#### **General Description**

The MAX3443E fault-protected RS-485/RS-422 transceiver features ±60V protection from signal faults on communication bus lines. Each device contains one differential line driver with three-state output, and one differential line receiver with three-state input. The 1/4-unit-load receiver input impedance allows up to 128 transceivers on a single bus. The device operates from a 5V supply at data rates up to 10Mbps. True fail-safe inputs guarantee a logic-high receiver output when the receiver inputs are open, shorted, or connected to an idle data line.

Hot-swap circuitry eliminates false transitions on the data cable during circuit initialization or connection to a live backplane. Short-circuit current limiting and thermal shutdown circuitry protect the driver against excessive power dissipation, and integrated  $\pm 15$ kV ESD protection eliminates costly external protection devices.

The MAX3443E is available in 8-pin SO and PDIP packages, and is specified over commercial, industrial, and automotive temperature ranges.

#### Applications

RS-422/RS-485 Communications Industrial Networks Telecommunication Systems Automotive Applications HVAC Controls

#### **Features**

- ♦ ±60V Fault Protection
- ±15kV ESD Protection
- Guaranteed 10Mbps Data Rate
- Allows Up to 128 Transceivers on the Bus
- ♦ -7V to +12V Common-Mode Input Range
- ♦ True Fail-Safe Receiver Inputs
- Hot-Swap Inputs for Telecom Applications
- ♦ Automotive Temperature Range (-40°C to +125°C)

Industry-Standard Pinout

#### **Ordering Information**

PART	TEMP RANGE	PIN-PACKAGE
MAX3443ECSA	0°C to +70°C	8 SO
MAX3443ECPA	0°C to +70°C	8 PDIP
MAX3443EESA	-40°C to +85°C	8 SO
MAX3443EEPA	-40°C to +85°C	8 PDIP
MAX3443EASA	-40°C to +125°C	8 SO
MAX3443EAPA	-40°C to +125°C	8 PDIP

### Pin Configuration and Typical Operating Circuit



#### 

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For pricing, delivery, and ordering information, please contact Maxim/Dallas Direct! at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.

# **MAX3443E**

#### **ABSOLUTE MAXIMUM RATINGS**

All Voltages Referenced with Respect to GND

V <sub>CC</sub> +7V
$\overline{RE}$ , DE, DI0.3V to (V <sub>CC</sub> + 0.3V)
A, B (Note 1)±60V
RO0.3V to (V <sub>CC</sub> + 0.3V)
Continuous Power Dissipation ( $T_A = +70^{\circ}C$ )
8-Pin SO (derate 5.9mW/°C above +70°C)471mW
8-Pin PDIP (derate 9.09mW/°C above +70°C)727mW

Operating Temperature Ranges	
MAX3443EC	0°C to +70°C
MAX3443EE	40°C to +85°C
MAX3443EA	40°C to +125°C
Storage Temperature Range	65°C to +150°C
Short-Circuit Duration (RO, A, B)	Continuous
Lead Temperature (soldering, 10s)	

Note 1: A, B must be terminated with  $54\Omega$  or  $100\Omega$  to guarantee ±60V fault protection.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### DC ELECTRICAL CHARACTERISTICS

(V<sub>CC</sub> = +4.75V to +5.25V,  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at V<sub>CC</sub> = +5V and  $T_A = +25^{\circ}$ C.)

PARAMETER	SYMBOL		CONDITIONS	MIN	ТҮР	МАХ	UNITS
DRIVER							
	N	Figure 1, $R_L = 50\Omega$		2.0		V <sub>CC</sub>	V
Differential Driver Output	VOD	Figure 1, RL	_ = 27Ω	1.5		V <sub>C</sub> C	V
Change in Magnitude of Differential Output Voltage	$\Delta V_{OD}$	Figure 1, R <sub>L</sub>	$= 50\Omega$ or $27\Omega$ (Note 2)			0.2	V
Driver Common-Mode Output Voltage	V <sub>OC</sub>	Figure 1, RL	$= 50\Omega$ or $27\Omega$		V <sub>CC</sub> / 2	3	V
Change In Magnitude of Common-Mode Voltage	ΔV <sub>OC</sub>	Figure 1, RL	$_{-} = 50\Omega$ or $27\Omega$ (Note 2)			0.2	V
DRIVER LOGIC		•					
Driver Input High Voltage	VDIH			2.0			V
Driver Input Low Voltage	VDIL					0.8	V
Driver Input Current	I <sub>DIN</sub>					±2	μA
Driver Output Fault Current	IOFC	V <sub>A, B</sub> = ±60	V, $R_L = 54\Omega$			±6	mA
Driver Short-Circuit Output Current	I <sub>OSD</sub>	-7V ≤ V <sub>OUT</sub> (Note 3)	≤ +12V			±350	mA
Driver Short-Circuit Foldback Output Current	IOSDF	-7V ≤ V <sub>OUT</sub> ≤ +12V (Note 3)				±25	mA
RECEIVER							
			eq:def-def-def-def-def-def-def-def-def-def-			250	μA
Input Current	I <sub>A,B</sub>	А, В	V <sub>A, B</sub> = -7V			-150	
			VA, B = ±60V			±6	mA
Receiver Differential Threshold Voltage	V <sub>TH</sub>	$-7V \le V_{CM} \le +12V$		-200		-50	mV
Receiver Input Hysteresis	$\Delta V_{TH}$				25		mV

#### DC ELECTRICAL CHARACTERISTICS (continued)

 $(V_{CC} = +4.75V \text{ to } +5.25V, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } V_{CC} = +5V \text{ and } T_A = +25^{\circ}C.)$ 

PARAMETER	SYMBOL	CONDITIONS	MIN TYP	MAX	UNITS
RECEIVER LOGIC			·		
Output High Voltage	VOH	Figure 2, $I_{OH} = -1.6mA$	V <sub>CC</sub> - 0.6		V
Output Low Voltage	Vol	Figure 2, I <sub>OL</sub> = 1mA		0.4	V
Three-State Output Current at Receiver	I <sub>OZR</sub>	$0 \le V_{A, B} \le V_{CC}$		±1	μA
Receiver Input Resistance	R <sub>IN</sub>	$-7V \le V_{CM} \le +12V$	48		kΩ
Receiver Output Short-Circuit Current	IOSR	$0 \le V_{RO} \le V_{CC}$		±95	mA
CONTROL		·	·		
Control Input High Voltage	VCIH	DE, RE	2.0		V
Input Current DE Current Latch During First DE Rising Edge			90		μA
Input Current RE Current Latch During First RE Falling Edge			90		μA

#### **PROTECTION SPECIFICATIONS**

(V<sub>CC</sub> = +4.75V to +5.25V,  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at V<sub>CC</sub> = +5V and  $T_A = +25^{\circ}$ C.)

PARAMETER	SYMBOL		CONDITIONS	MIN	ТҮР	MAX	UNITS	
Overvoltage Protection		A, B R <sub>SOURCE</sub> = 0	, $R_L = 54\Omega$	±60			V	
			IEC 1000-4-2 Air-Gap Discharge		±2			
ESD Protection	Α, Β	А, В	IEC 1000-4-2 Contact Discharge		±8		kV	
			Human Body Model		±15		1	
SUPPLY CURRENT								
Normal Operation	lQ	No load, DI = DE = V <sub>CC</sub>	No load, DI = $V_{CC}$ or GND, $\overline{RE}$ = GND, DE = $V_{CC}$			10	mA	
Supply Current in Shutdown Mode	I <sub>SHDN</sub>	$DE = GND, \overline{RE} = V_{CC}$				10	μA	
Supply Current with Output Shorted with ±60V	ISHRT	$DE = GND, \overline{R}$	$DE = GND, \overline{RE} = GND, output in three-state$			±15	mA	

#### SWITCHING CHARACTERISTICS (DRIVER)

(V<sub>CC</sub> = +4.75V to +5.25V,  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at V<sub>CC</sub> = +5V and  $T_A = +25^{\circ}$ C.)

BABAMETER	0/11501					
PARAMETER	SYMBOL	CONDITIONS	MIN	ТҮР	MAX	UNITS
Driver Propagation Delay	t <sub>PLHA,</sub> t <sub>PLHB</sub>	Figure 3, $R_L = 27\Omega$ , $C_L = 50pF$		60	ns	
Driver Differential Propagation Delay	t <sub>DPLH</sub> , t <sub>DPHL</sub>	Figure 4, $R_L = 54\Omega$ , $C_L = 50pF$			60	ns
Driver Differential Output Transition Time	t <sub>LH</sub> , t <sub>HL</sub>	Figure 4, $R_L = 54\Omega$ , $C_L = 50pF$			25	ns
Driver Output Skew	t <sub>SKEWAB</sub> , t <sub>SKEWBA</sub>	$\begin{split} R_L &= 54\Omega, \ C_L = 50 \text{pF}, \\ t_{\text{SKEWAB}} &= lt_{\text{PLHA}} - t_{\text{PHLB}}l, \\ t_{\text{SKEWBA}} &= lt_{\text{PLHB}} - t_{\text{PHLA}}l \end{split}$			10	ns
Differential Driver Output Skew	<sup>t</sup> DSKEW	$R_L = 54\Omega$ , $C_L = 50pF$ , tDSKEW = ItDPLH - tDPHLI			10	ns
Maximum Data Rate	f <sub>MAX</sub>		10			Mbps
Driver Enable Time to Output High	tpdzh	Figure 5, $R_L$ = 500 $\Omega$ , $C_L$ = 50pF			1200	ns
Driver Disable Time from Output High	t <sub>PDHZ</sub>	Figure 5, $R_L = 500\Omega$ , $C_L = 50pF$			1200	ns
Driver Wake Time from Shutdown to Output High	<sup>t</sup> PDHS	Figure 5, $R_L = 500\Omega$ , $C_L = 50pF$			4.2	μs
Driver Enable Time to Output Low	t <sub>PDZL</sub>	Figure 6, $R_L = 500\Omega$ , $C_L = 50pF$			1200	ns
Driver Disable Time from Output Low	t <sub>PDLZ</sub>	Figure 6, $R_L = 500\Omega$ , $C_L = 50pF$			1200	ns
Driver Wake Time from Shutdown to Output Low	t <sub>PDLS</sub>	Figure 6, $R_L = 500\Omega$ , $C_L = 50pF$			4.2	μs
Time to Shutdown	tshdn	$R_{L} = 500\Omega, C_{L} = 50pF$			800	ns

#### SWITCHING CHARACTERISTICS (RECEIVER)

 $(V_{CC} = +4.75V \text{ to } +5.25V, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } V_{CC} = +5V \text{ and } T_A = +25^{\circ}C.)$ 

PARAMETER	SYMBOL	CONDITIONS	MIN	ТҮР	МАХ	UNITS
Receiver Propagation Delay	t <sub>RPLH</sub> , t <sub>RPHL</sub>	Figure 7, $C_L = 20pF$ , $V_{ID} = 2V$ , $V_{CM} = 0$			75	ns
Receiver Output Skew	<sup>t</sup> RSKEW	C <sub>L</sub> = 20pF, t <sub>RSKEW</sub> = lt <sub>RPLH</sub> - t <sub>RPHL</sub> l			15	ns
Receiver Enable Time to Output High	t <sub>RPZH</sub>	Figure 8, $R_L$ = 1k $\Omega$ , $C_L$ = 20pF			400	ns
Receiver Disable Time from Output High	t <sub>RPHZ</sub>	Figure 8, R <sub>L</sub> = 1k $\Omega$ , C <sub>L</sub> = 20pF			400	ns
Receiver Wake Time from Shutdown to Output High	t <sub>RPSH</sub>	Figure 8, $R_L = 1k\Omega$ , $C_L = 20pF$			4.2	μs
Receiver Enable Time to Output Low	t <sub>RPZL</sub>	Figure 8, $R_L = 1k\Omega$ , $C_L = 20pF$			400	ns
Receiver Disable Time from Output Low	t <sub>RPLZ</sub>	Figure 8, $R_L = 1k\Omega$ , $C_L = 20pF$			400	ns
Receiver Wake Time from Shutdown to Output Low	t <sub>RPSL</sub>	Figure 8, $R_L = 1k\Omega$ , $C_L = 20pF$			4.2	μs
Time to Shutdown					800	ns

**Note 2:**  $\Delta V_{OD}$  and  $\Delta V_{OC}$  are the changes in  $V_{OD}$  and  $V_{OC}$ , respectively, when the DI input changes state.

**Note 3:** The short-circuit output current applies to peak current just prior to foldback current limiting; the short-circuit foldback output current applies during current limiting to allow a recovery from bus contention.

#### **Typical Operating Characteristics**



**MAX3443E** 

M/X/W



#### \_Typical Operating Characteristics (continued)

(V<sub>CC</sub> = +5V,  $T_A$  = +25°C, unless otherwise noted.)











-60 -50 -40 -30 -20 -10 0 10 20 30 40 50 60

A, B VOLTAGE (V)

#### **Test Circuits and Waveforms**



Figure 1. Driver VOD and VCC



Figure 2. Receiver VOH and VOL



Figure 3. Driver Propagation Times



Figure 4. Driver Differential Output Delay and Transition Times

**MAX3443E** 

**Test Circuits and Waveforms (continued)** 





Figure 5. Driver Enable and Disable Times



Figure 6. Driver Enable and Disable Times



Figure 7. Receiver Propagation Delay



#### \_Test Circuits and Waveforms (continued)

Figure 8. Receiver Enable and Disable Times

**Note 4:** The input pulse is supplied by a generator with the following characteristics: f = 5MHz, 50% duty cycle;  $tr \le 6ns$ ;  $Z_0 = 50\Omega$ . **Note 5:**  $C_L$  includes probe and stray capacitance.

#### **Pin Description**

PIN	NAME	FUNCTION
1	RO	Receiver Output. If $\overline{RE}$ = low and (A–B) ≥ -50mV, RO = high; if (A–B) ≤ -200mV, RO = low.
2	RE	Receiver Output Enable. Pull $\overline{RE}$ low to enable RO.
3	DE	Driver Output Enable. Force DE high to enable driver. Pull $\overline{\text{DE}}$ low to three-state the driver output. Drive $\overline{\text{RE}}$ high and pull DE low to enter low-power shutdown mode.
4	DI	Driver Input. A logic low on DI forces the noninverting output low and the inverting output high. A logic high on DI forces the noninverting output high and the inverting output low.
5	GND	Ground
6	А	Noninverting Receiver Input/Driver Output with Integrated ±15kV ESD Protection
7	В	Inverting Receiver Input/Driver Output with Integrated ±15kV ESD Protection
8	V <sub>CC</sub>	Positive Supply, $V_{CC} = +4.75V$ to $+5.25V$

#### 

**MAX3443E** 

#### \_Function Tables

MAX3443E (RS-485/RS-422)

TRANSMITTING							
INPUTS			OUTPUTS				
RE	DE	DI	A B				
0	0	Х	High-Z	High-Z			
0	1	0	0	1			
0	1	1	1	0			
1	0	Х	Shutdown	Shutdown			
1	1	0	0	1			
1	1	1	1	0			

X = Don't care.

#### **Detailed Description**

#### Driver

The driver accepts a single-ended, logic-level input (DI) and transfers it to a differential, RS-485/RS-422 level output (A and B). Driving DE high enables the driver, while pulling DE low places the driver outputs (A and B) into a high-impedance state (see the transmitting function table).

Receiver

The receiver accepts a differential, RS-485/RS-422 level input (A and B), and transfers it to a single-ended, logic-level output (RO). Pulling  $\overline{RE}$  low enables the receiver, while driving  $\overline{RE}$  high places the receiver inputs (A and B) into a high-impedance state (see the receiving function table).

#### **Low-Power Shutdown**

Force DE low and  $\overline{\text{RE}}$  high to shut down the MAX3443E. A time delay of 50ns prevents the device from accidentally entering shutdown due to logic skews when switching between transmit and receive modes. Holding DE low and  $\overline{\text{RE}}$  high for at least 800ns guarantees that the MAX3443E enters shutdown. In shutdown, the device consumes a maximum of 10µA supply current.

#### ±60V Fault Protection

The driver outputs/receiver inputs of RS-485 devices in industrial network applications often experience voltage faults resulting from shorts to the power bus that exceed the -7V to +12V range specified in the EIA/TIA-485 standard. In these applications, ordinary RS-485 devices (typical absolute maximum -8V to +12.5V) require costly external protection devices. To reduce system complexity and eliminate this need for external protection, the driver outputs/receiver inputs of the MAX3443E withstand voltage faults up to  $\pm$ 60V with

#### MAX3443E (RS-485/RS-422)

RECEIVING						
	INPUTS		OUTPUT			
RE	RE DE (A-B)					
0	Х	≥0.2V	1			
0	Х	≤-0.2V	0			
0	Х	Open/Shorted	1			
1	1	Х	High-Z			
1	0	Х	Shutdown			

X = Don't care.

respect to ground without damage. Protection is guaranteed regardless of whether the device is active, shut down, or without power.

#### True Fail-Safe

The MAX3443E uses a -50mV to -200mV differential input threshold to ensure true fail-safe receiver inputs. This threshold guarantees the receiver output is a logic high for shorted, open, or idle data lines. The -50mV to -200mV threshold complies with the  $\pm$ 200mV threshold specified in the EIA/TIA-485 standard.

#### ±15kV ESD Protection

As with all Maxim devices, ESD-protection structures are incorporated on all pins to protect against ESD encountered during handling and assembly. The MAX3443E receiver inputs/driver outputs (A, B) have extra protection against static electricity found in normal operation. Maxim's engineers developed state-ofthe-art structures to protect these pins against ±15kV ESD without damage. After an ESD event, the MAX3443E continues working without latchup.

ESD protection can be tested in several ways. The receiver inputs are characterized for protection to the following:

- ±15kV using the Human Body Model
- ±8kV using the Contact Discharge method specified in IEC 1000-4-2 (formerly IEC 801-2)
- ±15kV using the Air-Gap Discharge method specified in IEC 1000-4-2 (formerly IEC 801-2)

#### ESD Test Conditions

ESD performance depends on a number of conditions. Contact Maxim for a reliability report that documents test setup, methodology, and results.



**MAX3443E** 



Figure 9a. Human Body ESD Test Model

#### Human Body Model

Figure 9a shows the Human Body Model, and Figure 9b shows the current waveform it generates when discharged into a low impedance. This model consists of a 100pF capacitor charged to the ESD voltage of interest, which is then discharged into the device through a  $1.5 k\Omega$  resistor.

#### IEC 1000-4-2

Since January 1996, all equipment manufactured and/or sold in the European community has been required to meet the stringent IEC 1000-4-2 specification. The IEC 1000-4-2 standard covers ESD testing and performance of finished equipment; it does not specifically refer to integrated circuits. The MAX3443E helps you design equipment that meets Level 4 (the highest level) of IEC 1000-4-2, without additional ESD-protection components.

The main difference between tests done using the Human Body Model and IEC 1000-4-2 is higher peak current in IEC 1000-4-2. Because series resistance is lower in the IEC 1000-4-2 ESD test model (Figure 10a), the ESD withstand voltage measured to this standard is generally lower than that measured using the Human



Figure 10a. IEC 1000-4-2 ESD Test Model



**MAX3443E** 

Figure 9b. Human Body Model Current Waveform

Body Model. Figure 10b shows the current waveform for the  $\pm$ 8kV IEC 1000-4-2 Level 4 ESD Contact Discharge test. The Air-Gap test involves approaching the device with a charge probe. The Contact Discharge method connects the probe to the device before the probe is energized.

#### Machine Model

The Machine Model for ESD testing uses a 200pF storage capacitor and zero-discharge resistance. It mimics the stress caused by handling during manufacturing and assembly. All pins (not just RS-485 inputs) require this protection during manufacturing. Therefore, the Machine Model is less relevant to the I/O ports than are the Human Body Model and IEC 1000-4-2.

#### **Driver Output Protection**

Two mechanisms prevent excessive output current and power dissipation caused by faults, or bus contention. The first, a foldback current limit on the driver output stage, provides immediate protection against short circuits over the whole common-mode voltage range. The second, a thermal shutdown circuit, forces the driver



Figure 10b. IEC 1000-4-2 ESD Generator Current Waveform

outputs into a high-impedance state if the die temperature exceeds +160°C. Normal operation resumes when the die temperature cools to +140°C, resulting in a pulsed output during continuous short-circuit conditions.

#### Hot-Swap Capability Hot-Swap Inputs

Inserting circuit boards into a hot, or powered, backplane may cause voltage transients on DE, RE, and receiver inputs A and B that can lead to data errors. For example, upon initial circuit board insertion, the processor undergoes a power-up sequence. During this period, the high-impedance state of the output drivers makes them unable to drive the MAX3443E enable inputs (DE, RE) to a defined logic level. Meanwhile, leakage currents up to 10µA from the high-impedance output, or capacitively coupled noise from V<sub>CC</sub> or GND, could cause an input to drift to an incorrect logic state. To prevent such a condition from occurring, the MAX3443E features hot-swap input circuitry on DE and RE to safeguard against unwanted driver activation during hot-swap situations. When VCC rises, an internal pulldown (or pullup for RE) circuit holds DE low for at least 10µs, and until the current into DE exceeds 200µA. After the initial power-up sequence, the pulldown circuit becomes transparent, resetting the hotswap tolerable input.

#### Hot-Swap Input Circuitry

At the driver enable input (DE), there are two NMOS devices, M1 and M2 (Figure 11). When V<sub>CC</sub> ramps from zero, an internal 15µs timer turns on M2 and sets the SR latch, which also turns on M1. Transistors M2, a 2mA current sink, and M1, a 100µA current sink, pull DE to GND through a 5.6k $\Omega$  resistor. M2 pulls DE to the disabled state against an external parasitic capacitance up to 100pF that may drive DE high. After 15µs, the timer deactivates M2 while M1 remains on, holding DE low against three-state leakage currents that may drive DE high. M1 remains on until an external current source overcomes the required input current. At this time, the SR latch resets M1 and turns off. When M1 turns off, DE reverts to a standard, high-impedance CMOS input. Whenever VCC drops below +1V, the input is reset.

A complimentary circuit for  $\overline{\text{RE}}$  utilizes two PMOS devices to pull  $\overline{\text{RE}}$  to V<sub>CC</sub>.



Figure 11. Simplified Structure of the Driver Enable Pin (DE)

#### **Applications Information**

#### **128 Transceivers on the Bus**

The MAX3443E 1/4-unit-load receiver input impedance (48k $\Omega$ ) allows up to 128 transceivers connected in parallel on one communication line. Connect any combination of these devices, and/or other RS-485 devices, for a maximum of 32 unit loads to the line.

#### **RS-485** Applications

The MAX3443E transceiver provides bidirectional data communications on multipoint bus transmission lines. Figure 12 shows a typical network applications circuit. The RS-485 standard covers line lengths up to 4000ft. To minimize reflections, and reduce data errors, terminate the signal line at both ends in its characteristic impedance, and keep stub lengths off the main line as short as possible.

#### **J1708** Applications

///XI//

To configure the MAX3443E in a J1708 application, connect DI and  $\overline{RE}$  to GND. Connect the signal to be transmitted to DE through an inverter. At each transceiver, terminate the bus with the load circuit (shown in Figure 13). When all transceivers are idle in this configuration, all receivers output a logic high because of the pullup resistor on A and pulldown resistor on B. Since  $\overline{RE}$  is connected to GND, all transmitters on the bus listen at



Figure 12. MAX3443E Typical RS-485 Network

all times. Incoming data on DE enables the driver, which pulls the line low and causes all receivers to output a logic low.



Figure 13. J1708 Application Circuit

Chip Information

**MAX3443E** 

TRANSISTOR COUNT: 310 PROCESS: BICMOS

#### \_Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to **www.maxim-ic.com/packages**.)



M/XI/M

#### **Package Information (continued)**

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