

12- and 14-Bit Hybrid Synchro/ Resolver-to-Digital Converters

SDC/RDC1740/1741/1742

FEATURES

Internal Isolating Transformers Military Temperature Range Three Accuracy Options 14-Bit or 12-Bit Resolution High, Continuous Tracking Rate 32-Pin Welded Metal Package Hermetically Sealed Ratiometric Conversion Laser Trimmed – No External Adjustment Three-State Latched Outputs

APPLICATIONS

Flight Instrumentation Systems Military Servo Control Systems Artillery Fire Control Systems Avionic Systems Antenna Monitoring Robotics Engine Controllers Coordinate Conversion Axis Transformation CNC Machine Tooling Process Control

GENERAL DESCRIPTION

The SDC/RDC1740/1741/1742 are hybrid 14- or 12-bit continuous tracking synchro or resolver to digital converters contained in 32-pin welded metal packages. In the core of this hybrid the conversion process is performed by a monolithic IC manufactured in Analog Devices proprietary BiMOS II process that combines the advantages of CMOS logic and bipolar high accuracy linear circuits on the same chip. Internal isolating microtransformers are used to provide true isolation of the signal and reference inputs. The 14- or 12-bit digital word is in a threestate digital form available in two bytes. Using separate ENABLE inputs for the most significant 8 bits and the least significant 6 or 4 bits not only simplifies multiplexing of more than one device onto a single data bus, but also enables the **INHIBIT** input to be used without interrupting the operation of the tracking loop. The converters are hermetically sealed in a 32-pin welded metal package.



Functional Diagram of the SDC/RDC1740/1741/1742

MODELS AVAILABLE

The three synchro/resolver-to-digital converters described in this data sheet differ primarily in the areas of resolution, accuracy and dynamic performance as follows:

Model SDC1740XYZ is a 14-bit converter with an overall accuracy of ± 5.3 arc minutes and a resolution of 1.3 arc minutes.

Model SDC1741XYZ is a 12-bit converter with an overall accuracy of ± 15.3 arc minutes and a resolution of 5.3 arc minutes.

Model SDC1742XYZ is a 12-bit converter with an overall accuracy of ± 8.5 arc minutes and a resolution of 5.3 arc minutes.

Each model has two operating temperature range versions, those covering the industrial temperature range (0 to $+70^{\circ}$ C) and the military temperature range (-55° C to $+125^{\circ}$ C). The XYZ code defines the option as follows: (X) signifies the operating temperature range, (Y) signifies the reference frequency, (Z) signifies the signal and reference voltage whether it will accept synchro or resolver format. To ensure a high level of reliability each converter receives stringent precap visual inspection, environmental screening and final electrical test.

Military temperature range devices and those processed to high reliability screening standards (suffix B) receive further levels of testing and screening to ensure high levels of reliability. More information about the option codes is given under the heading Ordering Information.

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SPECIFICATIONS (typical at 25°C unless otherwise specified)

Parameter	SDC/RDC1740	SDC/RDC1741	SDC/RDC1742	Units	Comments	Notes
CONVERTER PERFORMANCE						
Accuracy	±5.3 max	±15.3 max	$\pm 8.5 \text{ max}$	arc min		1, 3
Tracking Rate	27 min	18 min	**	rev/s		4
Resolution	14	12	**	Bits	Output Coding Parallel	
	(1 LSB = 1.3)	(1 LSB = 5.3	**		Natural Binary	
	arc min)	arc min)				
Signal & Reference Frequency	400	*	*	Hz	Option X1Z	
	2.6	*	*	kHz	Option X4Z	
Repeatability of Position Output	1	*	*	LSB		4
Bandwidth	130	150	**	Hz		4
SIGNAL INPUT IMPEDANCE						
90V Signal	200	*	*	kΩ	Resistive Tolerance ±2%	4
26V Signal	57.7	*	*	kΩ		4
11.8V Signal	26	*	*	kΩ		4
REFERENCE INPUTS		1				
Reference Voltage	11.8, 26, 115	*	*	V rms	See Ordering	
Reference Impedance	, 20, 115				Information	
115V Ref	120	*	*	kΩ	Resistive Tolerance ±5%	4
26V Ref	27	*	*	kΩ		4
11.8V Ref	12.3	*	*	kΩ		4
	56000	80000	**	sec ⁻²	Symbol K _a	4
ACCELERATION CONSTANT			**			
LARGE STEP RESPONSE	85 typ 100 max	60 typ 75 max	**	ms ms	179° Step for Settling to 1 LSB of Error	1, 3
DOWED I DIES						
POWER LINES	20	*	*	mA	Quiescent Condition	1, 3
$+V_{s} = +15V$	28 typ 35 max	*	*		Quiescent Condition	1, 3
$-V_s = -15V$	28 typ 35 max	*	*	mA		
$V_L = +5V$	35 typ 56 max	*	*	mA W	Quiescent Condition	1, 3
Power Dissipation	1.4 max			w		
DIGITAL INPUTS (INHIBIT,						
ENABLE L, ENABLE M)						
V (Input High)	2 min	*	*	V dc	$V_L = +5V$	1, 3
V (Input Low)	0.7 max	*	*	V dc	$V_L = +5V$	1, 3
I (Input High)	20 max	*	*	μA	$V_{IH} = 2.4V$	1, 3
I (Input Low)	-400 max	*	*	μA	$V_{IL}=0.4V$	1, 3
ENABLE AND DISABLE TIME	80 max	*	*	ns		2, 4
INHIBIT						
Sense	Logic Low	*	*			
	to INHIBIT	*	*			
Time to Data Stable (after						
Negative-Going Edge						
of INHIBIT)	640 max	*	*	ns		4
BUSY OUTPUT						
Sense	Active Logic Hig	h when converter p	osition output chan	ging.		
Timing		dge 50ns before cha				
Width						
	400 typ	*	*	ns		1, 3
	200 min	*	*	ns		1, 3
	600 max	*	*	ns		1, 3
Load	2 min	*	*	TTL		4
DIGITAL OUTPUTS						
Voltage Levels						
Logic High	2.4 min	*	*	V dc	$V_{L} = +5V,$	1, 3
LOGIC MIGH	2.,				$I_{OH} = -240 \mu A$	
Logic Low	0.4 max	*	*	V dc	$V_L = +5V$	1, 3
LOGIC LOW	VIT IIIUA				$I_{OL} = 9.6 \text{mA}$	-,-
		1				

Parameter	SDC/RDC1740	SDC/RDC1741	SDC/RDC1742	Units	Comments	Notes
OPERATING TEMPERATURE RANGE						
Option 5YZ	0 to + 70	*	*	°C		
Option 4YZ	-55 to +125	*	*	°C		
DIMENSIONS	1.74×1.14×0.28	*	*	Inch	See Package	4
	(44.2×28.9×7.1)	*	*	mm	Information	
WEIGHT	0.86 max	*	*	oz		4
	25 max	*	*	grams		

NOTES

¹Specified over the appropriate operating temperature range and for: (a) $\pm 10\%$ signal and reference amplitude variation; (b) $\pm 10\%$ signal and reference harmonic distortion; (c) $\pm 5\%$ power supply variation; (d) $\pm 10\%$ variation in reference frequency.

²ENABLE M enables most significant 8 bits.

ENABLE L enables least significant 4 bits (or 6 bits for SDC/RDC1740).

³100% tested at nominal values of power supplies, input signal voltages and operating frequency.

⁴Guaranteed by design.

*Specifications same as SDC/RDC1740.

**Specifications same as SDC/RDC1741.

Specifications subject to change without notice.

ABSOLUTE MAXIMUM RATINGS

CAUTION:

 $^1\text{Correct}$ polarity voltages must be maintained on the $+V_s$ and $-V_s$ pins. ^2The +5V power supply must never go below GND potential.

NOTE

Absolute maximum ratings are those values beyond which damage to the device may occur.

ORDERING INFORMATION

For full definition, the converter part number should be suffixed by an option code. All the standard options and their option codes are shown below. For options not shown, please consult Analog Devices.





PIN FUNCTION DESCRIPTION

Pin	Mnemonic	Description
1-14	Bit 1-14 (1740)	Parallel output data bits.
1-12	Bit 1-12 (1741/1742)	
15 16	REF LO REF HI	Input pins for the reference signal.
17	S4 OR N/C	S4 signal input for Resolver option. N/C for Synchro option.
18	\$3	
19 20	S2 S1	Synchro/Resolver input signals.
21	N/C	No Connection.
22	N/C	No Connection.
23	CASE	Should be connected to 0V GND.
24	N/C	No Connection.
25	ENABLE L	ENABLE L enables the 6 or 4 least significant bits.
26	ENABLE M	ENABLE M enables the 8 most significant bits. Logic High sets the output data bits to a high impedance state; a Logic Low presents the data in the latches to the output pins.
27	BUSY	Converter busy. A Logic High output indicates that the output latches are being updated and data should not be transferred.
28	INHIBIT	Logic Low inhibits the data transfer from the counter to the output latches.
29	$+V_{S}$	Main positive power supply.
30	0V GND	Power supply ground.
31	$-V_s$	Main negative power supply.
32	$+V_L$	Logic power supply.

Table I. Bit Weight Table

0.0439

0.0220

13

14 (LSB for 1740)



14- OR 12-BIT DIGITAL OUTPUT WORD

Figure 1. Functional Diagram of the SDC/RDC1740/1741/1742

THEORY OF OPERATION

In the synchro-to-digital converter configuration, the 3-wire synchro output should be connected to S1, S2 and S3 on the unit and the Scott T transformer pair will convert these signals into resolver format, i.e.,

$V_1 = K$	Eo	sin	ωt	sin	θ	(SIN)
$V_2 = K$	Eo	sin	ωt	cos	θ	(COS)

where θ is the angle of the synchro shaft.

In the resolver-to-digital converter configuration, the 4-wire resolver output should be connected to S1, S2, S3 and S4 on the unit and the transformers will act purely as isolators.

To understand the conversion process, then assume that the current word state of the up-down counter is ϕ .

 V_1 is multiplied by COS ϕ and V_2 is multiplied by SIN ϕ to give:

K E_O sin ω t sin θ cos ϕ

and K $E_0 \sin \omega t \cos \theta \sin \phi$.

These signals are subtracted by the error amplifier to give:

K E_O sin ωt (sin θ cos ϕ -cos θ sin ϕ) or K E_O sin ωt sin (θ - ϕ).

A phase sensitive detector, integrator and voltage controlled oscillator (VCO) form a closed loop system which seeks to null $\sin(\theta-\phi)$. The digital output (counter ϕ), then represents the synchro/resolver shaft angle θ within the specified accuracy of the converter.

INHIBIT INPUT

The INHIBIT logic input only inhibits the data transfer from the up-down counter to the output latches and, therefore, does not interrupt the operation of the tracking loop. Releasing the INHIBIT automatically generates a busy pulse to refresh the output data.

ENABLE INPUTS

The $\overline{\text{ENABLE}}$ inputs determine the state of the output data. A Logic High maintains the output data pins in the high impedance condition, and application of a Logic Low presents the data in the latches to the output pins. $\overline{\text{ENABLE M}}$ enables the most significant 8 bits, while $\overline{\text{ENABLE L}}$, enables the least significant 4 bits (6 bits in the SDC/RDC1740). The operation of the $\overline{\text{ENABLE}}$ inputs has no effect on the conversion process.

DATA TRANSFER

Data transfer can be accomplished using either the INHIBIT input or the trailing edge, positive to negative transition of the BUSY pulse output.

The data will be valid 640ns after the application of a Logic Lo to the $\overline{INHIBIT}$ input. This is regardless of the time when the $\overline{INHIBIT}$ is applied and allows time for an active busy pulse to clear. By using the $\overline{ENABLE M}$ and $\overline{ENABLE L}$ inputs the two bytes of data can be transferred after which the $\overline{INHIBIT}$ should be returned to a Logic Hi state to enable the output latches to be updated.



Figure 2. Timing Diagram

BUSY OUTPUT

The validity of the output data is indicated by the state of the BUSY output. When the input to the converter is changing, the signal appearing on the BUSY output is a series of pulses at TTL levels. A BUSY is initiated each time the input moves by an analog equivalent of an LSB and the internal counter is incremented or decremented or the INHIBIT input is released.

Typically the width of the BUSY pulse is 400ns during the position data output updates. The trailing edge, positive to negative transition, of the BUSY pulse indicates that the position data output has been updated and is ready for transfer (data valid). The maximum load on the BUSY output using the trailing edge of the BUSY pulse is 2 TTL loads.

CONNECTING THE CONVERTER

The power supply voltages connected to $+V_S$ and $-V_S$ pins should be $\pm 15V$ and must not be reversed. The digital logic supply V_L is connected to +5V.

It is suggested that a parallel combination of a 0.1μ F ceramic and a 6.8μ F electrolytic capacitor is placed from each of the three supply pins to GND.

The pin marked CASE is connected electrically to the case and should be taken to a convenient zero volt potential in the system.

The digital output is taken from Pin 1 through to Pin 12 for the SDC/RDC1741/1742 and Pin 1 through to Pin 14 for the SDC/RDC1740 where Pin 1 is the MSB.

The reference connections are made to REF HI and REF LO. In the case of a synchro, the signals are connected to S1, S2 and S3 according to the following convention:

 $E_{S1-S3} = E_{RLO-RHI} \sin \omega t \sin \theta$

 $E_{S3-S2} = E_{RLO-RHI} \sin \omega t \sin (\theta + 120^{\circ})$

 $E_{S2-S1} = E_{RLO-RHI} \sin \omega t \sin (\theta + 240^{\circ})$

For a resolver, the signals are connected to S1, S2, S3 and S4 according to the following convention:

 $E_{S1-S3} = E_{RLO-RHI} \sin \omega t \sin \theta$

 $E_{S2-S4} = E_{RHI-RLO} \sin \omega t \cos \theta$

The BUSY, **INHIBIT** and **ENABLE** pins should be connected as described under the heading Data Transfer.

RESISTIVE SCALING OF INPUTS

A feature of these converters is that the signal and reference inputs can be resistively scaled to accommodate any change of input signal and reference voltages.

This means that a standard converter can be used with a personality card in systems where a wide range of input and reference voltages are encountered.

Note: The accuracy of the converter will be affected by the matching accuracies of resistors used for external scaling.

To calculate the values of the external scaling resistors in the case of a synchro converter, add $1.11k\Omega$ per extra volt of signal in series with S1, S2 and S3 and $1k\Omega$ per extra volt of reference

in series with RHI. In the case of a resolver-to-digital converter, add $2.22k\Omega$ in series with S1 and S2 per extra volt of signal and $1k\Omega$ per extra volt of reference in series with RHI.

DYNAMIC PERFORMANCE

The transfer function of the converter is given below.



Figure 3. Transfer Function of SDC/RDC1740/1741/1742

Open loop gain:

 $\frac{\theta_{OUT}}{\theta_{IN}}\,=\,\frac{K_a}{S^2}\cdot\frac{1\!+\!ST_1}{1\!+\!ST_2}$

Closed loop gain:

$$\frac{\theta_{OUT}}{\theta_{IN}} = \frac{1 + ST_1}{1 + ST_1 + \frac{S^2}{K_a} + \frac{S^3T_2}{K_a}}$$

Model SDC/RDC1740

Where $K_a = 56,000$ T1=0.01 T2=0.001525

The gain and phase diagrams are shown in Figures 4 and 5.

Model SDC/RDC1741/1742

Where $K_a = 80,000$ T1=0.0087 T2=0.001569

The gain and phase diagrams are shown in Figures 6 and 7.

ACCELERATION ERROR

A tracking converter employing a type 2 servo loop does not suffer any velocity lag, however, there is an additional error due to acceleration. This additional error can be defined using the acceleration constant K_a of the converter.

 $K_a = \frac{Input \ Acceleration}{Error \ in \ Output \ Angle}$

The numerator and denominator have the same units. K_a does not define maximum acceleration, only the error due to acceleration, maximum acceleration is in the region of 5 times the K_a figure. The following is an example using the K_a of the SDC1740.

Acceleration of 50 revolutions \sec^{-2} with $K_a = 56000$

Error in LSBs =
$$\frac{50 \times 16384}{56000}$$
 = 14.62LSBs



70 85 100 TEMPERATURE - °C Figure 8. SDC/RDC1740/41/42 MTBF Curve

55

40

32

0

25

As an example of the Mean Time Between Failures (MTBF) calculated according to MIL-HDBK-217E, Figure 8 shows the MTBF in years versus case temperature in naval sheltered conditions for SDC/RDC1740/41/42.

125

C811a-20-6/89

OUTLINE DIMENSIONS

Dimensions shown in inches and (mm).



STANDARD PROCESSING (5YZ OPTION)

As part of the standard manufacturing procedure, all converters receive the following processing:

Process

Conditions

1. Preseal Burn In 2. Precap Visual Inspection 64 hrs at +125°C In-house criteria

- In-house criteria 3. Seal Test, Fine and Gross Performed at +25°C
- 4. Final Electrical Test

Extended temperature range versions receive additional processing as follows:

Final Electrical Test

Performed at max and min operating temperatures

OTHER PRODUCTS

Many other hybrid products concerned with the conversion of synchro data are manufactured by Analog Devices, some of which are listed below. If you have any questions about our products or require advice about their use for a particular application, please contact our Applications Engineering Department.

The SDC/RDC1767 and SDC/RDC1768 are hybrid synchroto-digital converters with isolating microtransformers similar to the SDC/RDC1740/41/42 described on this data sheet with the additional features of analog velocity output and dc error output.

The OSC1758 is a hybrid sine/cosine power oscillator which can provide a maximum power output of 1.5 watts, over a frequency range of 0 to 10kHz.

The DRC1745 and DRC1746 are 14- and 16-bit natural binary latched output hybrid digital-to-resolver converters. The accuracies available are ± 2 and ± 4 arc mins, and the outputs can supply 2VA at 7V rms.

PROCESSING FOR HIGH RELIABILITY

Process	Conditions
1. Preseal Burn In	64 hrs at +125°C
2. Precap Visual Inspection	2017
3. Temperature Cycling	10 Cycles, -65°C to +150°C
4. Constant Acceleration	5000G, Y1 Plane
5. Interim Electrical Tests	
6. Operating Burn In	96 hours @ +125°C
7. Seal Test, Fine and Gross	1014
8. Final Electrical Testing	Performed at T _{min} , T _{ambient}
(Group A)	and T _{max}
9. External Visual Inspection	2009

NOTE

Test and screening data can be supplied. Further information on request.