

DOUBLE CHANNEL HIGH SIDE DRIVER

Table 1. General Features

TYPE	R _{D(on)}	I _{lim}	V _{CC}
VND600PEP-E	30mΩ (*)	25A	36V

(*) Per each channel

- DC SHORT CIRCUIT CURRENT: 25A
- CMOS COMPATIBLE INPUTS
- PROPORTIONAL LOAD CURRENT SENSE
- UNDervoltage AND OVERVOLTAGE SHUT-DOWN
- OVERVOLTAGE CLAMP
- THERMAL SHUT-DOWN
- CURRENT LIMITATION
- VERY LOW STAND-BY POWER DISSIPATION
- PROTECTION AGAINST:
 - LOSS OF GROUND AND LOSS OF V_{CC}
- REVERSE BATTERY PROTECTION (**)
- IN COMPLIANCE WITH THE 2002/95/EC EUROPEAN DIRECTIVE

DESCRIPTION

The VND600PEP-E is a monolithic device made using STMicroelectronics VIPower M0-3 technology. It is intended for driving resistive or inductive loads with one side connected to ground. Active V_{CC} pin voltage clamp protects the device against low energy spikes (see ISO7637 transient compatibility table).

Figure 1. Package

This device has two channels in high side configuration; each channel has an analog sense output on which the sensing current is proportional (according to a known ratio) to the corresponding load current. Built-in thermal shut-down and outputs current limitation protect the chip from over temperature and short circuit. Device turns off in case of ground pin disconnection.

Table 2. Order Codes

Package	Tube	Tape and Reel
PowerSSO-24	VND600PEP-E	VND600PEPTR-E

Note: (**) See application schematic at page 9

VND600PEP-E

Figure 2. Block Diagram

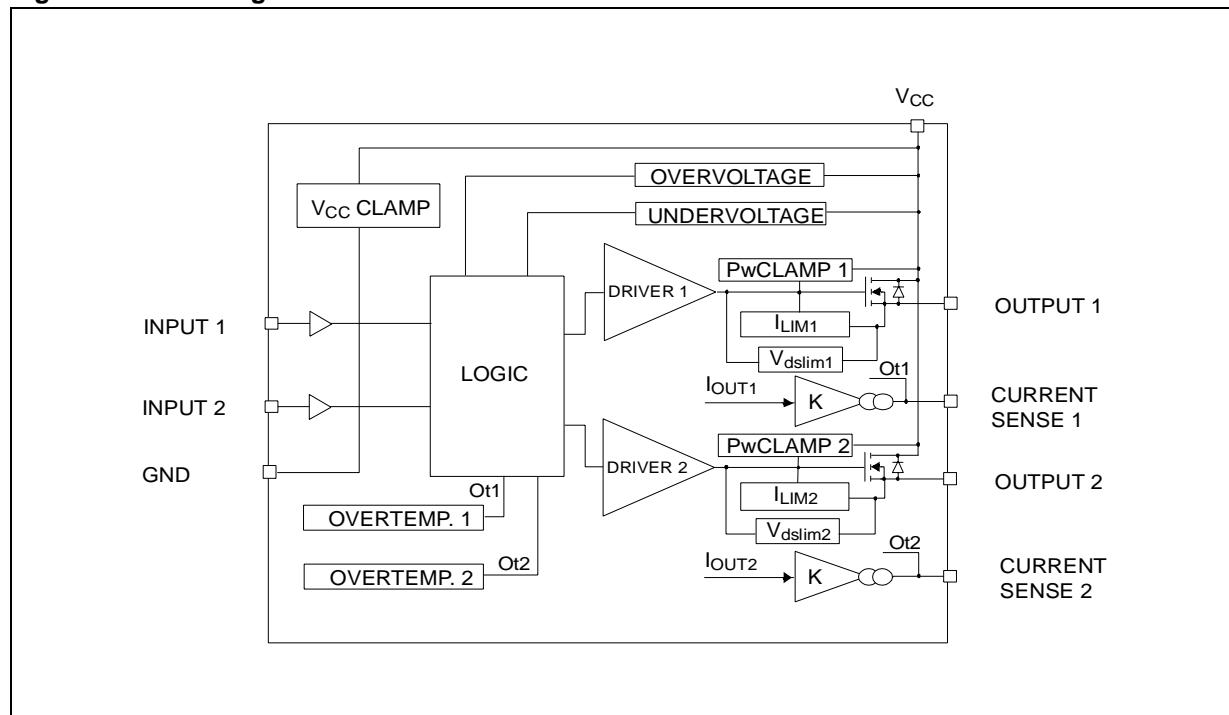
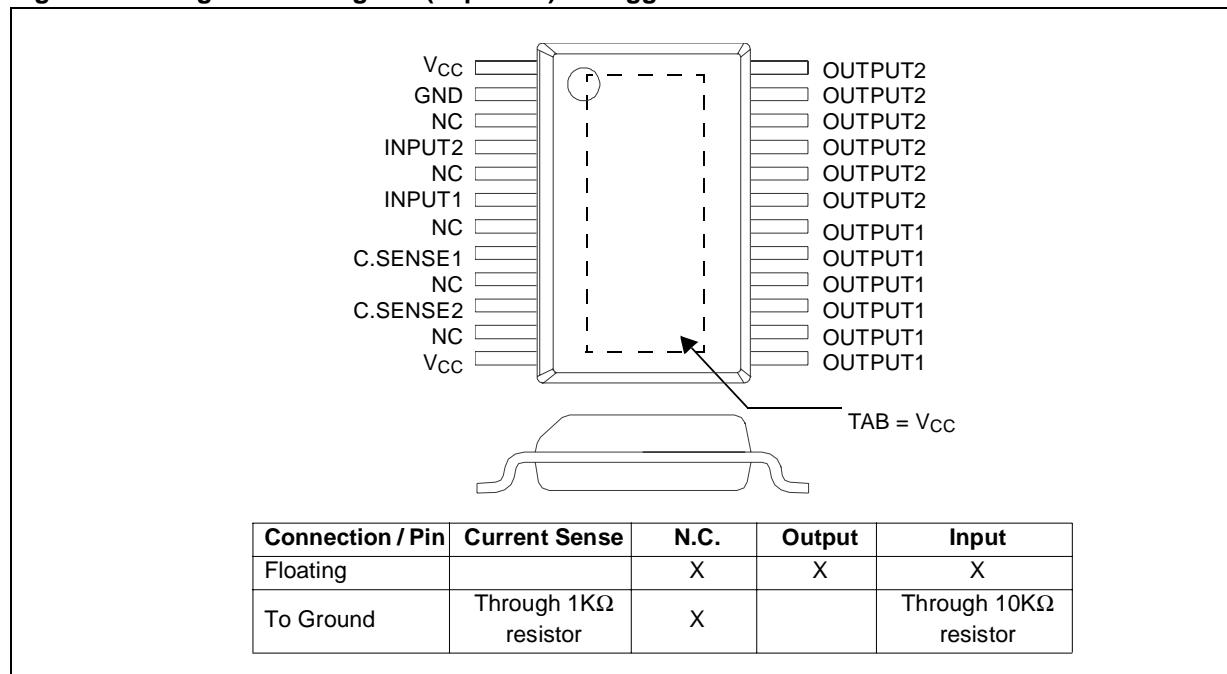
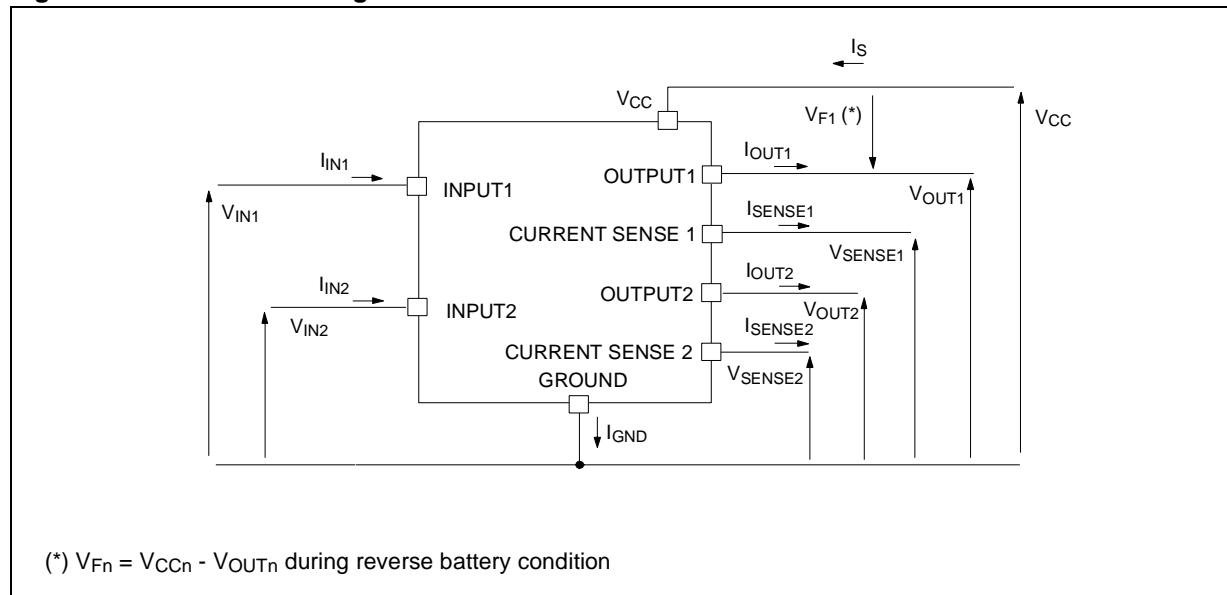


Table 3. Absolute Maximum Ratings

Symbol	Parameter	Value	Unit
V_{CC}	DC supply voltage	41	V
$-V_{CC}$	Reverse supply voltage	-0.3	V
$-I_{GND}$	DC reverse ground pin current	-200	mA
I_{OUT}	Output current	Internally limited	A
I_R	Reverse output current	-21	A
I_{IN}	Input current	± 10	mA
V_{CSENSE}	Current sense maximum voltage	-3 +15	V
V_{ESD}	Electrostatic Discharge (Human Body Model: $R=1.5\text{ k}\Omega$; $C=100\text{ pF}$)		
	- INPUT	4000	V
	- CURRENT SENSE	2000	V
	- OUTPUT	5000	V
	- V_{CC}	5000	V
E_{MAX}	Maximum Switching Energy ($L=0.13\text{ mH}$; $R_L=0\Omega$; $V_{bat}=13.5\text{ V}$; $T_{jstart}=150^\circ\text{C}$; $I_L=40\text{ A}$)	146	mJ
P_{tot}	Power dissipation at $T_c=25^\circ\text{C}$	96	W
T_j	Junction operating temperature	Internally limited	$^\circ\text{C}$
T_c	Case operating temperature	-40 to 150	$^\circ\text{C}$
T_{STG}	Storage temperature	-55 to 150	$^\circ\text{C}$

Figure 3. Configuration Diagram (Top View) & Suggested Connections for Unused and N.C. Pins**Figure 4. Current and Voltage Conventions****Table 4. Thermal Data**

Symbol	Parameter	Value	Unit
$R_{thj-case}^{(1)}$	Thermal resistance junction-case (MAX)	1.8	°C/W
$R_{thj-case}^{(2)}$	Thermal resistance junction-case (MAX)	1.3	°C/W
$R_{thj-amb}$	Thermal resistance junction-ambient (MAX)	54 (*) 39 (**)	°C/W

Note: (*) When mounted on a standard single-sided FR-4 board with 0.5cm^2 of Cu (at least $35\mu\text{m}$ thick).

Note: (**) When mounted on a standard single-sided FR-4 board with 8cm^2 of Cu (at least $35\mu\text{m}$ thick).

Note: (1) one channel ON - (2) two channels ON

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ELECTRICAL CHARACTERISTICS (8V<V_{CC}<36V; -40°C<T_j<150°C unless otherwise specified)
(Per each channel)

Table 5. Power

Symbol	Parameter	Test Conditions	Min.	Typ.	Max.	Unit
V _{CC} (**)	Operating supply voltage		5.5	13	36	V
V _{USD} (**)	Undervoltage shutdown		3	4	5.5	V
V _{Ov} (**)	Overvoltage shutdown		36			V
R _{ON}	On state resistance	I _{OUT} =5A; T _j =25°C I _{OUT} =5A; T _j =150°C I _{OUT} =3A; V _{CC} =6V			30 60 100	mΩ mΩ mΩ
V _{clamp}	Clamp Voltage	I _{CC} =20mA (see note 1)	41	48	55	V
I _S (**)	Supply current	Off State; V _{CC} =13V; V _{IN} =V _{OUT} =0V Off State; V _{CC} =13V; V _{IN} =V _{OUT} =0V; T _j =25°C On state; V _{IN} =5V; V _{CC} =13V; I _{OUT} =0A; R _{SENSE} =3.9kΩ		12 12	40 25 6	μA μA mA
I _{L(off1)}	Off State Output Current	V _{IN} =V _{OUT} =V _{SENSE} =0V	0		50	μA
I _{L(off3)}	Off State Output Current	V _{IN} =V _{OUT} =V _{SENSE} =0V; V _{CC} =13V; T _j =125°C			5	μA
I _{L(off4)}	Off State Output Current	V _{IN} =V _{OUT} =V _{SENSE} =0V; V _{CC} =13V; T _j =25°C			3	μA

Note: 1. V_{clamp} and V_{Ov} are correlated. Typical difference is 5V.

Note: (**) Per device.

Table 6. Switching (V_{CC} =13V)

Symbol	Parameter	Test Conditions	Min.	Typ.	Max.	Unit
t _{d(on)}	Turn-on delay time	R _L =2.6Ω (see Figure 5)		30		μs
t _{d(off)}	Turn-on delay time	R _L =2.6Ω (see Figure 5)		30		μs
(dV _{OUT} /dt) _{on}	Turn-on voltage slope	R _L =2.6Ω (see Figure 5)		See relative diagram		V/μs
(dV _{OUT} /dt) _{off}	Turn-off voltage slope	R _L =2.6Ω (see Figure 5)		See relative diagram		V/μs

Table 7. V_{CC} - Output Diode

Symbol	Parameter	Test Conditions	Min	Typ	Max	Unit
V _F	Forward on Voltage	-I _{OUT} =2.6A; T _j =150°C			0.6	V

ELECTRICAL CHARACTERISTICS (continued)**Table 8. Logic Input** (Channels 1,2)

Symbol	Parameter	Test Conditions	Min.	Typ.	Max.	Unit
V_{IL}	Input low level voltage				1.25	V
I_{IL}	Low level input current	$V_{IN}=1.25V$	20	65		μA
V_{IH}	Input high level voltage		3.25			V
I_{IH}	High level input current	$V_{IN}=3.25V$			10	μA
$V_{I(hyst)}$	Input hysteresis voltage		0.5			V
V_{ICL}	Input clamp voltage	$I_{IN}=1mA$ $I_{IN}=-1mA$	6	6.8 -0.7	8	V V

Table 9. Current Sense ($9V \leq V_{CC} \leq 16V$) (see Figure 8)

Symbol	Parameter	Test Conditions	Min	Typ	Max	Unit
K_1	I_{OUT}/I_{SENSE}	$I_{OUT1} \text{ or } I_{OUT2}=0.5A; V_{SENSE}=0.5V;$ other channels open; $T_j = -40^\circ C \dots 150^\circ C$	3300	4400	6000	
dK_1/K_1	Current Sense Ratio Drift	$I_{OUT1} \text{ or } I_{OUT2}=0.5A; V_{SENSE}=0.5V;$ other channels open; $T_j = -40^\circ C \dots 150^\circ C$	-10		+10	%
K_2	I_{OUT}/I_{SENSE}	$I_{OUT1} \text{ or } I_{OUT2}=5A; V_{SENSE}=4V;$ other channels open; $T_j = -40^\circ C \dots 150^\circ C$	3800 3950	4400 4400	5400 5200	
dK_2/K_2	Current Sense Ratio Drift	$I_{OUT1} \text{ or } I_{OUT2}=5A; V_{SENSE}=4V;$ other channels open; $T_j = -40^\circ C \dots 150^\circ C$	-6		+6	%
K_3	I_{OUT}/I_{SENSE}	$I_{OUT1} \text{ or } I_{OUT2}=15A; V_{SENSE}=4V;$ other channels open; $T_j = -40^\circ C \dots 150^\circ C$	3800 3950	4400 4400	4900 4700	
dK_3/K_3	Current Sense Ratio Drift	$I_{OUT1} \text{ or } I_{OUT2}=15A; V_{SENSE}=4V;$ other channels open; $T_j = -40^\circ C \dots 150^\circ C$	-6		+6	%
$V_{SENSE1,2}$	Max analog sense output voltage	$V_{CC}=5.5V; I_{OUT1,2}=2.5A;$ $R_{SENSE}=10k\Omega$ $V_{CC}>8V, I_{OUT1,2}=5A; R_{SENSE}=10k\Omega$	2 4			V V
V_{SENSEH}	Analog sense output voltage in overtemperature condition	$V_{CC}=13V; R_{SENSE}=3.9k\Omega$		5.5		V
$R_{VSENSEH}$	Analog sense output impedance in overtemperature condition	$V_{CC}=13V; T_j > T_{TSD}; \text{ All Channels Open}$		400		Ω
t_{DSENSE}	Current sense delay response	to 90% I_{SENSE} (see note 2)			500	μs

Note: 2. Current sense signal delay after positive input slope

ELECTRICAL CHARACTERISTICS (continued)
Table 10. Protections (See note 3)

Symbol	Parameter	Test Conditions	Min.	Typ.	Max.	Unit
I_{lim}	DC short circuit current	$V_{CC}=13V$ $5.5V < V_{CC} < 36V$	25	40	70	A
T_{TSD}	Thermal shut-down temperature		150	175	200	°C
T_R	Thermal reset temperature		135			°C
T_{HYST}	Thermal hysteresis		7	15		°C
V_{demag}	Turn-off output voltage clamp	$I_{OUT}=2A$; $V_{IN}=0V$; $L=6mH$	$V_{CC}-41$	$V_{CC}-48$	$V_{CC}-55$	V
V_{ON}	Output voltage drop limitation	$I_{OUT}=0.5A$; $T_j = -40°C...+150°C$		50		mV

Note: 3. To ensure long term reliability under heavy overload or short circuit conditions, protection and related diagnostic signals must be used together with a proper software strategy. If the device is subjected to abnormal conditions, this software must limit the duration and number of activation cycles.

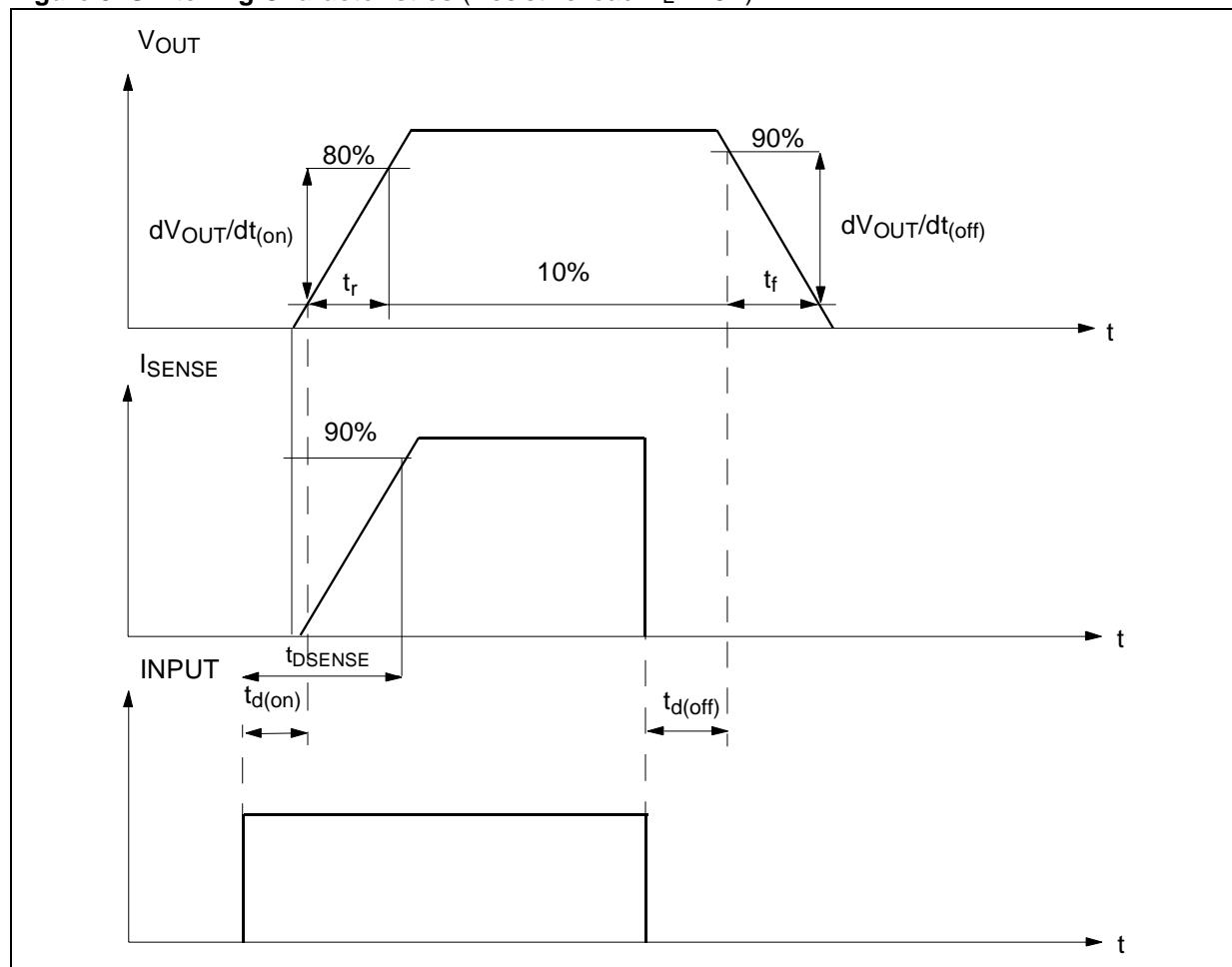
Figure 5. Switching Characteristics (Resistive load $R_L=2.6\Omega$)


Table 11. Truth Table (per channel)

CONDITIONS	INPUT	OUTPUT	SENSE
Normal operation	L	L	0
	H	H	Nominal
Overtemperature	L	L	0
	H	L	V _{SENSEH}
Undervoltage	L	L	0
	H	L	0
Overvoltage	L	L	0
	H	L	0
Short circuit to GND	L	L	0
	H	L	(T _j <T _{TSD}) 0
	H	L	(T _j >T _{TSD}) V _{SENSEH}
Short circuit to V _{CC}	L	H	0
	H	H	< Nominal
Negative output voltage clamp	L	L	0

Table 12. Electrical Transient Requirements

ISO T/R 7637/1 Test Pulse	TEST LEVELS				
	I	II	III	IV	Delays and Impedance
1	-25 V	-50 V	-75 V	-100 V	2 ms 10 Ω
2	+25 V	+50 V	+75 V	+100 V	0.2 ms 10 Ω
3a	-25 V	-50 V	-100 V	-150 V	0.1 μs 50 Ω
3b	+25 V	+50 V	+75 V	+100 V	0.1 μs 50 Ω
4	-4 V	-5 V	-6 V	-7 V	100 ms, 0.01 Ω
5	+26.5 V	+46.5 V	+66.5 V	+86.5 V	400 ms, 2 Ω

ISO T/R 7637/1 Test Pulse	TEST LEVELs RESULTS			
	I	II	III	IV
1	C	C	C	C
2	C	C	C	C
3a	C	C	C	C
3b	C	C	C	C
4	C	C	C	C
5	C	E	E	E

CLASS	CONTENTS
C	All functions of the device are performed as designed after exposure to disturbance.
E	One or more functions of the device is not performed as designed after exposure to disturbance and cannot be returned to proper operation without replacing the device.

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Figure 6. Waveforms

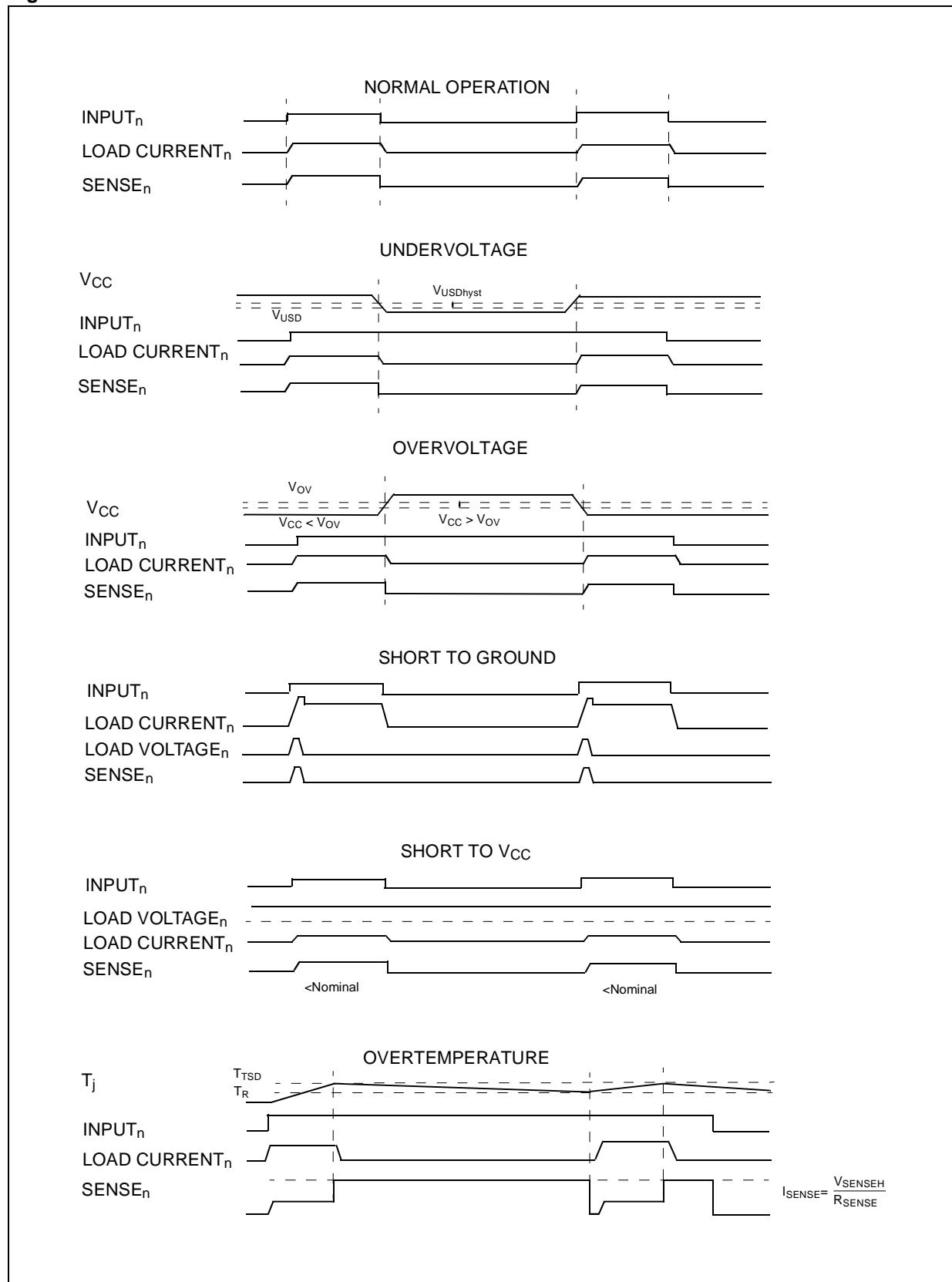
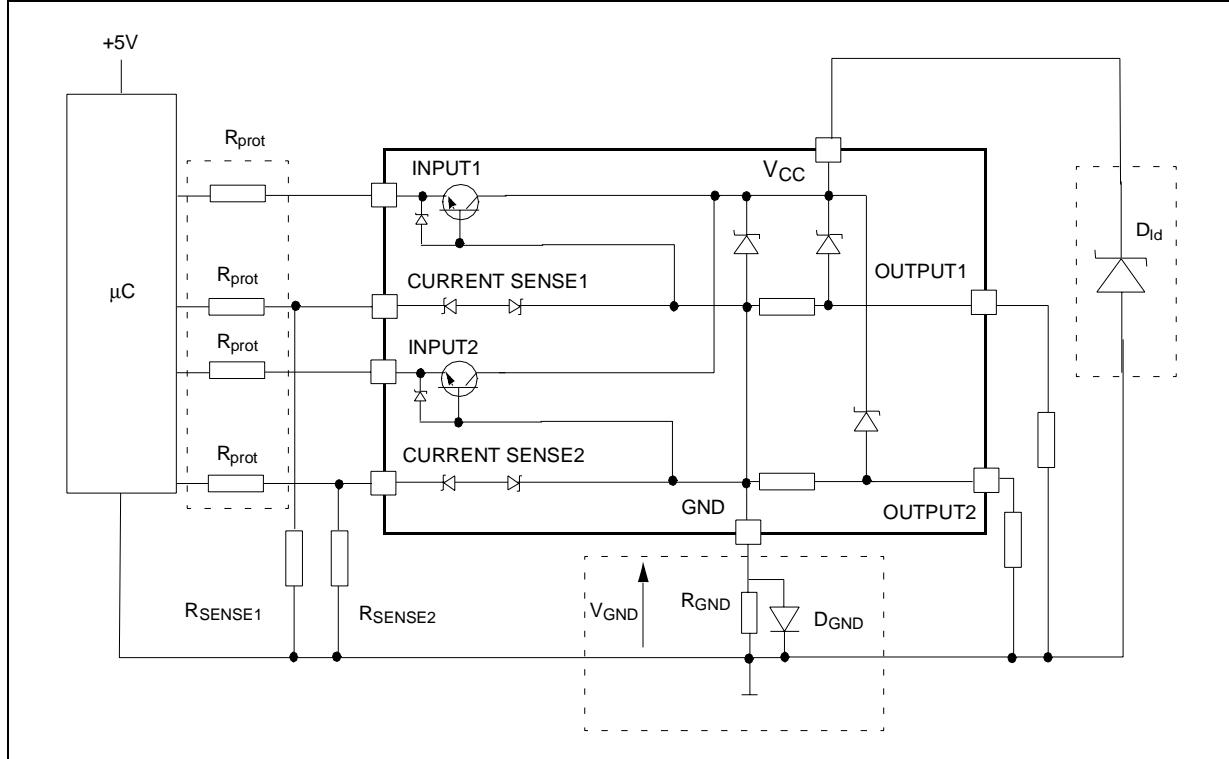


Figure 7. Application Schematic

GND PROTECTION NETWORK AGAINST REVERSE BATTERY

Solution 1: Resistor in the ground line (R_{GND} only). This can be used with any type of load.

The following is an indication on how to dimension the R_{GND} resistor.

- 1) $R_{GND} \leq 600\text{mV} / (I_{S(on)\max})$.
- 2) $R_{GND} \geq (-V_{CC}) / (-I_{GND})$

where $-I_{GND}$ is the DC reverse ground pin current and can be found in the absolute maximum rating section of the device's datasheet.

Power Dissipation in R_{GND} (when $V_{CC} < 0$: during reverse battery situations) is:

$$P_D = (-V_{CC})^2 / R_{GND}$$

This resistor can be shared amongst several different HSD. Please note that the value of this resistor should be calculated with formula (1) where $I_{S(on)\max}$ becomes the sum of the maximum on-state currents of the different devices.

Please note that if the microprocessor ground is not common with the device ground then the R_{GND} will produce a shift ($I_{S(on)\max} * R_{GND}$) in the input thresholds and the status output values. This shift will vary depending on how many devices are ON in the case of several high side drivers sharing the same R_{GND}.

If the calculated power dissipation leads to a large resistor or several devices have to share the same resistor then the ST suggests to utilize Solution 2 (see below).

Solution 2: A diode (D_{GND}) in the ground line.

A resistor (R_{GND}=1kΩ) should be inserted in parallel to D_{GND} if the device will be driving an inductive load.

This small signal diode can be safely shared amongst several different HSD. Also in this case, the presence of the ground network will produce a shift ($\approx 600\text{mV}$) in the input threshold and the status output values if the microprocessor ground is not common with the device ground. This shift will not vary if more than one HSD shares the same diode/resistor network.

Series resistor in INPUT line is also required to prevent that, during battery voltage transient, the current exceeds the Absolute Maximum Rating.

Safest configuration for unused INPUT pin is to leave it unconnected, while unused SENSE pin has to be connected to Ground pin.

LOAD DUMP PROTECTION

D_{Id} is necessary (Voltage Transient Suppressor) if the load dump peak voltage exceeds V_{CC} max DC rating. The same applies if the device will be subject to transients on the V_{CC} line that are greater than the ones shown in the ISO T/R 7637/1 table.

μC I/Os PROTECTION:

If a ground protection network is used and negative transients are present on the V_{CC} line, the control pins will be pulled negative. ST suggests to insert a resistor (R_{prot}) in line to prevent the μC I/Os pins to latch-up.

The value of these resistors is a compromise between the leakage current of μC and the current required by the HSD I/Os (Input levels compatibility) with the latch-up limit of μC I/Os.

$$-V_{CCpeak}/I_{latchup} \leq R_{prot} \leq (V_{OH\mu C} - V_{IH} - V_{GND}) / I_{IHmax}$$

Calculation example:

For $V_{CCpeak} = -100\text{V}$ and $I_{latchup} \geq 20\text{mA}$; $V_{OH\mu C} \geq 4.5\text{V}$
 $5\text{k}\Omega \leq R_{prot} \leq 65\text{k}\Omega$.

Recommended R_{prot} value is 10kΩ.

Figure 8. I_{OUT}/I_{SENSE} versus I_{OUT}

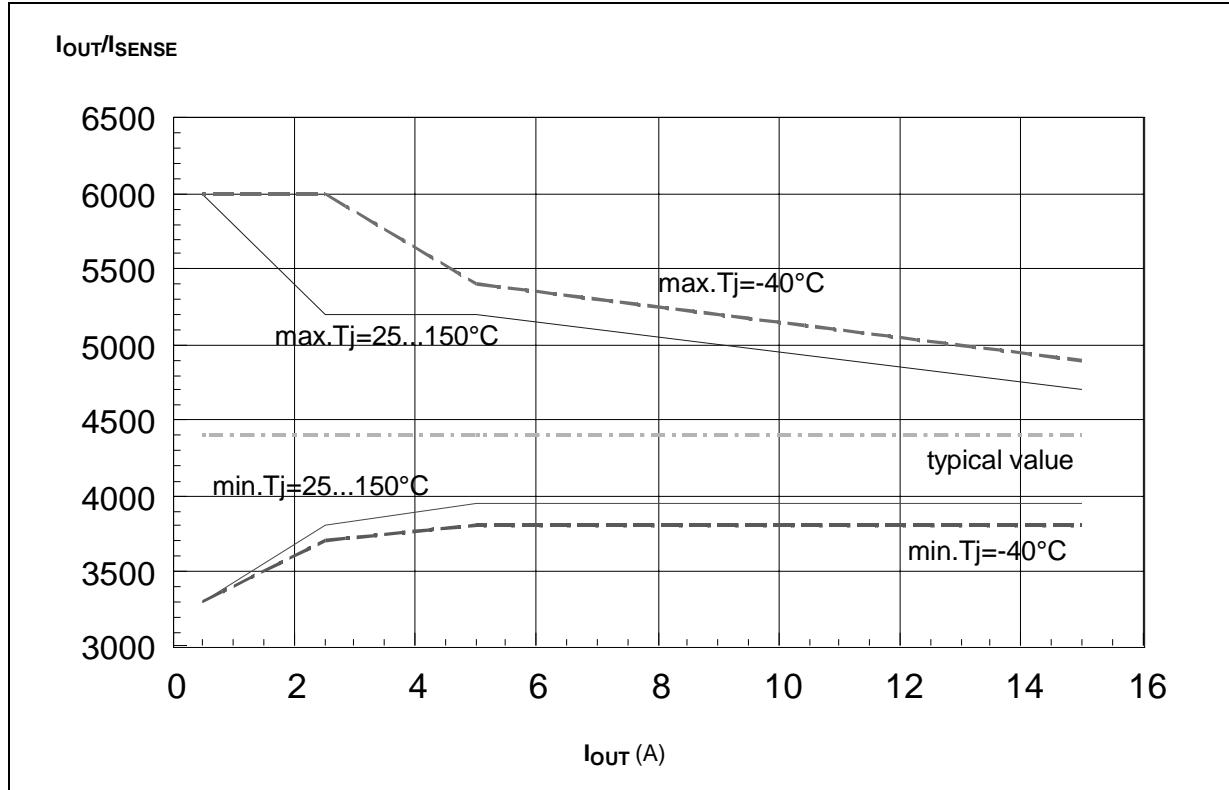


Figure 9. Off State Output Current

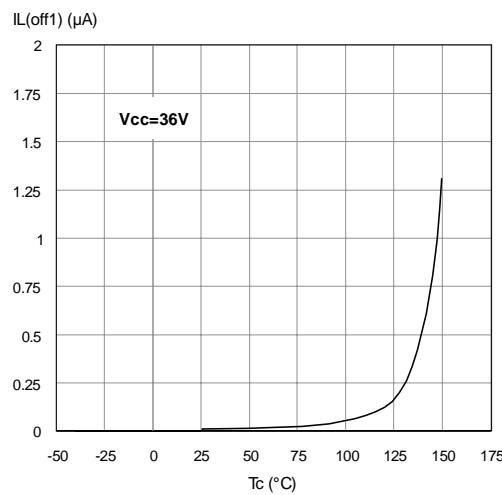


Figure 10. High Level Input Current

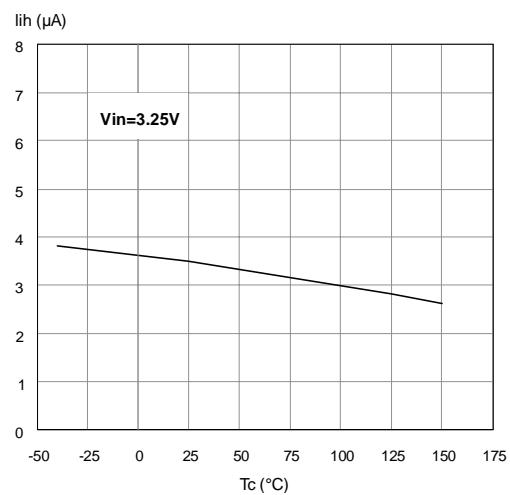


Figure 11. Input Clamp Voltage

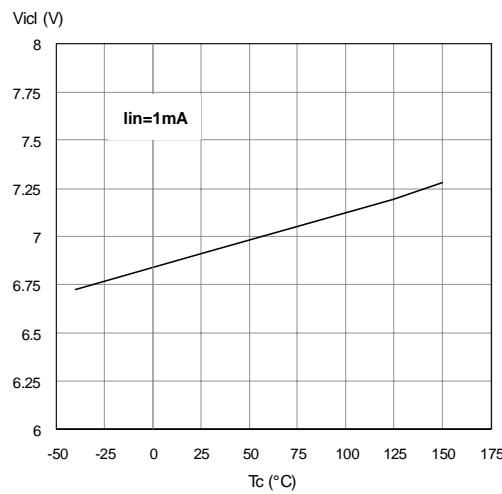


Figure 13. Input High Level

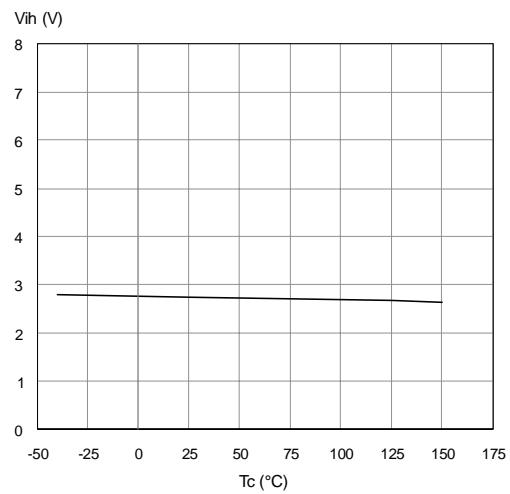


Figure 12. Input Low Level

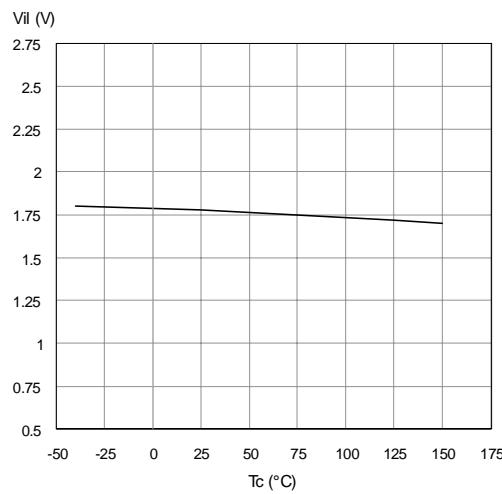
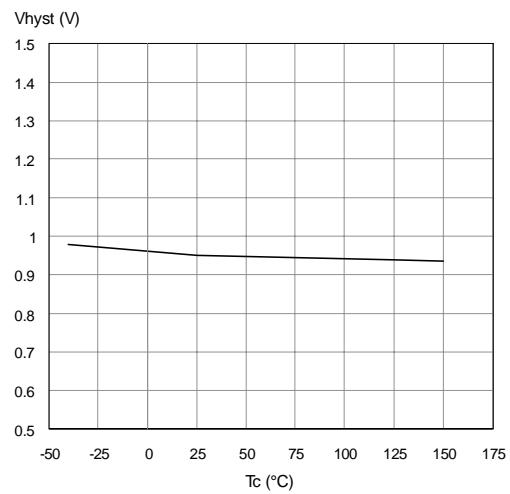


Figure 14. Input Hysteresis Voltage



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Figure 15. Overvoltage Shutdown

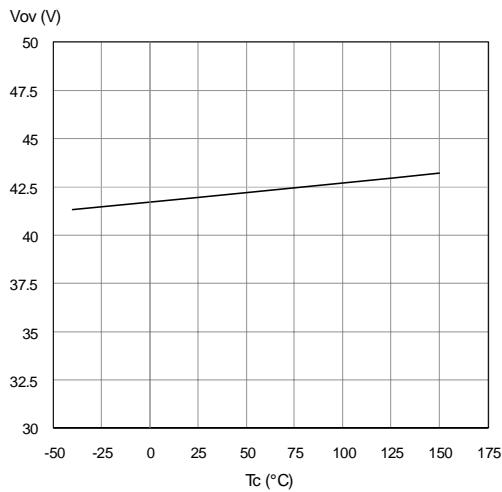


Figure 16. Turn-on Voltage Slope

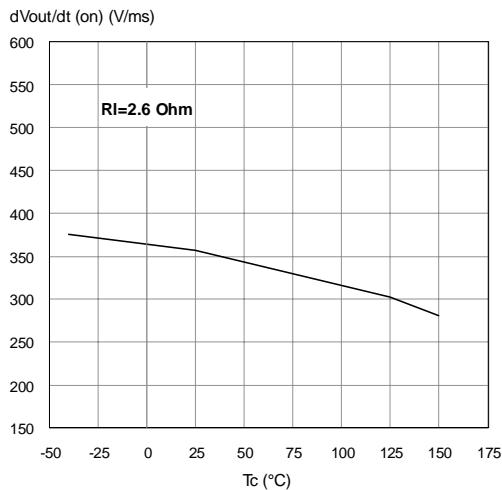


Figure 17. On State Resistance Vs T_{case}

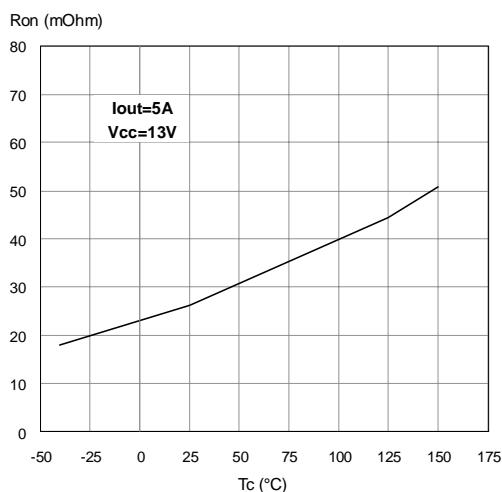


Figure 18. I_{LIM} Vs T_{case}

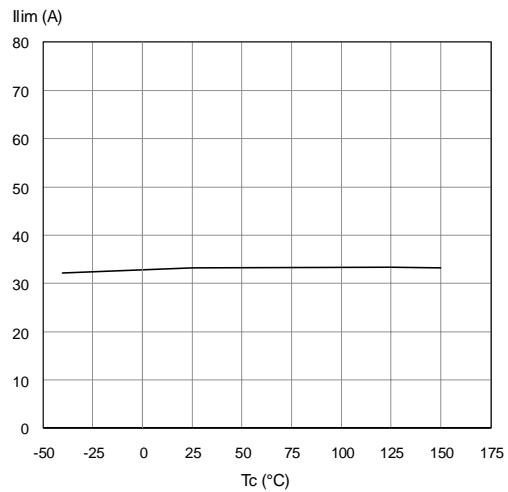


Figure 19. Turn-off Voltage Slope

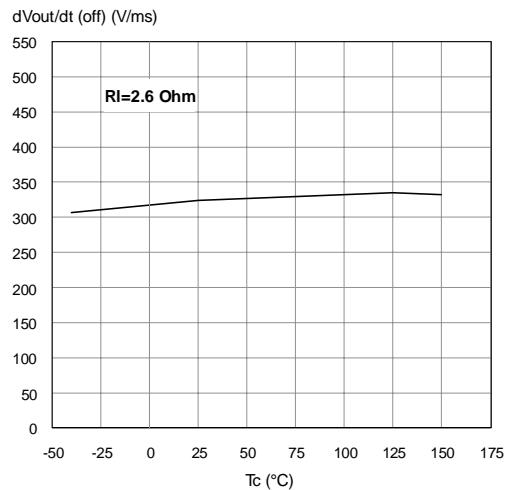
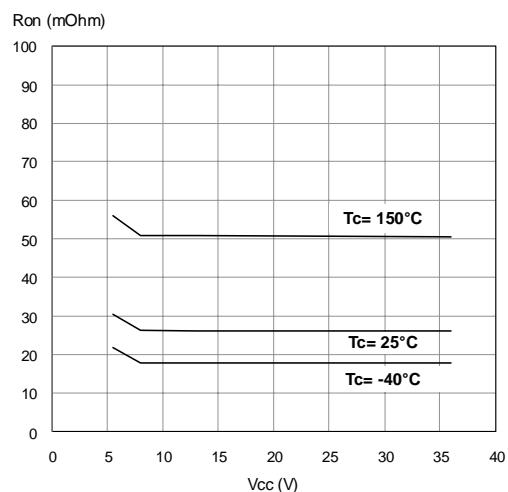


Figure 20. On State Resistance Vs V_{cc}



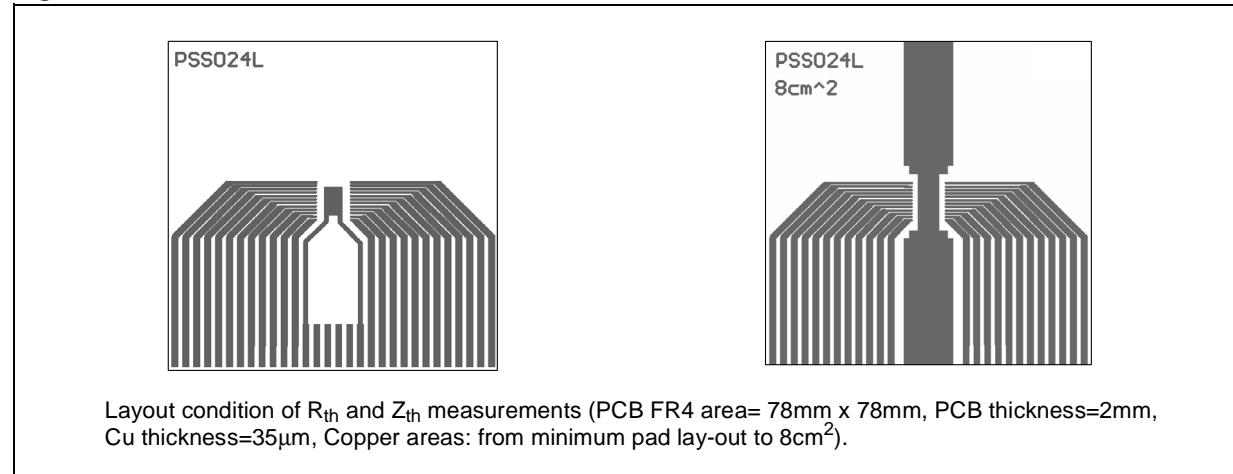
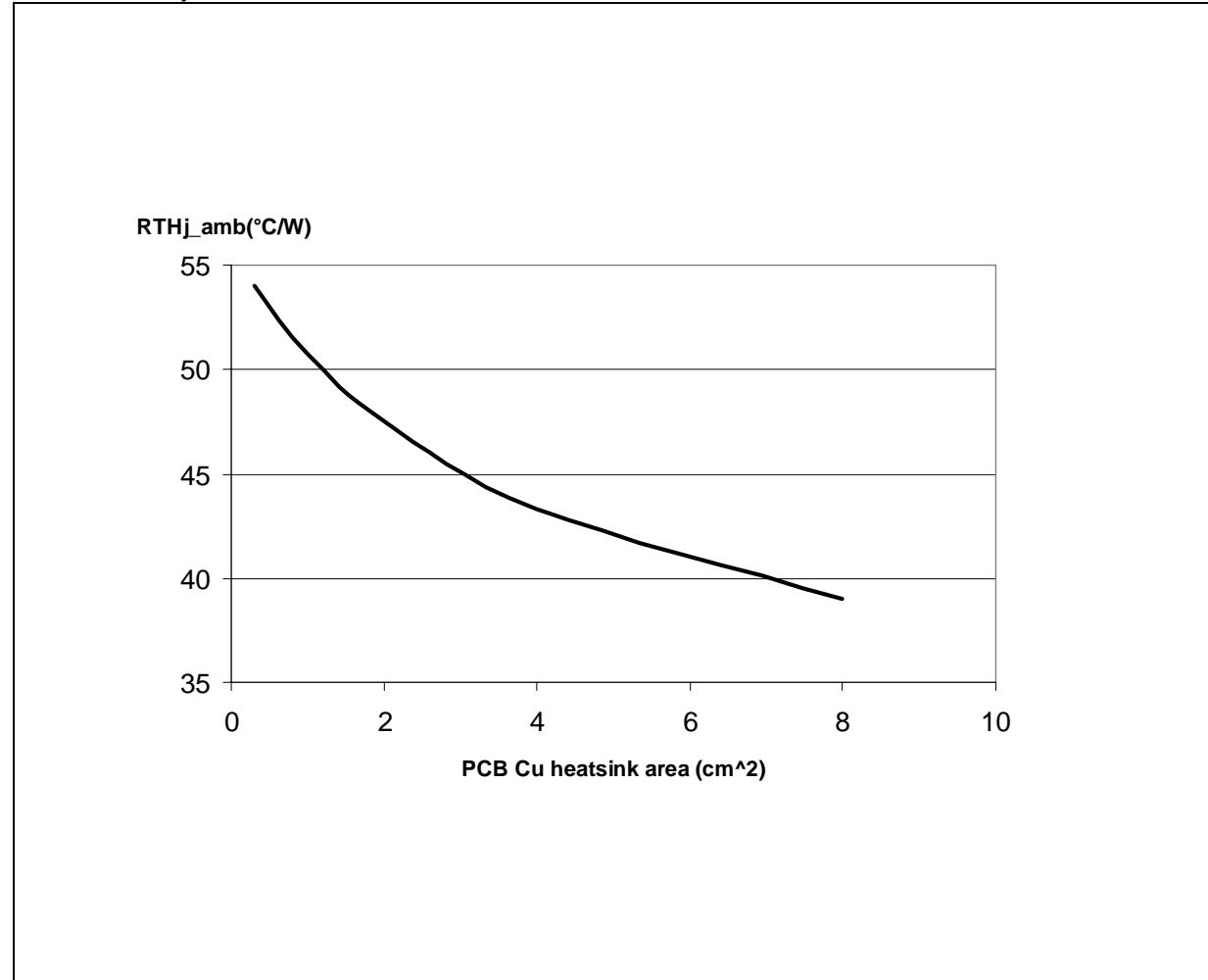
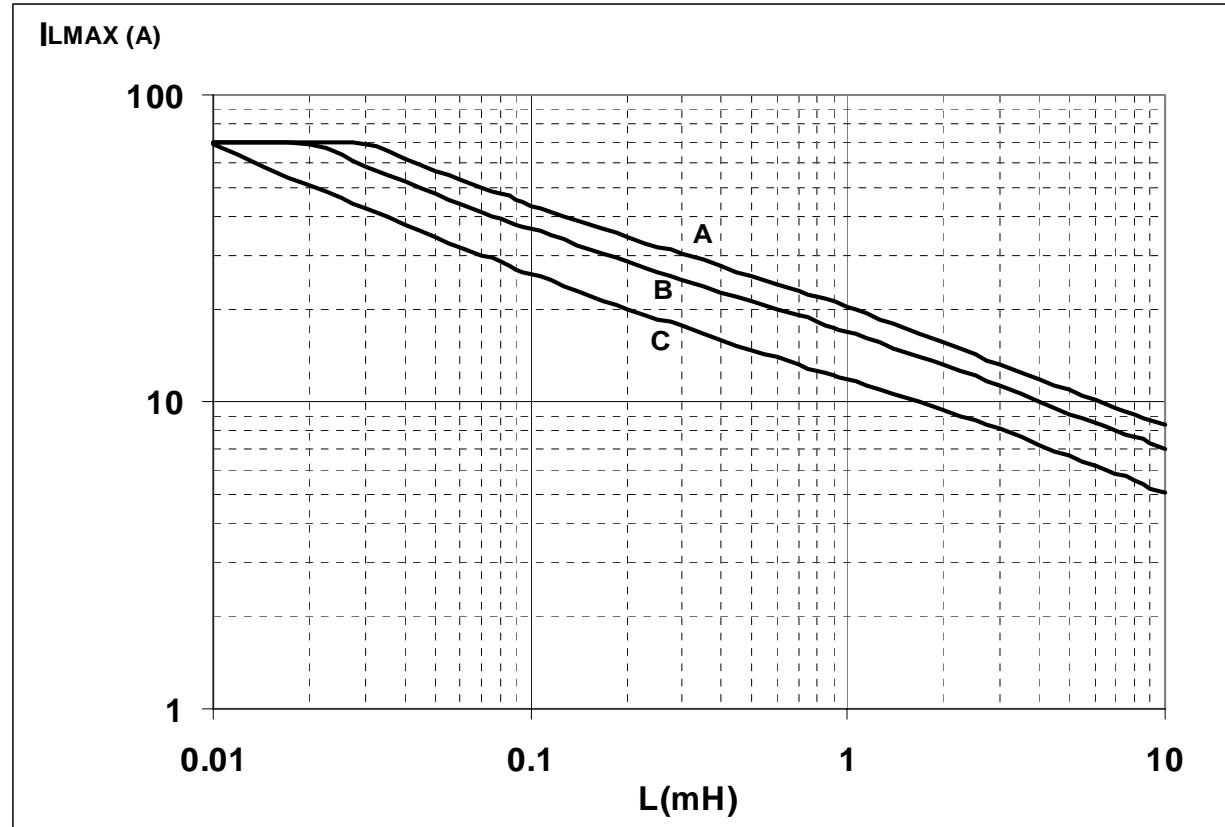
PowerSSO-24 Thermal Data**Figure 21. PowerSSO-24 PC Board****Figure 22. R_{thj_amb} Vs PCB copper area in open box free air condition**

Figure 23. Maximum turn off current versus load inductance



A = Single Pulse at $T_{jstart}=150^{\circ}\text{C}$

B= Repetitive pulse at $T_{jstart}=100^{\circ}\text{C}$

C= Repetitive Pulse at $T_{jstart}=125^{\circ}\text{C}$

Values are generated with $R_L=0\Omega$

In case of repetitive pulses, T_{jstart} (at beginning of each demagnetization) of every pulse must not exceed the temperature specified above for curves B and C.

Conditions:

$V_{CC}=13.5\text{V}$

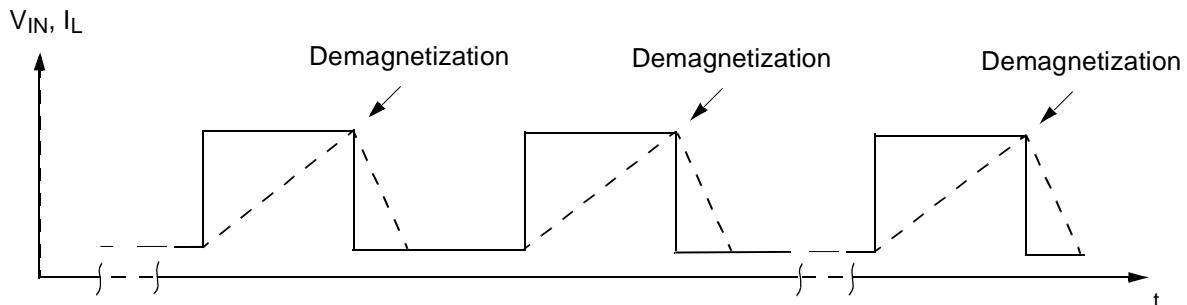
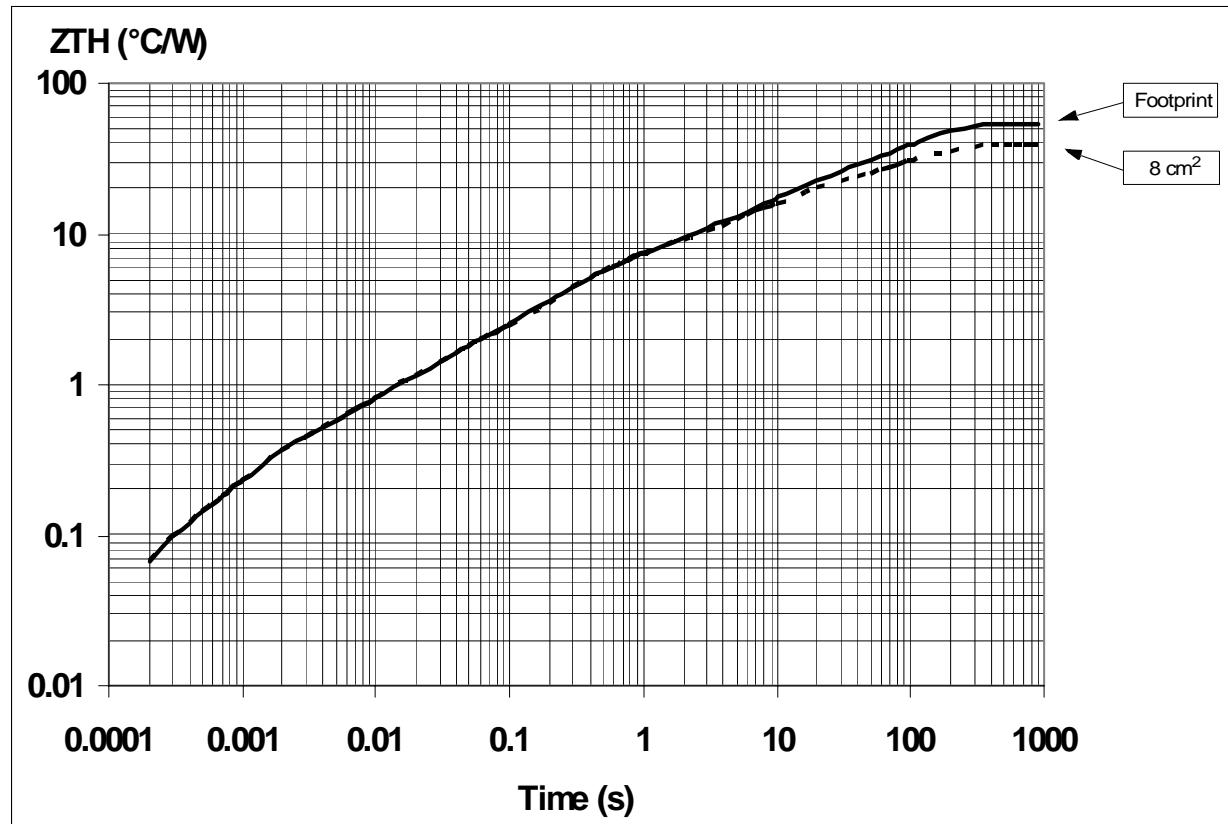
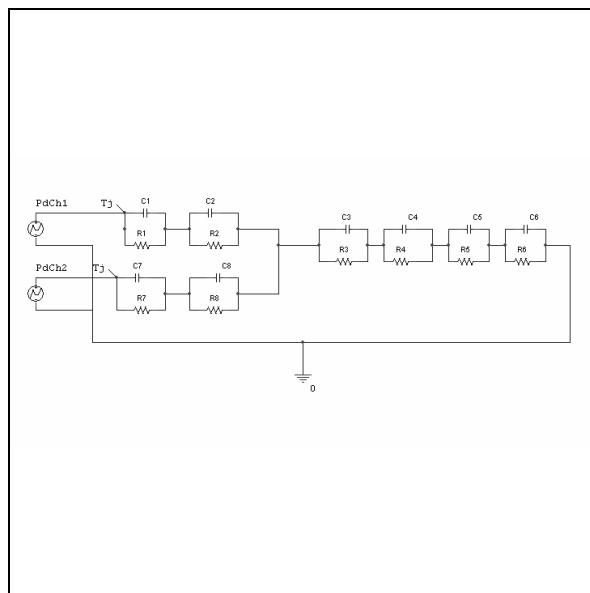


Figure 24. PowerSSO-24 Thermal Impedance Junction Ambient Single Pulse**Figure 25. Thermal Fitting Model of a Double Channel HSD in PowerSSO-24****Pulse Calculation Formula**

$$Z_{\text{TH}\delta} = R_{\text{TH}} \cdot \delta + Z_{\text{THtp}}(1 - \delta)$$

where $\delta = t_p/T$

Table 13. Thermal Parameter

Area/island (cm^2)	Footprint	8
R1=R7 ($^{\circ}\text{C}/\text{W}$)	0.05	
R2=R8 ($^{\circ}\text{C}/\text{W}$)	0.3	
R3 ($^{\circ}\text{C}/\text{W}$)	0.9	
R4 ($^{\circ}\text{C}/\text{W}$)	5	
R5 ($^{\circ}\text{C}/\text{W}$)	13.5	
R6 ($^{\circ}\text{C}/\text{W}$)	37	22
C1=C7 (W.s/ $^{\circ}\text{C}$)	0.001	
C2=C8 (W.s/ $^{\circ}\text{C}$)	0.005	
C3 (W.s/ $^{\circ}\text{C}$)	0.025	
C4 (W.s/ $^{\circ}\text{C}$)	0.08	
C5 (W.s/ $^{\circ}\text{C}$)	0.7	
C6 (W.s/ $^{\circ}\text{C}$)	3	5

PACKAGE MECHANICAL**Table 14. PowerSSO-24™ Mechanical Data**

Symbol	millimeters		
	Min	Typ	Max
A	2.15		2.47
A2	2.15		2.40
a1	0		0.075
b	0.33		0.51
c	0.23		0.32
D	10.10		10.50
E	7.4		7.6
e		0.8	
e3		8.8	
G			0.1
G1			0.06
H	10.1		10.5
h			0.4
L	0.55		0.85
N			10deg
X	4.1		4.7
Y	6.5		7.1

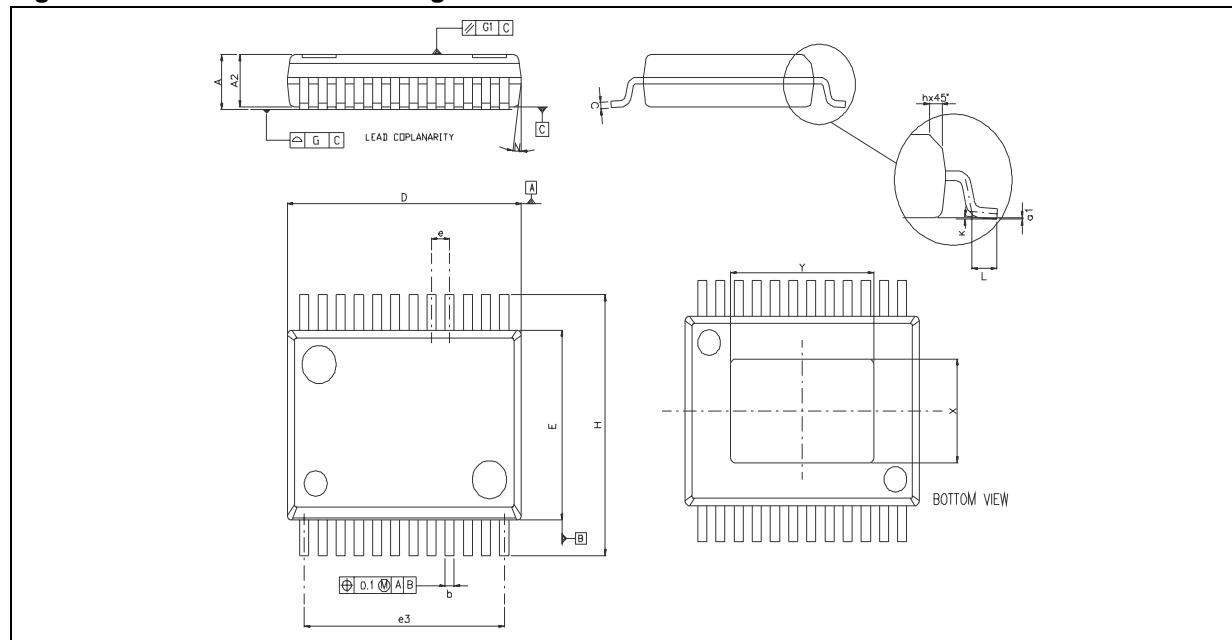
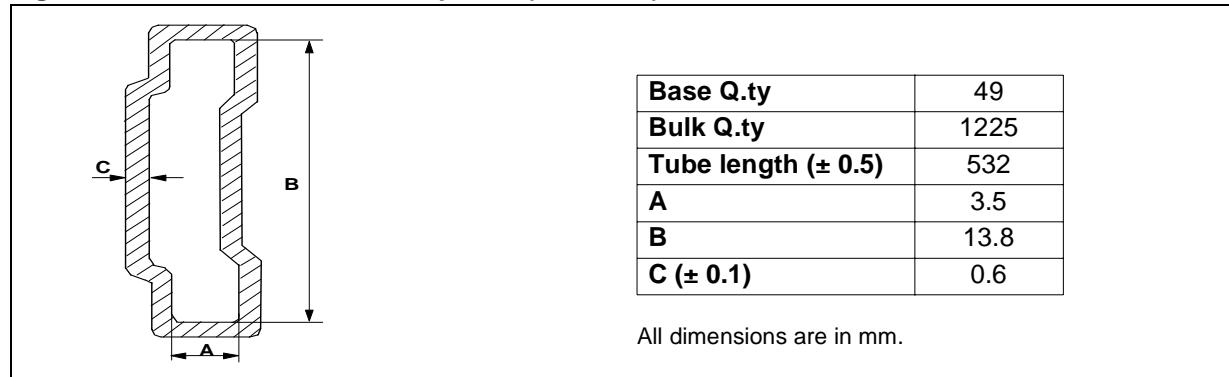
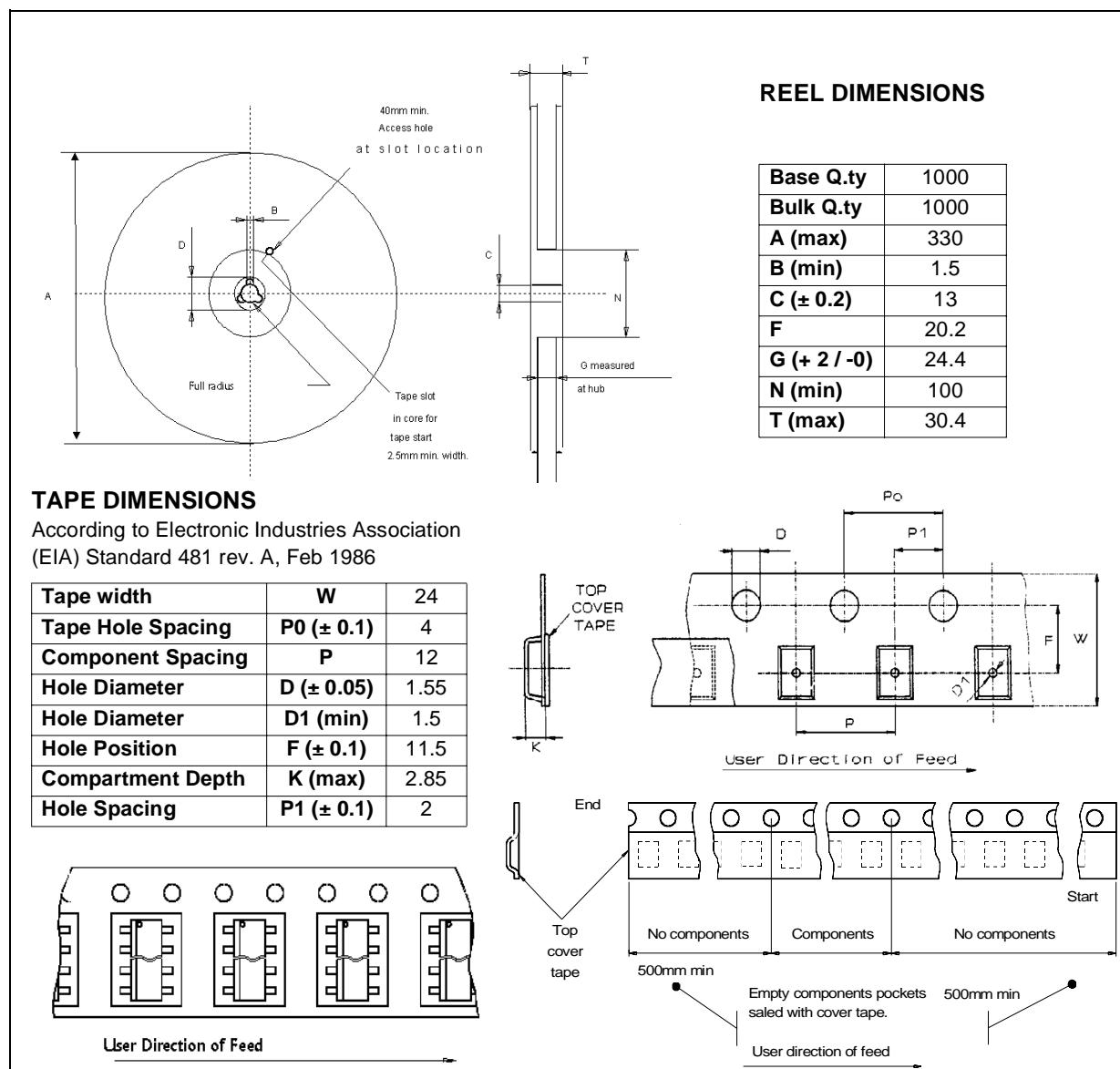
Figure 26. PowerSSO-24™ Package Dimensions

Figure 27. PowerSSO-24 Tube Shipment (No Suffix)**Figure 28. Tape And Reel Shipment (Suffix "TR")**

REVISION HISTORY**Table 15. Revision History**

Date	Revision	Description of Changes
Nov. 2004	1	- First Issue.
Dec. 2004	2	- $I_{L(off2)}$ removal.
Mar. 2005	3	- Maximum Switching Energy insertion; - Thermal data insertion; - Maximum turn off current versus load inductance; - Thermal Impedance Junction Ambient Single Pulse curve insertion.
Apr. 2005	4	- Configuration diagram modification - Shipment data insertion
May 2005	5	- Minor changes

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