН СОН <sup>‡</sup> 87Н ООН СВН САН	A7 AD15 B7 RD C7 <sup>‡</sup> - SMOD1 D7 CY	A6 AD14/ AD22 B6 WR C6 <sup>‡</sup> - SMOD0 D6	A5 ADA13/ AD21 B5 T1 C5 <sup>‡</sup> -	A4 AD12/AD20 B4 T0 C4 <sup>‡</sup> -	A3 AD11/ AD19 B3 INT1 C3 <sup>‡</sup>	A2 AD10/ AD18 B2 INT0 C2 <sup>‡</sup> -	A1 AD9/ AD17 B1 TxD0 C1 <sup>‡</sup> TxD1/ <del>SS</del>	A0 AD8/ AD16 B0 RxD0 C0 <sup>‡</sup> RxD1/	FFH FFH
3 4 er Control Register ram Status Word vr2 Capture High or2 Capture Low	вон Сон‡ 87Н Doн Свн	AD15 B7 RD C7 <sup>‡</sup> - SMOD1 D7	AD14/ AD22 B6 WR C6 <sup>‡</sup> - SMOD0	ADA13/ AD21 B5 T1 C5 <sup>‡</sup>	AD12/AD20 B4 T0 C4 <sup>‡</sup> -	AD11/ AD19 B3 INT1 C3 <sup>‡</sup>	AD10/ AD18 B2 INT0 C2 <sup>‡</sup>	AD9/ AD17 B1 TxD0 C1 <sup>‡</sup>	AD8/ AD16 B0 RxD0 C0 <sup>‡</sup>	
4 er Control Register ram Status Word br2 Capture High br2 Capture Low	СоН <sup>‡</sup> 87Н D0Н СВН	RD C7 <sup>‡</sup> - SMOD1 D7	B6 WR C6 <sup>‡</sup> - SMOD0	B5 T1 C5 <sup>‡</sup>	T0 C4 <sup>‡</sup>	B3 INT1 C3 <sup>‡</sup>	B2 INT0 C2 <sup>‡</sup>	B1 TxD0 C1 <sup>‡</sup>	B0 RxD0 C0 <sup>‡</sup>	FFH
4 er Control Register ram Status Word br2 Capture High br2 Capture Low	СоН <sup>‡</sup> 87Н D0Н СВН	RD C7 <sup>‡</sup> - SMOD1 D7	WR C6 <sup>‡</sup> - SMOD0	T1 C5 <sup>‡</sup>	T0 C4 <sup>‡</sup>	INT1 C3 <sup>‡</sup>	INT0 C2 <sup>‡</sup>	TxD0 C1 <sup>‡</sup>	RxD0 C0 <sup>‡</sup>	FFH
4 er Control Register ram Status Word br2 Capture High br2 Capture Low	СоН <sup>‡</sup> 87Н D0Н СВН	C7 <sup>‡</sup> - SMOD1 D7	C6 <sup>‡</sup> - SMOD0	C5 <sup>‡</sup>	C4 <sup>‡</sup>	C3‡	C2 <sup>‡</sup>	C1 <sup>‡</sup>	C0‡	FFH
er Control Register ram Status Word or2 Capture High or2 Capture Low	87Н D0Н СВН	- SMOD1 D7	- SMOD0	-	-					
er Control Register ram Status Word or2 Capture High or2 Capture Low	87Н D0Н СВН	SMOD1 D7	SMOD0			-	-	TxD1/SS		4
ram Status Word r2 Capture High r2 Capture Low	D0H CBH	D7		-	1				MISO	FFH
r2 Capture High r2 Capture Low	СВН		D6		POF	GF1	GF0	PD	IDL	00H/10H <sup>8</sup>
r2 Capture High r2 Capture Low	СВН	CY		D5	D4	D3	D2	D1	D0	
r2 Capture Low			AC	F0	RS1	RS0	OV	F1	Р	00H
	CAH									00H
al Port 0 Control		9F	9E	9D	9C	9B	9A	99	98	00H
	98H	SM0_0/ FE_0	SM1_0	SM2_0	REN_0	TB8_0	RB8_0	TI_0	RI_0	00H
al Port 0 Data Buffer Register	99H									ххH
al Port 0 Address Register	A9H									00H
al Port 0 Address Enable	B9H									00H
al Port 0 Status	8CH‡	DBMOD_ 0	INTLO_0	CIDIS_0	DBISEL_0	FE_0	BR_0	OE_0	STINT_0	00H%
		87 <sup>‡</sup>	86 <sup>‡</sup>	85 <sup>‡</sup>	84 <sup>‡</sup>	83 <sup>‡</sup>	82 <sup>‡</sup>	81 <sup>‡</sup>	80 <sup>‡</sup>	
al Port 1 Control	80H‡	SM0_1/ FE_1	SM1_1	SM2_1	REN_1	TB8_1	RB8_1	TI_1	RI_1	00H
al Port 1 Data buffer Register	81H <sup>‡</sup>									ХХН
al Port 1 Address Register	82H <sup>‡</sup>									00H
al Port 1 Address Enable	83H <sup>‡</sup>		r		, ,		T	1		00H
al Port 1 Status	84H <sup>‡</sup>	DBMOD_ 1	INTLO_1	CIDIS_1	DBISEL1	FE_1	BR_1	OE_1	STINT_1	00H%
k Pointer (or Stack Pointer Byte When EDATA sorted)	81H									08H
Control Register	E2H	SSIG	SPEN	DORD	MSTR	CPOL	СРНА	-	-	00H%
Configuration Register	E1H	SPIF	SPWCOL	-	-	PSC3	PSC2	PSC1	PSC0	00H <sup>%</sup>
Data	E3H									00H
k Pointer High	FBH <sup>‡</sup>									00H
al al al kEoo	Port 1 Data buffer Register Port 1 Address Register Port 1 Address Enable Port 1 Status Pointer (or Stack Pointer Byte When EDATA orted)	Port 1 Data buffer Register Port 1 Address Register Port 1 Address Enable Port 1 Address Enable Port 1 Status Port 1 Status Pointer (or Stack Pointer Byte When EDATA orted) Sorted Control Register E2H configuration Register E1H ata	Port 1 Data buffer Register     81H <sup>‡</sup> Port 1 Address Register     82H <sup>‡</sup> Port 1 Address Enable     83H <sup>‡</sup> Port 1 Status     84H <sup>‡</sup> Pointer (or Stack Pointer Syte When EDATA orted)     81H       control Register     E2H       SSIG     SSIG       control Register     E3H	Port 1 Data buffer Register     81H <sup>‡</sup> Port 1 Address Register     82H <sup>‡</sup> Port 1 Address Enable     83H <sup>‡</sup> Port 1 Status     84H <sup>‡</sup> DBMOD_     INTLO_1       Pointer (or Stack Pointer Byte When EDATA orted)     81H       oontrol Register     E2H       SSIG     SPEN       onfiguration Register     E1H       ata     E3H	Port 1 Data buffer Register     81H <sup>‡</sup> 81H <sup>‡</sup> Port 1 Address Register     82H <sup>‡</sup> Port 1 Address Enable     83H <sup>‡</sup> Port 1 Status     84H <sup>‡</sup> Pointer (or Stack Pointer Syte When EDATA orted)       oontrol Register     E2H       SSIG     SPEN       DORD       eata     E3H	Port 1 Data buffer Register     81H <sup>‡</sup> Port 1 Address Register     82H <sup>‡</sup> Port 1 Address Enable     83H <sup>‡</sup> Port 1 Status     84H <sup>‡</sup> DBMOD_     INTLO_1       CIDIS_1     DBISEL1       Pointer (or Stack Pointer Syte When EDATA orted)     81H       vontrol Register     E2H       SSIG     SPEN       DORD     MSTR       onfiguration Register     E3H	Outline     FE_1     Outline     Outline     IDD       Port 1 Data buffer Register     81H <sup>‡</sup> 82H <sup>‡</sup> 82H <sup>‡</sup> Port 1 Address Register     83H <sup>‡</sup> BMOD_1     INTLO_1     CIDIS_1     DBISEL1     FE_1       Port 1 Status     84H <sup>‡</sup> DBMOD_1     INTLO_1     CIDIS_1     DBISEL1     FE_1       Pointer (or Stack Pointer Syte When EDATA orted)     81H     E2H     SSIG     SPEN     DORD     MSTR     CPOL       oontrol Register     E2H     SSIG     SPEN     DORD     MSTR     CPOL       ata     E3H     E3H     SPIF     SPWCOL     -     PSC3	Port 1 Data buffer Register     81H <sup>‡</sup> Port 1 Address Register     82H <sup>‡</sup> Port 1 Address Enable     83H <sup>‡</sup> Port 1 Status     84H <sup>‡</sup> DBMOD_     INTLO_1       CIDIS_1     DBISEL1       FE_1     BR_1       DBMOD_     1       Port 1 Status     84H <sup>‡</sup> Pointer (or Stack Pointer Syte When EDATA orted)     81H       ontrol Register     E2H       SSIG     SPEN       DORD     MSTR       CPOL     CPHA       stata     E3H	Port 1 Data buffer Register     81H <sup>‡</sup> Port 1 Address Register     82H <sup>‡</sup> Port 1 Address Enable     83H <sup>‡</sup> Port 1 Status     84H <sup>‡</sup> DBMOD_1     INTLO_1       CIDIS_1     DBISEL1       FE_1     BR_1       OE_1       Pointer (or Stack Pointer Syte When EDATA orted)       Sontrol Register       E2H       SSIG       SPIF       SPIF	Port 1 Data buffer Register     81H <sup>‡</sup> Port 1 Address Register     82H <sup>‡</sup> Port 1 Address Enable     83H <sup>‡</sup> Port 1 Status     84H <sup>‡</sup> DBMOD_1     INTLO_1       CIDIS_1     DBISEL1       FE_1     0E_1       STINT_1       DBMOD_1       INTLO_1       CIDIS_1       DBISEL1       FE_1       BR_1       OE_1       STINT_1

## P87C51MB2/P87C51MC2

### **Special Function Registers (Continued)**

SYMBOL	DESCRIPTION	DIRECT		BIT ADD	DRESS, SYI	MBOL, OR	ALTERNA	TE PORT FU	INCTION		Reset
		ADDRE55	MSB							LSB	Value
			8F	8E	8D	8C	8B	8A	89	88	
TCON*	Timer Control Register	88H	TF1	TR1	TF0	TR0	IE1	IT1	IE0	IT0	00H
			CF	CE	CD	СС	СВ	CA	C9	C8	
T2CON#*	Timer2 Control Register	C8H	TF2	EXF2	RCLK	TCLK	EXEN2	TR2	C/T2	CP/RL2	00H
T2MOD#	Timer2 Mode Control	С9Н	-	-	-	-	-	-	T2OE	DCEN	00H <sup>%</sup>
TH0	Timer 0 High	8CH									00H
TH1	Timer 1 High	8DH									00H
TH2	Timer 2 High	CDH									00H
TL0	Timer 0 Low	8AH									00H
TL1	Timer 1 Low	8BH									00H
TL2	Timer 2 Low	ССН									00H
TMOD	Timer 0 and 1 Mode	89H	GATE	C/T	M1	MO	GATE	C/T	M1	MO	00H
WDTRST#	Watchdog Timer Reset	A6H									FFH
WDCON#	Watchdog Timer Control	8FH <sup>‡</sup>	-	-	-	-	-	WDPRE2	WDPRE1	WDPRE0	00H%

#### Notes:

- \* SFRs are bit addressable.
- # SFRs are modified from or added to the 80C51 SFRs.
- ‡ Extended SFRs accessed by preceeding the instruction with 51MX escape (opcode A5h).
- Reserved bits, must be written with 0's.
- & Power on reset is 10H. Other reset is 00H.
- § BRGR1 and BRGR0 must only be written if BRGEN in BRGCON SFR is '0'. If any of them is written if BRGEN = 1, result is unpredictable.
- % The unimplemented bits (labeled '-') in the SFRs are 'X's (unknown) at all times. '1's should NOT be written to these bits, as they may be used for other purposes in future derivatives. The reset values shown for these bits are '0's although they are unknown when read.

## P87C51MB2/P87C51MC2

## FUNCTIONAL DESCRIPTION

The following paragraphs briefly describe the features of the P87C51Mx2. For more detailed information, please refer to the P87C51Mx2 User Manual or the 51MX Architecture Reference.

#### INTERRUPTS

Table 1 summarizes the interrupt sources, flag bits, vector addresses, enable bits, priority bits, polling priority, and whether each interrupt may wake up the CPU from Power Down mode.

Description	Interrupt Flag Bit(s)	Vector Address	Interrupt Enable Bit(s)	Interrupt Priority	Polling Priority	Power Down Wakeup
External Interrupt 0	IE0	0003h	EX0 (IEN0.0)	IP0H.0, IP0.0	1 (highest)	Yes
Timer 0 Interrupt	TF0	000Bh	ET0 (IEN0.1)	IP0H.1, IP0.1	2	No
External Interrupt 1	IE1	0013h	EX1 (IEN0.2)	IP0H.2, IP0.2	3	Yes
Timer 1 Interrupt	TF1	001Bh	ET1 (IEN0.3)	IP0H.3, IP0.3	4	No
Serial Port 0 Tx and Rx <sup>1,5</sup>	TI_0 & RI_0 <sup>5</sup>	00006			6	No
Serial Port 0 Rx <sup>1,5</sup>	RI_0 <sup>5</sup>	0023h	ES0(IEN0.4)	IP0H.4, IP0.4	6	No
Timer 2 Interrupt	TF2, EXF2	002Bh	ET2 (IEN0.5)	IP0H.5, IP0.5	7	No
PCA interrupt	CF, CCFn*	0033h	EC (IEN0.6)	IP0H.6, IP0.6	5	No
Serial Port 1 Tx and Rx <sup>2,6</sup>	TI_1 & RI_1 <sup>6</sup>	00506			44	Ne
Serial Port 1 Rx <sup>2,6</sup>	RI_1 <sup>6</sup>	0053h	ES1 (IEN1.0)	IP1H.0, IP1.0	11	No
Serial Port 0 Tx <sup>3</sup>	TI_0	003Bh	EI10 (IEN1.1)	IP1H.1, IP1.1	8	No
Serial Port 1 Tx <sup>4</sup>	TI_1	0043h	EI11 (IEN1.2)	IP1H.2, IP1.2	9	No
SPI Interrupt	SPI	004Bh	EI11 (IEN1.3)	IP1H.3, IP1.3	10	No
		005Bh	EI12 (IEN1.4)	IP1H.4, IP1.4	12	No
Deserved		0063h	EI13 (IEN1.5)	IP1H.5, IP1.5	13	No
Reserved		006Bh	EI13 (IEN1.6)	IP1H.6, IP1.6	14	No
		0073h	EI14 (IEN1.7)	IP1H.7, IP1.7	15 (lowest)	No

 S0STAT.5 = 0 selects combined Serial Port 0 Tx and Rx interrupt; S0STAT.5 = 1 selects Serial Port 0 Rx interrupt only (and TX interrupt will be different, see Note 3 below).

 S1STAT.5 = 0 selects combined Serial Port 1 Tx and Rx interrupt; S1STAT.5 = 1 selects Serial Port 1 Rx interrupt only (and TX interrupt will be different, see Note 4 below).

3. This interrupt is used as Serial Port 0 Tx interrupt if and only if S0STAT.5 = 1, and is disabled otherwise.

4. This interrupt is used as Serial Port 1 Tx interrupt if and only if S1STAT.5 = 1, and is disabled otherwise.

5. If S0STAT.0 = 1, the following Serial Port 0 additional flag bits can cause this interrupt: FE\_0, BR\_0, OE\_0.

6. If S1STAT.0 = 1, the following Serial Port 1 additional flag bits can cause this interrupt: FE\_1, BR\_1, OE\_1.

Table 1: Summary of Interrupts

## P87C51MB2/P87C51MC2

#### DATA RAM

The P87C51MB2 and P87C51MC2 have 2 Kbytes and 3 K bytes of on-chip RAM respectively. Usages of the different data segments are described in the 51MX Architecture Reference.

	Data Memory	Size (ir	n Bytes)
Туре	Description	P87C51MB2	P87C51MC2
DATA	memory that can be addressed directly and indirectly	128	128
IDATA	memory that can be addressed indirectly (where direct address is for SFR only)	128	128
EDATA	memory that can only be addressed indirectly	1024	1024
XDATA	memory (on-chip "External Data") that is accessed using the MOVX instructions	768	1792
	Total	2048	3072

#### Table 2: On-Chip Data Memory Usage.

#### PORT 4

The P87C51Mx2 has a fifth I/O port (Port 4) that is shared with the second UART pins (RXD1 and TXD1) and two of the SPI pins (MISO and SS). This port is also bit addressable and can be accessed in the same manner as any other ports, except that the associated SFR is in the extended SFR space. Accesses to this SFR space is the same as those to the conventional SFR space except that the instructions must be preceeded by an escape code (A5h), as described in the 51MX Architecture Reference.

#### LOW POWER MODES

The P87C51Mx2 supports the standard 51MX low power modes - Stop Clock Mode, Idle Mode and Power-Down Mode.

The PCON register is the same as the standard 51MX PCON register. Note that bits PCON.7 and PCON.6 are for UART configurations (see section "UARTs").

### ONCE™ MODE

The ONCE ("On-Circuit Emulation") Mode facilitates testing and debugging of systems without the device having to be removed from the circuit. It is supported in the P87C51Mx2.

### PERIPHERALS

The P87C51Mx2 peripherals are described in more detail in the User Manual. The on-chip peripherals include:

- Timers:
  - Timers 0 and 1.
  - Timer 2.

Note: When Timer 1 or Timer 2 can only be used as a baud rate generator for UART 0, but not for UART 1.

• Two enhanced UARTs with an independent Baud Rate Generator - The section "UARTs" provides information regarding the two UARTs.

Note: UART 1 shares the RXD1 and TXD1 with the SPI pins. The SPEN (SPCTL.6) bit must be cleared '0' (reset value) to enable UART 1 operation.

- Serial Peripheral Interface (SPI). **Note:** The SPI shares pins with the UART 1 shares the RXD1 and TXD1 with the SPI pins. The SPEN (SPCTL.6) bit must be set to '1' to enable SPI operation.
- Watchdog Timer.
- Programmable Counter Array (PCA).

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#### UARTS

P87C51Mx2 includes two enhanced UART ports with one independent Baud Rate Generator:

- UART 0 is the standard 51MX enhanced UART as described in the User Manual. It can be selected to use Timer1 overflow, Timer2 overflow or the independent Baud Rate Generator.
- UART 1 only uses the independent Baud Rate Generator to generate its baud rate. It has the same baud rate for both transmission and reception.
- The Baud Rate Generator is described in the User Manual.

Each of the UARTs has one set of enhanced UART SFRs. Please refer to the descriptions on the corresponding SFRs in the User Manual:

Register	Description	SFR Location	51MX Extended SFR Location	See Description in User Manual on
S0CON	Serial Port 0 Control	98H		SCON
SOBUF	Serial Port 0 Data Buffer	99H		SBUF
S0ADDR	Serial Port 0 Address	A9H		SADDR
S0ADEN	Serial Port 0 Address Enable	B9H		SADEN
SOSTAT	Serial Port 0 Status		8CH	SSTAT
S1CON	Serial Port 1 Control		80H	SCON
S1BUF	Serial Port 1 Data Buffer		81H	SBUF
S1ADDR	Serial Port 1 Address		82H	SADDR
S1ADEN	Serial Port 1 Address Enable		83H	SADEN
S1STAT	Serial Port 1 Status		84H	SSTAT

#### Table 3: UARTs 0 and 1 SFRs.

#### PCON.7 and PCON.6 SFR Bits

The PCON.7 and PCON.6 SFR bits configure the UARTs as follows:

- PCON.7 (SMOD1) Baud Rate Control bit for serial port 0. When 0, the baud rate for UART 0 will be the input rate (T1 timer or baud rate generator, as determined by the BRGCON extended SFR) divided by two. When 1, the baud rate for UART 0 will be the input rate (T1 timer or baud rate generator). UART 1 is not affected by this bit
- PCON.6 (SMOD0) Framing Error Location:
  - When 0, bit 7 of S0CON and S1CON will function as SM0 for UARTs 0 and 1 respectively.
  - When 1, bit 7 of S0CON and S1CON will be used for framing error status for UART 0 and 1 respectively. PCON.6 also determines when the UART receive interrupts RI\_0 and RI\_1 occur in UART modes 2 or 3. (Refer to User Manual for details.)

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#### **Baud Rate Selection**

UART 0 and UART 1 selects the baud rate differently as shown in Tables 4 and 5:

S0CON.7 (SM0_0)	S0CON.6 (SM1_0)	T2CON.5/4 (RCLK - Receive TCLK - Transmit)	PCON.7 (SMOD1)	BRGCON.1 (S0BRGS)	Receive/Transmit Baud Rate for UART 0
0	0	Х	Х	Х	f <sub>OSC</sub> /6
		0	0	Х	T1_rate/32 <sup>*</sup>
0	1	0	1	Х	T1_rate/16 <sup>*</sup>
0	I I	1	Х	0	T2_rate/16 <sup>*</sup>
		1	Х	1	f <sub>OSC</sub> /(BRATE×16+16) <sup>*</sup>
1	0	Х	0	Х	f <sub>OSC</sub> /32
I	0	Х	1	Х	f <sub>OSC</sub> /16
		0	0	Х	T1_rate/32 <sup>*</sup>
4	4	0	1	Х	T1_rate/16 <sup>*</sup>
1	1	1	Х	0	T2_rate/16 <sup>*</sup>
		1	Х	1	f <sub>OSC</sub> /(BRATE×16+16) <sup>*</sup>

Table 4: Baud Rate Generation for UART 0. Use T2CON.5 (RCLK) in Receive Baud Rate Selection, T2CON.4 (TCLK) in Transmit Baud Rate Selection

S1CON.7 (SM0_1)	S1CON.6 (SM1_1)	Baud Rate for UART 1
0	0	f <sub>OSC</sub> /6
0	1	f <sub>OSC</sub> /(BRATE×16+16) <sup>*</sup>
1	0	f <sub>OSC</sub> /(BRATE×16+16) <sup>*</sup>
1	1	f <sub>OSC</sub> /(BRATE×16+16) <sup>*</sup>
* UART1h	as the same r	eceive and transmit baud rate.

Table 5: Baud Rate Generation for UART 1.

## P87C51MB2/P87C51MC2

### SECURITY BITS

The P87C51Mx2 has security bits to protect users' firmware codes. With none of the security bits programmed, the code in the program memory can be verified. With only security bit 1 (see Table 6) is programmed, MOVC instructions executed from external program memory are disabled from fetching code bytes from the internal memory. EA is latched on Reset and all further programming of EPROM is disabled. When security bits 1 and 2 are programmed, in addition to the above, verify mode is disabled. When all three security bits are programmed, all of the conditions above apply and all external program memory execution is disabled.

	Security Bits <sup>1,2</sup>			
	Bit 1	Bit 2	Bit 3	Protection Description
1	U	U	U	No program security features enabled. EEPROM is programmable and verifiable.
2	Р	U	U	MOVC instructions executed from external program memory are disabled from fetching code bytes from internal memory, EA is sampled and latched on Reset, and further programming of the EPROM is disabled.
3	Р	Р	U	Same as 2, also verification is disabled.
4	Р	Р	Р	Same as 3, external execution is disabled.
<b>Notes:</b> 1. P - p	rogramm	ed. U- un	program	med.

2. Any other combination of security bits is not defined.

**Table 6: EPROM Security Bits** 

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### **ABSOLUTE MAXIMUM RATINGS**

PARAMETER	RATING	UNIT
Operating temperature under bias	-55 to +125	°C
Storage temperature range	-65 to +150	°C
Voltage on EA/V <sub>PP</sub> pin to V <sub>SS</sub>	0 to + 13.0	V
Voltage on any other pin to V <sub>SS</sub>	-0.5 to V <sub>DD</sub> +0.5V	V
Maximum I <sub>OL</sub> per I/O pin	20	mA
Power dissipation (based on package heat transfer, not device power consumption)	1.5	W

Notes:

- Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress
  rating only and functional operation of the device at these or any conditions other than those described in the AC and DC
  Electrical Characteristics section of this specification are not implied.
- 2. This product includes circuitry specifically designed for the protection of its internal devices from the damaging effects of excessive static charge. Nonetheless, it is suggested that conventional precautions be taken to avoid applying greater than the rated maximum.
- 3. Parameters are valid over operating temperature range unless otherwise specified. All voltages are with respect to V<sub>SS</sub> unless otherwise noted.

## P87C51MB2/P87C51MC2

## DC ELECTRICAL CHARACTERISTICS

V<sub>DD</sub> = 2.7V to 5.5V unless otherwise specified;

 $T_{amb} = 0$  to +70°C for commercial, unless otherwise specified.

	DADAMETER	TEST CONDITIONS	LIMITS				
SYMBOL	PARAMETER	TEST CONDITIONS	MIN	TYP <sup>1</sup>	MAX	UNIT	
V <sub>IL</sub>	Input low voltage		-0.5		0.2V <sub>DD</sub> -0.1	V	
V <sub>IH</sub>	In <u>put</u> high voltage (ports 0, 1, 2, 3, 4, EA)		0.2V <sub>DD</sub> +0.9		V <sub>DD</sub> +0.5	V	
V <sub>IH1</sub>	Input high voltage, XTAL1, RST		0.7V <sub>DD</sub>		V <sub>DD</sub> +0.5	V	
V <sub>OL</sub>	Output low voltage, ports 1, 2, 3, 4 <sup>8</sup>	V <sub>DD</sub> = 2.7V, I <sub>OL</sub> = 1.6mA			0.4	V	
V <sub>OL1</sub>	Output low voltage, port 0, ALE, PSEN <sup>7,8</sup>	V <sub>DD</sub> = 2.7V, I <sub>OL</sub> = 3.2mA			0.4	V	
V <sub>OH</sub>	Output high voltage, ports 1, 2, 3, 4	$V_{DD} = 4.5V, I_{OH} = -30\mu A$ $V_{DD} = 2.7V, I_{OH} = -10\mu A$	V <sub>DD</sub> - 0.7			V	
V <sub>OH1</sub>	Output high voltage (port 0 in external bus mode), ALE <sup>9</sup> , PSEN <sup>3</sup>	$V_{DD} = 2.7V, I_{OH} = -3.2mA$	V <sub>DD</sub> - 0.7			V	
I <sub>IL</sub>	Logical 0 input current, ports 1, 2, 3, 4	V <sub>IN</sub> = 0.4V	-1		-75	μA	
I <sub>TL</sub>	Logical 1 -to-0 transition current, ports 1, 2, 3, 4 <sup>8</sup>	4.5V < V <sub>DD</sub> < 5.5V, V <sub>IN</sub> = 2.0V, See Note 4			-650	μA	
I <sub>L1</sub>	Input leakage current, port 0	0.45 < V <sub>IN</sub> < V <sub>DD</sub> -0.3			±10	μA	
	Power supply current						
	Active mode (see Note 5)	V <sub>DD</sub> = 5.5V			7 + 2.7 /MHz × f <sub>OSC</sub>	mA	
		V <sub>DD</sub> = 3.6V			4 + 1.3 /MHz × f <sub>OSC</sub>		
I <sub>CC</sub>	Idle mode (see Note 5)	V <sub>DD</sub> = 5.5V			4 + 1.3 /MHz × f <sub>OSC</sub>	mA	
		V <sub>DD</sub> = 3.6V			1 + 1.0 /MHz × f <sub>OSC</sub>		
	Power-down mode or clock	V <sub>DD</sub> = 5.0V		20		μA	
	stopped (see Figure 16 for conditions)	V <sub>DD</sub> = 5.5V			100	μA	
R <sub>RST</sub>	Internal reset pull-down resistor		40		225	kΩ	
C <sub>10</sub>	Pin capacitance <sup>10</sup> (except $\overline{EA}$ )			1	15	pF	

#### Notes:

1. Typical ratings are not guaranteed. The values listed are at room temperature (+25°C), 5V, unless otherwise stated.

- 2. Capacitive loading on ports 0 and 2 may cause spurious noise to be superimposed on the V<sub>OL</sub> of ALE and ports 1, 3 and 4. The noise is due to external bus capacitance discharging into the port 0 and port 2 pins when these pins make 1-to-0 transitions during bus operations. In the worst cases (capacitive loading>100 pF), the noise pulse on the ALE pin may exceed 0.8 V. In such cases, it may be desirable to qualify ALE with a Schmitt Trigger, or use an address latch with a Schmitt Trigger STROBE input. I<sub>OL</sub> can exceed these conditions provided that no single output sinks more than 5mA and no more than two
- outputs exceed the test conditions.
   Capacitive loading on ports 0 and 2 may cause the V<sub>OH</sub> on ALE and PSEN to momentarily fall below the V<sub>DD</sub>-0.7V specification when the address bits are stabilizing.
- Pins of ports 1, 2, 3 and 4 source a transition current when they are being externally driven from 1 to 0. The transition current reaches its maximum value when V<sub>IN</sub> is approximately 2 V for 4.5V < V<sub>DD</sub> < 5.5V.</li>
- 5. See Figures 13 through 16 for I<sub>CC</sub> test conditions. f<sub>OSC</sub> is the oscillator frequency in MHz.
- 6. This value applies to  $T_{amb} = 0^{\circ}C$  to +70°C.

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7. Load capacitance for port 0, ALE, and  $\overline{PSEN} = 100 \text{ pF}$ , load capacitance for all other outputs = 80pF

8. Under steady state (non-transient) conditions, I<sub>OL</sub> must be externally limited as follows:

Maximum I<sub>OL</sub> per port pin:15 mAMaximum I<sub>OL</sub> per 8-bit port:26 mA

Maximum total I<sub>OL</sub> for all outputs: 71 mA

If I<sub>OL</sub> exceeds the test condition, V<sub>OL</sub> may exceed the related specification. Pins are not guaranteed to sink current greater than the listed test conditions.

9. ALE is tested to V<sub>OH1</sub>, except when ALE is off then V<sub>OH</sub> is the voltage specification.

10. Pin capacitance is characterized but not tested.

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## AC ELECTRICAL CHARACTERISTICS

T <sub>amb</sub> = 0 to +70°C for commercial unless otherwise specified. <sup>1</sup>	,2,3
$amb = 0.00 \pm 70.00$ for commercial diffess otherwise specified.	

			2	2.7V < VDD < 5	5.5V		4	1.5V < VDD < 5	5.5V		1
SYMBOL	FIGURE(S)	PARAMETER	Variable Clock <sup>4</sup>			12MHz <sup>4</sup>	Variable Clock <sup>4</sup>		f <sub>OSC</sub> =24MHz <sup>4</sup>		UNIT
			MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX	
fosc		Oscillator frequency	0	12			0	24			MH
t <sub>CLCL</sub>	15	CLock cycle			83				41.5		ns
t <sub>LHLL</sub>	1,2	ALE pulse width	t <sub>CLCL</sub> -66		16		t <sub>CLCL</sub> -33		8		ns
t <sub>AVLL</sub>	1,2,3, 4,5,6	Address valid to ALE low	t <sub>CHCX</sub> -25		8		t <sub>CHCX</sub> -12		4		ns
t <sub>LLAX</sub>	1,2,3, 4,5,6	Address hold after ALE low	t <sub>CLCX</sub> -25		8		t <sub>CLCX</sub> -12		4		ns
t <sub>LLIV</sub>	1,2	ALE low to valid instruction in		2t <sub>CLCL</sub> -108		58		2t <sub>CLCL</sub> -54		29	ns
t <sub>LLPL</sub>	1,2	ALE low to PSEN low	t <sub>CLCX</sub> -25		8		t <sub>CLCX</sub> -12		4		ns
t <sub>PLPH</sub>	1,2	PSEN pulse width	t <sub>CLCL</sub> +t <sub>CHCX</sub> -66		50		t <sub>CLCL</sub> +t <sub>CHCX</sub> -33		25		ns
t <sub>PLIV</sub>	1,2	PSEN low to valid instruction in		t <sub>CLCL</sub> +t <sub>CHCX</sub> -91		25		t <sub>CLCL</sub> +t <sub>CHCX</sub> -46		12	ns
t <sub>PXIX</sub>	1,2	Input instruction hold after PSEN	0		0		0		0		ns
t <sub>PXIZ</sub>	1,2	Input instruction float after PSEN		t <sub>CLCX</sub> -25		8		t <sub>CLCX</sub> -12		4	ns
t <sub>AVIV</sub>	1	Address (A8-A15) to valid instruction in (non-Extended Addressing Mode)		2t <sub>CLCL</sub> +t <sub>CHCX</sub> -36		180		2t <sub>CLCL</sub> +t <sub>CHCX</sub> -28		81	ns
t <sub>AVIV1</sub>	2	Address (A8-A15) to valid instruction in (Extended Addressing Mode)		t <sub>CLCL</sub> +t <sub>CHCX</sub> -44		89		2t <sub>CLCL</sub> +t <sub>CHCX</sub> -34		33	ns
t <sub>PLAZ</sub>	1,2	PSEN low to address float		16		16		8		8	ns
Data Mem	ory	· · · · · ·					•	•			
t <sub>RLRH</sub>	3,4	RD pulse width	3t <sub>CLCL</sub> -166		83		3t <sub>CLCL</sub> -83		41.5		n
t <sub>WLWH</sub>	5,6	WR pulse width	3t <sub>CLCL</sub> -166		83		3t <sub>CLCL</sub> -83		41.5		n
t <sub>RLDV</sub>	3,4	RD low to valid data in		2t <sub>CLCL</sub> +t <sub>CHCX</sub> -141		58		2t <sub>CLCL</sub> +t <sub>CHCX</sub> -70		29	ns
t <sub>RHDX</sub>	3,4	Data hold after RD	0		0		0		0		ns
t <sub>RHDZ</sub>	3,4	Data float after RD		t <sub>CLCL</sub> -34		49		t <sub>CLCL</sub> -17		24	n
t <sub>LLDV</sub>	3,4	ALE low to valid data in		4t <sub>CLCL</sub> -250		83		4t <sub>CLCL</sub> -125		41	n
t <sub>AVDV</sub>	3	Address (A8-A15) to valid data in (non-Extended Addressing Mode)		4t <sub>CLCL</sub> +t <sub>CHCX</sub> -36		346		4t <sub>CLCL</sub> +t <sub>CHCX</sub> -28		164	ns
t <sub>AVDV1</sub>	4	Address (A8-A15) to valid data in (Extended Addressing Mode)		3t <sub>CLCL</sub> +t <sub>CHCX</sub> -44		255		3t <sub>CLCL</sub> +t <sub>CHCX</sub> -34		116	ns
t <sub>LLWL</sub>	3,4, 5,6	ALE low to $\overline{RD}$ or $\overline{WR}$ low	t <sub>CLCL</sub> +t <sub>CLCX</sub> -83	t <sub>CLCL</sub> +t <sub>CLCX</sub> +83		208	t <sub>CLCL</sub> +t <sub>CLCX</sub> -41	t <sub>CLCL</sub> +t <sub>CLCX</sub> +41		104	ns
t <sub>AVWL</sub>	3,5	Address (A8-A15) valid to WR or RD low (non-Extended Addressing Mode)	2t <sub>CLCL</sub> -15		151		2t <sub>CLCL</sub> -20		63		ns
t <sub>AVWL1</sub>	4,6	Address (A8-A15) valid to WR or RD low (Extended Addressing Mode)	t <sub>CLCL</sub> -20		63		t <sub>CLCL</sub> -25		16.5		ns
t <sub>QVWX</sub>	5,6	Data valid to WR transition	t <sub>CLCX</sub> -33		0		t <sub>CLCX</sub> -16		0		ns
t <sub>WHQX</sub>	5,6	Data hold after WR	t <sub>CHCX</sub> -24		9		t <sub>CHCX</sub> -11		5		ns
t <sub>QVWH</sub>	5,6	Data valid to $\overline{WR}$ high	3t <sub>CLCL</sub> +t <sub>CLCX</sub> -207		75		3t <sub>CLCL</sub> +t <sub>CLCX</sub> -103		37.5		n
t <sub>RLAZ</sub>	3,4	RD low to address float		0		0		0		0	n
t <sub>WHLH</sub>	3,4, 5,6	RD or WR high to ALE high	t <sub>CHCX</sub> -24	t <sub>CHCX</sub> +25	9	75	t <sub>CHCX</sub> -11	t <sub>CHCX</sub> +12	5	37	ns
External C	Clock										
t <sub>CHCX</sub>	12	High time	33	$t_{CLCL}-t_{CLCX}$	33	50	16	t <sub>CLCL</sub> -t <sub>CLCX</sub>	16	24.5	n
t <sub>CLCX</sub>	12	Low time	33	t <sub>CLCL</sub> -t <sub>CHCX</sub>	33	50	16	t <sub>CLCL</sub> -t <sub>CHCX</sub>	16	24.5	n
t <sub>CLCH</sub>	12	Rise time		8		8		4		4	ns
t <sub>CHCL</sub>	12	Fall Time		8		8		4		4	n

## P87C51MB2/P87C51MC2

			2	2.7V < VDD <	5.5V		4.5V < VDD < 5.5V				
SYMBOL	FIGURE(S)	PARAMETER	Variable Clock <sup>4</sup> f <sub>OSC</sub> =12MHz <sup>4</sup>			Variable	f <sub>OSC</sub> =24MHz <sup>4</sup>		UNIT		
			MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX	
Shift Regi	ster										
t <sub>XLXL</sub>	7	Serial port clock cycle time	6t <sub>CLCL</sub>		500		6t <sub>CLCL</sub>		250		ns
t <sub>QVXH</sub>	7	Output data setup to clock rising edge	5t <sub>CLCL</sub> -221		195		5t <sub>CLCL</sub> -110		98		ns
t <sub>XHQX</sub>	7	Output data hold after clock rising edge	t <sub>CLCL</sub> -50		34		t <sub>CLCL</sub> -25		17		ns
t <sub>XHDX</sub>	7	Input data hold after clock rising edge	0		0		0		0		ns
t <sub>XHDV</sub>	7	Clock rising edge to input data valid		5t <sub>CLCL</sub> -222		195		5t <sub>CLCL</sub> -111		97	ns
SPI Interfa	ice		•				•				
		Operating frequency									
f <sub>SPI</sub>		- 3.0MHz	0	3.0	0	3.0	0	3.0	0	3.0	MHz
		- 6.0MHz	-	-	-	-	0	6.0	0	6.0	
		Cycle time									
t <sub>SPICYC</sub>	8, 9, 10, 11	- 3.0MHz	333		333		333		333		ns
		- 6.0MHz	-		-		166		166		
		Enable lead time (Slave)									
t <sub>SPILEAD</sub>	10, 11	- 3.0MHz	TBD		TBD		TBD		TBD		ns
		- 6.0MHz	-		-		TBD		TBD		
		Enable lag time (Slave)									
t <sub>SPILAG</sub>	10, 11	- 3.0MHz	TBD		TBD		TBD		TBD		ns
		- 6.0MHz	-		-		TBD		TBD		
		SPICLK high time									
t <sub>SPICLKH</sub>	8, 9, 10, 11		TBD		TBD		TBD		TBD		ns
		- Slave	TBD		TBD		TBD		TBD		
		SPICLK low time									
t <sub>SPICLKL</sub>	8, 9, 10, 11	- Master	TBD		TBD		TBD		TBD		ns
		- Slave	TBD		TBD		TBD		TBD		
t <sub>SPIDSU</sub>	8, 9, 10, 11	Data setup time (Master or Slave)	TBD		TBD		TBD		TBD		ns
t <sub>SPIDH</sub>		Data hold time (Master or Slave)	TBD		TBD		TBD		TBD		ns
t <sub>SPIA</sub>	10, 11	Access time (Slave)		TBD		TBD		TBD		TBD	ns
-SPIA	10, 11	Disable time (Slave)		100		100		100		100	110
taninia	10, 11	- 3.0MHz		TBD		TBD		TBD		TBD	ns
t <sub>SPIDIS</sub>	10, 11	- 6.0MHz		TBD		TBD		TBD		TBD	115
		Enable to output data valid		IBD		TBD		שטו		TBD	
t	8, 9, 10, 11			TBD		TBD		TBD		TBD	-
t <sub>SPIDV</sub>	0, 9, 10, 11	- 6.0MHz		IBD				TBD		TBD	ns
+	0 0 10 11		0	-	0	-	0	TBD	0	TBD	
t <sub>SPIOH</sub>	8, 9, 10, 11	Output data hold time	0		0		0		0		ns
		Rise time		TDD		TDD		TDD		TDD	
t <sub>SPIR</sub> 8,	8, 9, 10, 11	- SPI outputs (SPICLK,MOSI, MISO)		TBD		TBD		TBD		TBD	ns
		- <u>SPI</u> inputs (SPICLK,MOSI, MISO, SS)		TBD		TBD		TBD		TBD	
		Fall time									
t <sub>SPIF</sub>	8, 9, 10, 11	<ul> <li>SPI outputs (SPICLK,MOSI, MISO)</li> <li><u>SPI</u> inputs (SPICLK,MOSI, MISO, SS)</li> </ul>		TBD		TBD		TBD		TBD	ns
		- SPI inputs (SPICLK.MOSI, MISO,		TBD		TBD	1	TBD		TBD	

#### Notes:

1. Parameters are valid over operating temperature range unless otherwise specified.

2. Load capacitance for port 0, ALE, and  $\overrightarrow{PSEN} = 100pF$ , load capacitance for all other outputs = 80pF.

3. Interfacing the microcontroller to devices with float times up to 45ns is permitted. This limited bus contention will not cause damage to Port 0 drivers.

4. Parts are tested down to 2 MHz, but are guaranteed to operate down to 0Hz.

## P87C51MB2/P87C51MC2

#### **EXPLANATION OF AC SYMBOLS**

Each timing symbol has five characters. The first character is always 't' (= time). The other characters, depending on their positions, indicate the name of a signal or the logical status of that signal. The designations are:

- A Address
- C Clock
- D Input data
- H Logic level high
- I Instruction (program memory contents)
- L Logic level low, or ALE
- P PSEN
- Q Output data
- R RD signal
- t Time
- V Valid
- W- WR signal
- X No longer a valid logic level
- Z Float

#### Examples:

t<sub>AVLL</sub> - Time for address valid to ALE low.

t<sub>LLPL</sub> - Time for ALE low to PSEN low



Figure 1: External Program Memory Read Cycle (Non-Extended Memory Cycle)



Figure 2: External Program Memory Read Cycle (Extended Memory Cycle)



Figure 3: External Data Memory Read Cycle (Non-Extended Memory Cycle)



Figure 4: External Data Memory Read Cycle (Extended Memory Cycle)



Figure 5: External Data Memory Write Cycle (Non-Extended Memory Cycle)



Figure 6: External Data Memory Write Cycle (Extended Memory Cycle)



Figure 7: Shift Register Mode Timing



Figure 8: SPI Master Timing (CPHA = 0)



Figure 9: SPI Master Timing (CPHA = 1)



Figure 10: SPI Slave Timing (CPHA = 0)



Figure 11: SPI Slave Timing (CPHA = 1)



Figure 12: External Clock Drive



Figure 13:  $I_{CC}$  Test Condition, Active Mode (All other pins are disconnected)



Figure 14: I<sub>CC</sub> Test Condition, Idle Mode (All other pins are disconnected)



Figure 15: Clock Signal Waveform for  $I_{CC}$  Tests in Active and Idle Modes  $t_{CLCH} = t_{CHCL} = 5$ ns



Figure 16:  $I_{CC}$  Test Condition, Power Down Mode (All other pins are disconnected,  $V_{DD}$  = 2.0V to 5.5V)

#### P87C51MB2/P87C51MC2

#### Data sheet status

Data sheet status	Product status	Definition <sup>[1]</sup>
Objective specification	Development	This data sheet contains the design target or goal specifications for product development. Specification may change in any manner without notice.
Preliminary specification	Qualification	This data sheet contains preliminary data, and supplementary data will be published at a later date. Philips Semiconductors reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.
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[1] Please consult the most recently issued datasheet before initiating or completing a design.

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# Errata sheet

### P87C51MB2/P87C51MC2

## FUNCTIONAL DEVIATIONS

### **Deviation #1**

RxD1 pin is an open drain configuration.

### Work-around:

A resistor must be used if this pin is to be used as an output. These pins will become port 4 on the next release fixing this issue.

### **Deviation #2**

Port 4 does not exist for the RxD1 and TxD1 pins. DC parameters differ from standard port pins.

### Work-around:

None. These pins will become port 4 on the next release.

### **Deviation #3**

RxD1, TxD1, and ALE pins will not go into once mode.

### Work-around:

None. This will be fixed on the next release.

## Deviation #4

In the UART, the contents of RB8 and SBUF change when they shouldn't if SM2=1 in modes 2 and 3.

### Work-around:

None. Will be fixed on the next release.

### **Deviation #5**

The UART double buffering will be implemented on the next release.

### Work-around:

None.

### **Deviation #6**

SPI block will be implemented on the next release.

### Work-around:

None.

### Deviation #7

Security bits are not 100% compatible with past 80c51 products.

### Work-around:

The security bits will be compatible on the next release.

# Errata sheet

#### P87C51MB2/P87C51MC2

### **Deviation #8**

UART mode 0 receive data is sampled one clock later than standard 80C51 UARTS.

### Work-around:

This requires an increased data hold time. This will be fixed on the next release.

### **Deviation #9**

The PCA Watchdog timer function may not function properly at 24 MHz  $f_{OSC}$  when the PCA Count Pulse selection is set to "internal clock,  $f_{OSC}/2$ ".

### Work-around:

None. This will be fixed on the next release.