

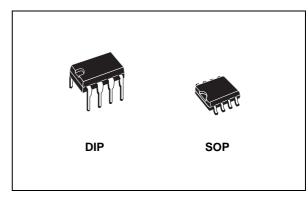


±15KV ESD PROTECTED, LOW POWER RS-485/RS-422 TRANSCEIVER

- LOW QUIESCENT CURRENT: 300µA
- DESIGNED FOR RS-485 INTERFACE APPLICATIONS
- -7V TO 12V COMMON MODE INPUT VOLTAGE RANGE
- DRIVER MAINTAINS HIGH IMPEDANCE IN 3-STATE OR WITH THE POWER OFF
- 70mV TYPICAL INPUT HYSTERESIS
- 30ns PROPAGATION DELAYS, 5ns SKEW
- OPERATE FROM A SINGLE 5V SUPPLY
- CURRENT LIMITING AND THERMAL SHUTDOWN FOR DRIVER OVERLOAD PROTECTION
- ESD PROTECTION: ±15KV (H.B.M.) ±8KV (IEC-1000-4-2 CONTACT DISCHARGE)
- ALLOWS UP TO 64 TRANSCEIVERS ON THE BUS

DESCRIPTION

The ST485E is al low power transceiver for RS-485 and RS-422 communication. Each driver output and receiver input is protected against $\pm 15 \, \text{KV}$ electrostatic discharge (H.B.M.) (ESD) shocks, without latcup. These parts contain one



driver and one receiver in half duplex configuration.

This transceiver draw $300\mu A$ (typ.) of supply current when unloaded or fully loaded with disabled drivers.

It operates from a single 5V supply.

Driver is short-circuit current limited and is protected against excessive power dissipation by thermal shutdown circuitry that place the driver outputs into a high-impedance state.

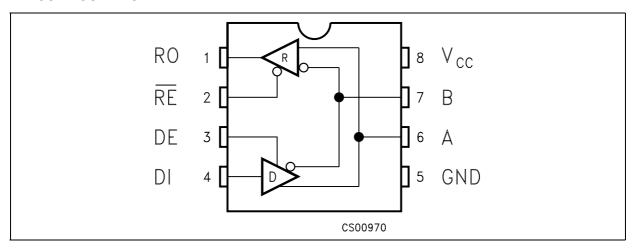
The ST485E is designed for bi-directional data communications on multipoint bus transmission line (half-duplex applications).

ORDERING CODES

Туре	Temperature Range	Package	Comments
ST485ECN	0 to 70 °C	DIP-8	50parts per tube / 40tube per box
ST485EBN	-40 to 85 °C	DIP-8	50parts per tube / 40tube per box
ST485EXN	-55 to 125 °C	DIP-8	50parts per tube / 40tube per box
ST485ECD	0 to 70 °C	SO-8 (Tube)	100parts per tube / 20tube per box
ST485EBD	-40 to 85 °C	SO-8 (Tube)	100parts per tube / 20tube per box
ST485EXD	-55 to 125 °C	SO-8 (Tube)	100parts per tube / 20tube per box
ST485ECDR	0 to 70 °C	SO-8 (Tape & Reel)	2500 parts per reel
ST485EBDR	-40 to 85 °C	SO-8 (Tape & Reel)	2500 parts per reel
ST485EXDR	-55 to 125 °C	SO-8 (Tape & Reel)	2500 parts per reel

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PIN CONFIGURATION



PIN DESCRIPTION

PIN N°	SYMBOL	NAME AND FUNCTION
1	RO	Receiver Output
2	RE	Receiver Output Enable
3	DE	Driver Output Enable
4	DI	Driver Input
5	GND	Ground
6	A	Non-inverting Receiver Input and Non-inverting Driver Output
7	В	Inverting Receiver Input and Inverting Driver Output
8	V _{cc}	Supply Voltage

TRUTH TABLE (DRIVER)

	INPUTS	OUTPUTS		
RE	DE	В	Α	
X	Н	Н	L	Н
X	Н	L	Н	L
Х	L	Х	Z	Z

X= Don't Care; Z=High Impedance

TRUTH TABLE (RECEIVER)

	INPUTS					
RE	DE	A-B	RO			
L	L	≥ +0.2V	Н			
L	L	≤ - 0.2V	L			
L	L	INPUTS OPEN	Н			
Н	L	X	Z			

X= Don't Care; Z=High Impedance

ABSOLUTE MAXIMUM RATINGS

Symbol	Parameter	Value	Unit
V _{CC}	Supply Voltage	7	V
VI	Control Input Voltage (RE, DE)	-0.5 to (V _{CC} + 0.5)	V
V _{DI}	Driver Input Voltage (DI)	-0.5 to (V _{CC} + 0.5)	V
V _{DO}	Driver Output Voltage (A, B)	± 14	V
V _{RI}	Receiver Input Voltage (A, B)	± 14	V
V _{RO}	Receiver Output Voltage (RO)	-0.5 to (V _{CC} + 0.5)	V

Absolute Maximum Ratings are those values beyond which damage to the device may occur. Functional operation under these condition is not implied.

ESD PERFORMANCE: TRANSMITTER OUTPUTS, RECEIVER INPUTS

Symbol	Parameter	Test Conditions	Min.	Тур.	Max.	Unit
ESD	ESD Protection Voltage	Human Body Model	±15			ΚV
ESD	ESD Protection Voltage	IEC-1000-4-2	±8			KV

DC ELECTRICAL CHARACTERISTICS

 $(V_{CC}=5V\pm5\%,\,T_A=T_{MIN}\,\,\,to\,\,T_{MAX}\,,\,unless\,otherwise\,specified.\,Typical\,values\,are\,\,referred\,to\,\,T_A=25^{\circ}C)$ (See Note 1)

Symbol	Parameter	Test Conditions	Min.	Тур.	Max.	Unit
V_{OD1}	Differential Driver Output (No Load)				5	V
V_{OD2}	Differential Driver Output (With Load)	$R_L = 27\Omega \text{ (RS-485) (See Fig. 1)}$ $R_L = 50\Omega \text{ (RS-422) (See Fig. 1)}$	1.5		5 5	V V
ΔV _{OD}	Change in Magnitude of Driver Differential Output Voltage for Complementary Output States	$R_L = 27\Omega$ or 50Ω (See Fig. 1)			0.2	V
V _{oc}	Driver Common-Mode Output Voltage	$R_L = 27\Omega \text{ or } 50\Omega \text{ (See Fig. 1)}$			3	V
ΔV _{OC}	Change in Magnitude of Driver Common-Mode Output Voltage for Complementary Output States	$R_L = 27\Omega$ or 50Ω (See Fig. 1)			0.2	V
V_{IH}	Input High Voltage	RE, DE, DI	2.0			V
V _{IL}	Input Low Voltage	RE, DE, DI			0.8	V
I _{IN1}	Input Current	RE, DE, DI			± 2	μΑ
I _{IN2}	Input Current (A, B)	$V_{CM} = 0V \text{ or } 5.25V$ $V_{DE} = 0V$ $V_{IN} = 12V$ $V_{IN} = -7V$			1 -0.8	mA mA
V_{TH}	Receiver Differential Threshold Voltage	V _{CM} = -7 to 12V	-0.2		0.2	V
ΔV_{TH}	Receiver Input Hysteresis	$V_{CM} = 0V$		70		mV
V _{OH}	Receiver Output High Voltage	$I_O = -4mA$ $V_{ID} = 200mV$	3.5			V
V _{OL}	Receiver Output Low Voltage	$I_O = 4mA$ $V_{ID} = -200mV$			0.4	V
I _{OZR}	3-State (High Impedance) Output Current at Receiver	$V_{O} = 0.4 \text{ to } 2.4 \text{V}$			± 1	μА
R _{IN}	Receiver Input Resistance	V _{CM} = -7 to 12V	24			KΩ
I _{CC}	No Load Supply Current (Note 2)	$V_{RE} = 0V \text{ or } V_{CC}$ $V_{DE} = V_{CC}$ $V_{DE} = 0V$		400 300	900 500	μA μA
I _{OSD1}	Driver Short-Circuit Current, V _O =High	V _O = -7 to 12V (Note 3)	35		250	mA
I _{OSD2}	Driver Short-Circuit Current, V _O =Low	$V_O = -7$ to 12V (Note 3)	35		250	mA
I _{OSR}	Receiver Short-Circuit Current	$V_{O} = 0V \text{ to } V_{CC}$	7		95	mA

Note 1: All currents into device pins are positive; all cuttents out of device pins are negative; all voltages are referenced to device ground



Note 2: Supply current specification is valid for loaded transmitters when V_{DE} = 0V Note 3: Applies to peak current. See typical Operating Characteristics.

DRIVER SWITCHING CHARACTERISTICS

(V_{CC} = 5V ± 5%, T_A = T_{MIN} to T_{MAX} , unless otherwise specified. Typical values are referred to T_A = 25°C) (See Note 1)

Symbol	Parameter	Test C	Conditions	Min.	Тур.	Max.	Unit
t _{PLH}	Propagation Delay Input to	$R_{DIFF} = 54\Omega$	$C_{L1} = C_{L2} = 100pF$		25	45	ns
t _{PHL}	Output	(See Fig. 3 and 5)					
t _{SK}	Output Skew to Output	$R_{DIFF} = 54\Omega$	$C_{L1} = C_{L2} = 100pF$		2	5	ns
		(See Fig. 3 and 5)					
t _{TLH}	Rise or Fall Time	$R_{DIFF} = 54\Omega$	$C_{L1} = C_{L2} = 100pF$		15	40	ns
t _{THL}		(See Fig. 3 and 5)					
t _{PZH}	Output Enable Time	C _L = 100pF	S2 = Closed		35	50	ns
		(See Fig. 4 and 6)					
t _{PZL}	Output Enable Time	C _L = 100pF	S1 = Closed		25	40	ns
		(See Fig. 4 and 6)					
t _{PLZ}	Output Disable Time	C _L = 15pF	S1 = Closed		25	40	ns
		(See Fig. 4 and 6)					
t _{PHZ}	Output Disable Time	C _L = 15pF	S2 = Closed		35	50	ns
		(See Fig. 4 and 6)					

Note 1: All currents into device pins are positive; all cuttents out of device pins are negative; all voltages are referenced to device ground unless specified.

RECEIVER SWITCHING CHARACTERISTICS

(V_{CC} = 5V \pm 5%, T_A = T_{MIN} to T_{MAX} , unless otherwise specified. Typical values are referred to T_A = 25°C) (See Note 1)

Symbol	Parameter	Test C	Conditions	Min.	Тур.	Max.	Unit
t _{PLH}	Propagation Delay Input to Output	$R_{DIFF} = 54\Omega$ (See Fig. 3 and 7)	$C_{L1} = C_{L2} = 100pF$		110	130	ns
t _{SKD}	Differential Receiver Skew	$R_{DIFF} = 54\Omega$ (See Fig. 3 and 7)	$C_{L1} = C_{L2} = 100pF$		5	10	ns
t _{PZH}	Output Enable Time	C _{RL} = 15pF (See Fig. 2 and 8)	S2 = Closed		11	35	ns
t _{PZL}	Output Enable Time	C _{RL} = 15pF (See Fig. 2 and 8)	S1 = Closed		13	35	ns
t _{PLZ}	Output Disable Time	C _{RL} = 15pF (See Fig. 2 and 8)	S1 = Closed		13	35	ns
t _{PHZ}	Output Disable Time	C _{RL} = 15pF (See Fig. 2 and 8)	S2 = Closed		11	35	ns
f _{MAX}	Maximum Data Rate			5			Mbps

Note 1: All currents into device pins are positive; all cuttents out of device pins are negative; all voltages are referenced to device ground unless specified.

TEST CIRCUITS AND TYPICAL CHARACTERISTICS

Figure 1 : Driver DC Test Load

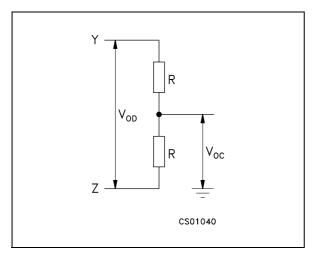


Figure 2: Receiver Timing Test Load

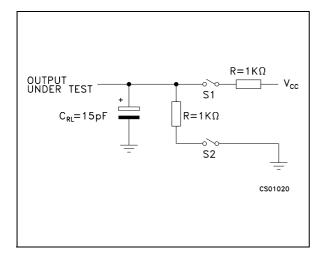


Figure 3 : Drive/Receiver Timing Test Circuit

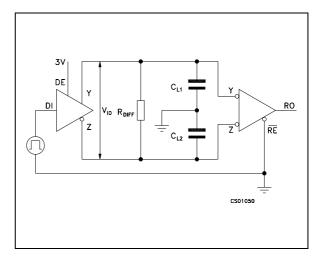


Figure 4 : Driver Timing Test Load

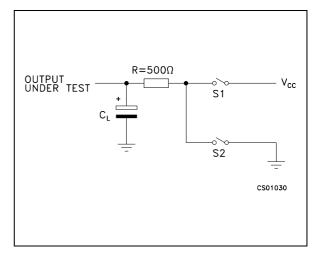


Figure 5 : Driver Propagation Delay

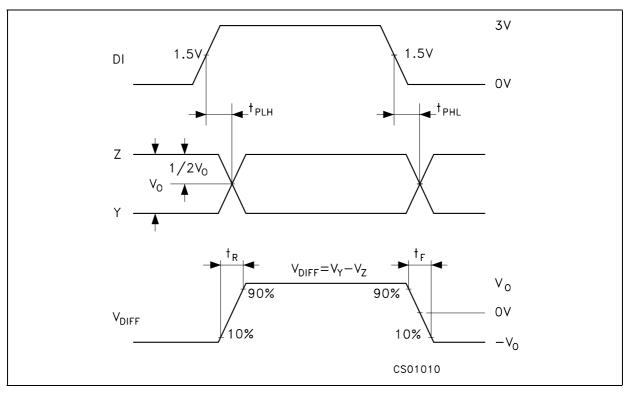


Figure 6: Driver Enable and Disable Time

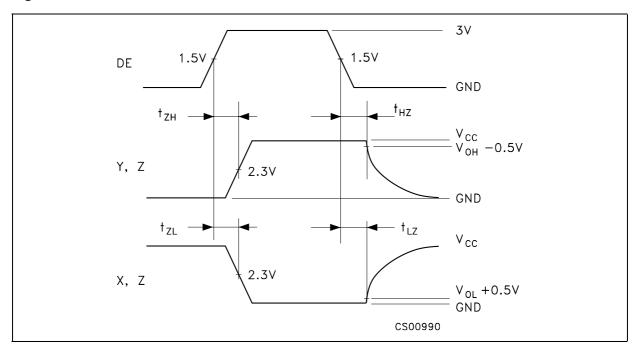


Figure 7: Receiver Propagation Delay

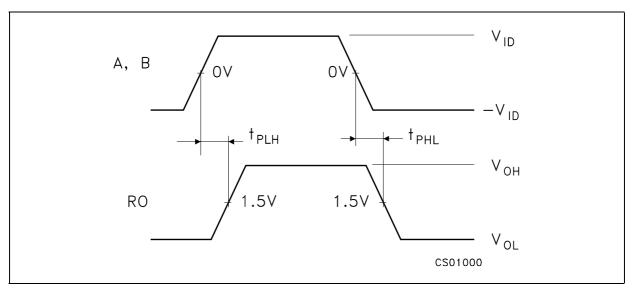


Figure 8: Receiver Enable and Disable Time

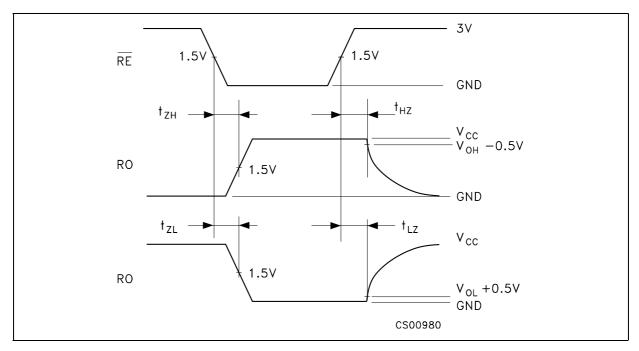


Figure 9 : Receiver Output Current vs Output Low Voltage

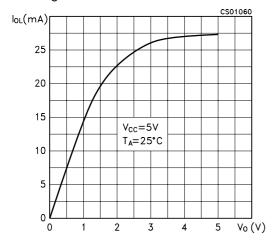


Figure 10 : Receiver Output Current vs Output High Voltage

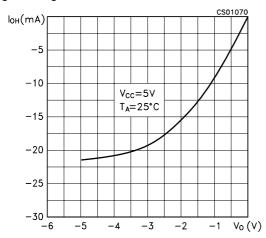


Figure 11 : Driver Output Current vs Output Low Voltage

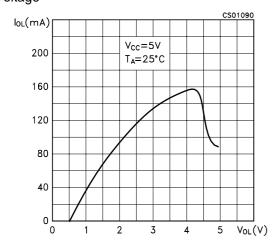


Figure 12 : Driver Output Current vs Output High Voltage

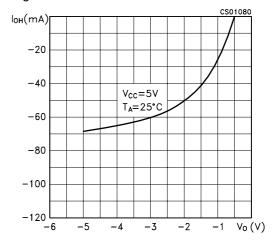


Figure 13 : Supply Current vs Temperature

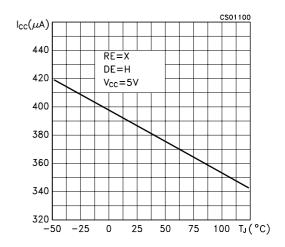


Figure 14 : Receiver High Level Output Voltage vs Temperature

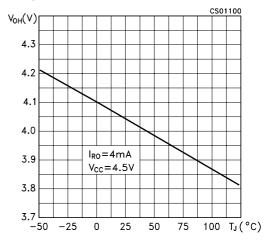


Figure 15 : Receiver Low Level Output Voltage vs Temperature

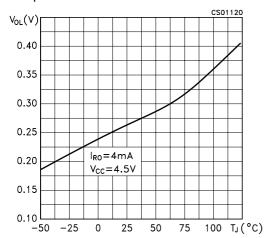
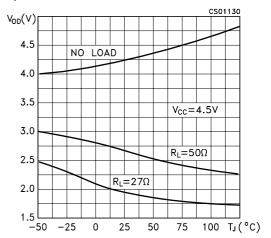
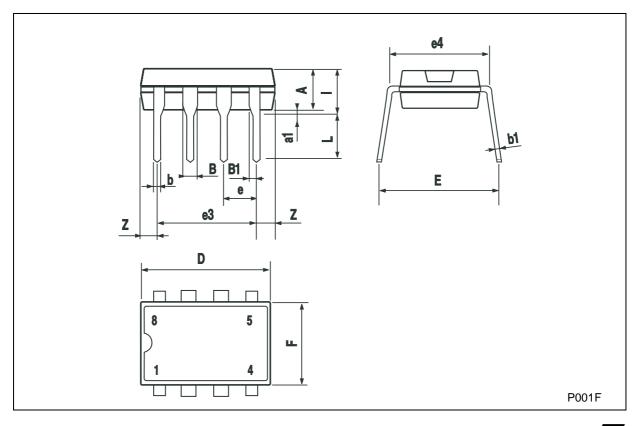


Figure 16 : Differential Driver Output Voltage vs Temperature



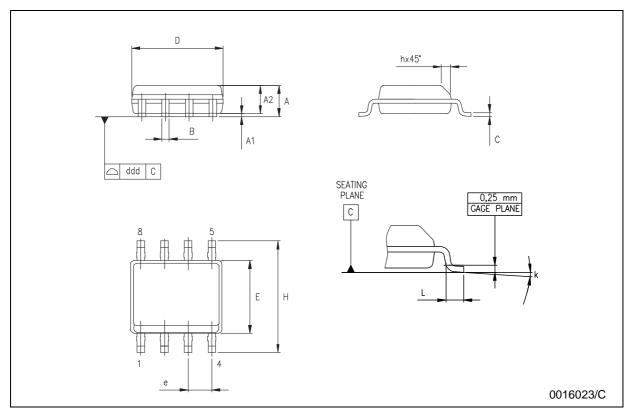
Plastic DIP-8 MECHANICAL DATA

DIM.		mm.			inch			
DIIVI.	MIN.	TYP	MAX.	MIN.	TYP.	MAX.		
А		3.3			0.130			
a1	0.7			0.028				
В	1.39		1.65	0.055		0.065		
B1	0.91		1.04	0.036		0.041		
b		0.5			0.020			
b1	0.38		0.5	0.015		0.020		
D			9.8			0.386		
Е		8.8			0.346			
е		2.54			0.100			
e3		7.62			0.300			
e4		7.62			0.300			
F			7.1			0.280		
I			4.8			0.189		
L		3.3			0.130			
Z	0.44		1.6	0.017		0.063		

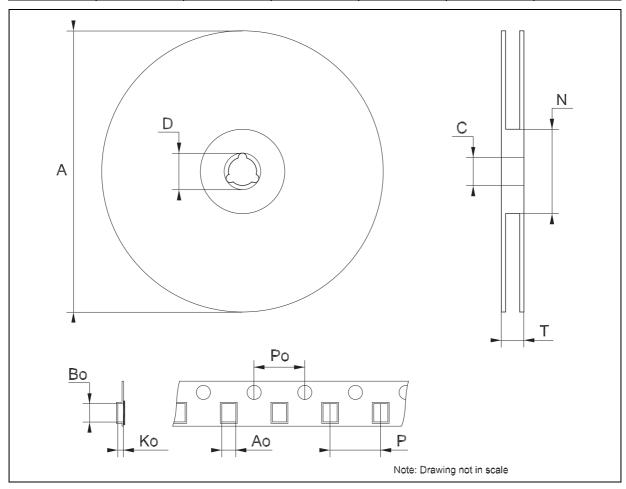


SO-8 MECHANICAL DATA

DIM.		mm.		inch		
DINI.	MIN.	TYP	MAX.	MIN.	TYP.	MAX.
А	1.35		1.75	0.053		0.069
A1	0.10		0.25	0.04		0.010
A2	1.10		1.65	0.043		0.065
В	0.33		0.51	0.013		0.020
С	0.19		0.25	0.007		0.010
D	4.80		5.00	0.189		0.197
Е	3.80		4.00	0.150		0.157
е		1.27			0.050	
Н	5.80		6.20	0.228		0.244
h	0.25		0.50	0.010		0.020
L	0.40		1.27	0.016		0.050
k			8° (n	nax.)		-
ddd			0.1			0.04



DIM.	mm.			inch		
	MIN.	TYP	MAX.	MIN.	TYP.	MAX.
А			330			12.992
С	12.8		13.2	0.504		0.519
D	20.2			0.795		
N	60			2.362		
Т			22.4			0.882
Ao	8.1		8.5	0.319		0.335
Во	5.5		5.9	0.216		0.232
Ko	2.1		2.3	0.082		0.090
Ро	3.9		4.1	0.153		0.161
Р	7.9		8.1	0.311		0.319



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