1. General description

The UBA3070 driver IC is the first member of a first generation of power-efficient LED backlight driver ICs.

Highly efficient, flexible and reliable LED drivers can easily be designed using the UBA3070 control IC.

2. Features

- Switch-mode buck controller that drives strings of LEDs up to 600 V power-efficiently
- Controller with power-efficient boundary conduction mode of operation:
 - No reverse recovery losses in freewheel diode
 - Zero current switching for turn-on of switch
 - Zero voltage or valley switching for turn-on of switch
 - Minimal required inductance value and size
- Direct Pulse Width Modulation (PWM) dimming available
- Fast transient response through cycle-by-cycle current control, thereby:
 - Preventing over or undershoots in the LED current
 - Enabling efficient PWM dimming by quickly turning the converter on and off and thereby removing the need for extra dim switches and high-side drivers
- Single loosely controlled input voltage required for all LED strings in RGB backlights
- No binning on LED forward voltage required
- Protections:
 - Undervoltage lockout
 - Leading edge blanking
 - Overcurrent
 - Overtemperature
- Low cost LED driver solution:
 - No Schottky diode required because of zero-current switching
 - No dim switch and high-side driver required for PWM dimming
 - Smaller inductor possible compared to fixed-frequency continuous conduction mode controllers

3. Applications

The UBA3070 is typically suited as a high voltage LED backlighting application in LCD televisions and monitors (See Figure 1)



4. Ordering information

Table 1. Ordering information			
Type number Package			
	Name	Description	Version
UBA3070T	SO8	plastic small outline package; 8 leads; body width 3.9 mm	SOT96-1

5. Block diagram





6. Pinning information

6.1 Pinning



6.2 Pin description

Table 2.Pin description

Symbol	Pin SO8	Description
V _{CC}	1	supply voltage
GND	2	ground
PWM	3	PWM input voltage
MASK	4	masking input voltage
	-	
SENSE	5	resistor programmable current sense input

Table 2.	Pin d	escription	.continued
Syml	bol	Pin	Description
		SO8	
GATE		6	gate driver output
HVS		7	high voltage safety spacer: not connected
DRAIN		8	drain of external MOS switch: input for valley sensing

7. Functional description

The UBA3070 is a monolithic driver IC for controlling the current through LED strings and is especially suitable as driver stage for LED Backlighting applications like LCD televisions.

The driver stage enables optimal performance for series connected LED strings in 0D, 1D and 2D segmented backlight units (BLUs). Since the UBA3070 drives an external power device, it can be used for all kinds of BLU designs ranging from high-power to low-power LEDs, and high-voltage to low-voltage LED strings. Consequently it provides a driver solution for all LCD screen sizes and types of LEDs. By combining the UBA3070 with the appropriate power devices, the amount of drivers can be minimized by optimizing the amount of LEDs put in series.

Each driver stage consists of a buck converter operating in boundary conduction mode of which the peak level can be chosen by means of the external sense resistor. Since the peak and zero levels are fixed by design, the converter behaves as a current source. This gives an average current through the LEDs that is half the peak value of that through the inductor. The ripple current through the LEDs can be chosen by means of the external capacitor in parallel to the LEDs.

7.1 Supply management and undervoltage lockout

As long as V_{CC} is below the V_{CC(startup)} level of typically 10 V, the supply current is below 600 μ A. The IC will activate the converter as soon as the voltage on the V_{CC} pin passes the V_{CC(startup)} level. The moment the voltage on pin V_{CC} drops below the undervoltage lockout voltage of typically 8.7 V the IC stops switching.

7.2 Current control and PWM

If the PWM input is high (> 2 V) the converter is disabled, it will not switch and the LED current is zero. If the PWM input pin is low (< 0.5 V) the converter is enabled and operation is as follows. The external FET is turned on and current in the inductor will build up. During this charging phase of the inductor the current is sensed across an external sense resistor. The internal driver turns off the external FET upon detection of a voltage level of typically 0.52 V at the SENSE pin. The inductor will freewheel its current through the external diode and will discharge. After discharge the switch node will ring. Upon detection of a valley or zero voltage on the switch node the internal driver will turn on the external FET. Consequently turn-on of the FET is at zero current and at minimal voltage resulting in minimal power losses and EMI. The conversion cycle will repeat as described above, until the PWM input signal is driven high to disable the converter and steer the LED current to zero.

If the PWM pin is open circuit or not connected, a fault condition is assumed and the converter will stop switching. Operation will recommence as soon as the fault condition is removed.

7.3 Masking and valley switching

The mask pin ensures that turn-on of the converter is at a valley during ringing and not at a peak during freewheeling of the inductor. If the voltage level at the mask pin is typically above 100 mV, then turn-on of the switching FET is prevented. If the voltage level is below this 100 mV, then turn-on prevention of the FET is released and at the moment of valley detection the FET will actually turn on. The signal for the mask pin can be easily derived from the signal at the switch node as shown in the application diagram. The current flowing into the mask pin should be lower than the typical stop current of 60 μ A.

If pin MASK is open circuit or not connected, a fault condition is assumed and the converter will stop operating immediately. Operation will recommence as soon as the fault condition is removed.

7.4 Conversion frequency

The maximum conversion frequency is limited to minimally 145 kHz by an internal oscillator. Consequently the inductance value should be chosen such that with the given supply voltage, LED voltage and component spread the conversion frequency is always smaller than this. There is no limitation for the minimum conversion frequency.

7.5 Minimum on-time

The minimum on-time of the switch mode converter is determined by the leading edge blanking time of typically 370 ns. The leading edge blanking time is required to prevent inadvertent switch off after turn on of the FET due to coupling to the sense node.

7.6 Overcurrent protection

Since the converter behaves as a current source it is principally self-protected from overcurrent. An extra level of protection is added by means of a second trip level at typically 0.88 V at the sense node to protect against short-circuits in external components like diodes, inductors, capacitors or LEDs. Upon detection of this abnormal situation the converter will stop switching.

7.7 Soft start-up (pin SENSE)

To have slow start-up the inductor peak current is slowly increased by the soft start-up function. This can be achieved by inserting a resistor and a capacitor between the SENSE-pin (pin 5) and sense resistor R_{sense} . An internal current source charges the capacitor to $V_{SENSE} = I_{ch} \times R_{ss}$ (about 0.5 V maximum).

The start level and the time constant of the increasing primary current level can be adjusted externally by changing the values of R_{ss} and C_{ss} .

$$I_{DM} = \frac{V_{sense(max)} - (I_{ch} \times R_{ss})}{R_{sense}}$$

$$\tau = R_{ss} \times C_{ss}$$

The charge current I_{ch} will flow as long as the voltage on pin SENSE is below approximately 0.5 V. If the voltage on pin SENSE exceeds 0.5 V, the soft start current source will start limiting current I_{ch}. At V_{startup}, the I_{ch} current source is completely switched off, see Figure 4.



7.8 Overtemperature protection

An accurate temperature protection is provided in the UBA3070. When the junction temperature exceeds the thermal shutdown temperature of typically 140 °C the converter will stop switching.

7.9 Driver

The driver circuit to the gate of the power FET has a current sourcing capability of 135 mA typical and a current sinking capability of 560 mA typical. This permits fast turn-on and turn-off of the FET for efficient operation. A low driver source current has been chosen to limit the $\Delta V/\Delta t$ at turn-on thereby reducing EMI and voltage spikes across R_{sense}. The driver circuit to the gate of the power MOSFET has a current sourcing capability of 135 mA typical and a current sink capability of 560 mA typical. This permits fast turn-on and turn-off of the power MOSFET for efficient operation.

8. Limiting values

Table 3. In accordar	Limiting values nce with the Absolute Maxin	num Rating System (IEC 60134).[<u>1]</u>		
Symbol	Parameter	Conditions	Min	Max	Unit ^[1]
Voltages					
V _{CC}	supply voltage	current limited	-0.4	+20	V
V _{PWM}	voltage on pin PWM		-0.4	+5	V
V _{MASK}	voltage on pin MASK	current limited	-0.4	-	V
V _{SENSE}	voltage on pin SENSE	current limited	-0.4	-	V
V _{DRAIN}	voltage on pin DRAIN		-0.4	+650	V
Currents					
I _{PWM}	current on pin PWM		-	5	mA

In accorda	nce with the Absolute Maxir	num Rating System (IEC	C 60134). <mark>[1]</mark>		
Symbol	Parameter	Conditions	Min	Max	Unit ^[1]
I _{MASK}	current on pin MASK		-250	+250	μΑ
I _{SENSE}	current on pin SENSE		-1	+10	mA
I _{GATE}	current on pin GATE	d < 10 %	-0.8	+2	А
I _{DRAIN}	current on pin DRAIN		-	5	mA
General					
P _{tot}	total power dissipation	T _{amb} < 70 °C	-	0.5	W
T _{stg}	storage temperature		-55	+150	°C
Тj	junction temperature		-40	+145	°C
ESD					
V _{ESD}	electrostatic discharge				
voltage	all pins except pins DRAIN and V _{CC} ; HBM class 1	<u>[2]</u> _	2000	V	
		pins DRAIN and V _{CC} ; HBM class 1	[2] -	1500	V
		any pin; MM	[3] _	200	V

Table 3. Limiting values ... continued

[1] All voltages are measured with respect to ground; positive currents flow into the IC. The pin V_{CC} may not be current driven. The voltage ratings are valid provided other ratings are not violated. The current ratings are valid provided the maximum power rating is not violated.

[2] Human Body Model (HBM): equivalent to discharging a 100 pF capacitor through a 1.5 kΩ resistor.

[3] Machine Model (MM): equivalent to discharging a 200 pF capacitor through a 0.75 μ H coil and a 10 Ω resistor.

Thermal characteristics 9.

Table 4.	Thermal characteristics			
Symbol	Parameter	Conditions	Тур	Unit
R _{th(j-a)}	thermal resistance from junction to ambient	In free air	150	K/W

10. Characteristics

Table 5. **Characteristics**

T_{amb} = 25 ° C; V_{CC} = 15 V; all voltages are measured with respect to ground; currents are positive when flowing into the IC; unless otherwise specified.

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
Start-up curr	ent source (pin DRAIN)					
V _{BR}	breakdown voltage		650	-	-	V
Supply voltage	ge management (pin V _{CC})					
V _{CC(startup)}	start-up supply voltage		9.3	10	10.6	V
V _{CC(UVLO)}	undervoltage lockout supply voltage		8.1	8.7	9.3	V
V _{CC(hys)}	hysteresis of supply voltage	$V_{CC(startup)} - V_{CC(UVLO)}$	1.0	1.3	1.6	V

UBA3070 2

Table 5. Characteristics ...continued

 $T_{amb} = 25 \circ C$; $V_{CC} = 15 V$; all voltages are measured with respect to ground; currents are positive when flowing into the IC; unless otherwise specified.

MASKMASK $V_{clamp(pos)(MASK)}$ positive clamp voltage on pin MASK $I_{MASK} = 250 \mu A$ 0.50.7 $I_{stop(pos)(MASK)}$ positive stop current on pin MASK5460 $I_{stop(pos)(MASK)}$ positive stop current on pin MASK5460 $I_{sup(xfmr_ring)}$ transformer ringing suppression timestart secondary shock1.11.5 $I_{prot(MASK)}$ protection current on pin MASK $V_{MASK} = 50 mV$ -5011 -Oscillator $V_{osc(high)}$ high oscillator frequency V_{PWM} is low14517PWM duty cycle control (pin PWM) $V_{IL(en)ILED(PWM)}$ LED current enable LOW-level input voltage on pin PWM[2] $V_{IH(dis)ILED(PWM)}$ LED current disable HIGH-level input voltage on pin PWM[2]2.0- $I_{prot(PWM)}$ protection current on pin PWM $V_{PWM} = 1.5 V$ $-1.0[1]$ -0 $Valley switch (pin DRAIN)$ valley recognition voltage change with time -85 -	3 1.5 600 35 0 150 .25 -0.0 7 0.9 66	mA μA mA
lcC(startup)start-up supply current $V_{CC} < V_{CC(startup)}$ -lcC(prot)protection supply current $V_{CC} < V_{CC(UVLO)}$ -0.6Masking management (pin MASK)VV-0.6Vth(MASK)threshold voltage on pin MASK5010Vclamp(neg)(MASK)negative clamp voltage on pin MASK5010Vclamp(pos)(MASK)positive clamp voltage on pin MASK-0.5-0Vclamp(pos)(MASK)positive clamp voltage on pin MASKImask = 250 μ A0.50.7lstop(pos)(MASK)positive stop current on pin MASK5460tsup(xfmr_ring)transformer ringing suppressionstart secondary shock1.11.5lprot(MASK)protection current on pin MASKVMASK = 50 mV-50[1]-Oscillatorfosc(high)high oscillator frequencyVPWM is low14517PVMM duty cycle control (pin PWM)VIL(en)ILED(PWM)LED current disable HIGH-level input voltage on pin PWM22.0-lprot(PVM)protection current on pin PWMVPWM = 1.5 V-1.0[1]-0Valley switch (pin DRAIN)($\Delta V/\Delta t)_{Vrec}$ valley recognition voltage change with time-85-	600 35 - 0 150 .25 -0.0 7 0.9 66 5 1.9	μΑ mA mV 05 V V
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$(\Delta V/\Delta t)_{vrec}$ valley recognition voltage change -85 - with time	.8 –0.5	5 μΑ
with time		
ty you walley recognition to switch-on - 15	+85	V/μs
t _{d(vrec-swon)} valley recognition to switch-on - 15 delay time	0 <u>[1]</u> -	ns
Overcurrent protection (pin SENSE)		
$V_{sense(max)}$ maximum sense voltage $\Delta V/\Delta t = 0.1 V/\mu s$ 0.48 0.5	52 0.56	6 V
t_{PD} propagation delay $\Delta V/\Delta t = 0.5 V/\mu s$ - 14	0 185	ns
V _{swp} short-winding protection voltage 0.83 0.8	38 0.95	5 V
t _{leb} leading edge blanking time 300 37	0 440	ns
$I_{startup(soft)}$ soft startup current $R_{sense} < 0.5 V$ 45 60	75	μΑ
Driver (pin GATE)		
I_{source} source current $V_{CC} = 9.5 V$;1: $V_{DRIVER} = 2 V$	35 -	mA
$I_{sink} \qquad sink \ current \qquad V_{CC} = 9.5 \ V; \qquad - 24 \\ V_{DRIVER} = 2 \ V$	0 -	mA
V _{CC} = 9.5 V; - 56 V _{DRIVER} = 9.5 V	0 -	mA
$V_{o(max)}$ maximum output voltage $V_{CC} > 12 V$ - 11		V

Table 5. Characteristics ...continued

 $T_{amb} = 25 \circ C$; $V_{CC} = 15 V$; all voltages are measured with respect to ground; currents are positive when flowing into the IC; unless otherwise specified.

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
Overtempera	ature protection					
T _{pl(max)}	maximum protection level temperature		130	140	150	°C
T _{pl(hys)}	protection level hysteresis temperature		-	8	-	°C

[1] Guaranteed by design.

[2] When the voltage at pin PWM is between 0.5 V and 2.0 V the peak current and the frequency will be reduced.

UBA3070 LED backlight driver IC

11. Package outline



Package outline SOT96-1(SO8) Fig 5.

12. Revision history

Table 6. Revisio	on history			
Document ID	Release date	Data sheet status	Change notice	Supersedes
UBA3070_2	20081202	Product data sheet	-	UBA3070_1
Modifications:	 The minimu 	m value for junction tempe	erature has been updated	l in <u>Table 3</u> .
UBA3070_1	20080605	Product data sheet	-	-

13. Legal information

13.1 Data sheet status

Document status[1][2]	Product status ^[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

[3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL http://www.nxp.com.

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