

PCA9517A Level translating I²C-bus repeater Rev. 02 — 5 May 2008

1. General description

The PCA9517A is a CMOS integrated circuit that provides level shifting between low voltage (down to 0.9 V) and higher voltage (2.7 V to 5.5 V) I²C-bus or SMBus applications. While retaining all the operating modes and features of the I²C-bus system during the level shifts, it also permits extension of the I²C-bus by providing bidirectional buffering for both the data (SDA) and the clock (SCL) lines, thus enabling two buses of 400 pF. Using the PCA9517A enables the system designer to isolate two halves of a bus for both voltage and capacitance. The SDA and SCL pins are overvoltage tolerant and are high-impedance when the PCA9517A is unpowered.

The 2.7 V to 5.5 V bus port B drivers behave much like the drivers on the PCA9515A device, while the adjustable voltage bus port A drivers drive more current and eliminate the static offset voltage. This results in a LOW on the port B translating into a nearly 0 V LOW on the port A which accommodates smaller voltage swings of lower voltage logic.

The static offset design of the port B PCA9517A I/O drivers prevent them from being connected to another device that has rise time accelerator including the PCA9510, PCA9511, PCA9512, PCA9513, PCA9514, PCA9515A, PCA9516A, PCA9517A (port B), or PCA9518. Port A of two or more PCA9517As can be connected together, however, to allow a star topography with port A on the common bus, and port A can be connected directly to any other buffer with static or dynamic offset voltage. Multiple PCA9517As can be connected in series, port A to port B, with no build-up in offset voltage with only time of flight delays to consider.

The PCA9517A drivers are not enabled unless V_{CC(A)} is above 0.8 V and V_{CC(B)} is above 2.5 V. The EN pin can also be used to turn the drivers on and off under system control. Caution should be observed to only change the state of the enable pin when the bus is idle.

The output pull-down on the port B internal buffer LOW is set for approximately 0.5 V, while the input threshold of the internal buffer is set about 70 mV lower (0.43 V). When the port B I/O is driven LOW internally, the LOW is not recognized as a LOW by the input. This prevents a lock-up condition from occurring. The output pull-down on port A drives a hard LOW and the input level is set at $0.3V_{CC(A)}$ to accommodate the need for a lower LOW level in systems where the low voltage side supply voltage is as low as 0.9 V.

Table 1. PCA9517 and PCA9517A comparison

Parameter	PCA9517[1]	PCA9517A ^[2]
electrostatic discharge, HBM	> 2 kV	> 5.5 kV
electrostatic discharge, MM	> 200 V	> 450 V

[1] Will continue to be supported for existing designs and new designs where migrating to the PCA9517A is not possible.

[2] Highly recommended for all new designs due to improved I²C-bus operation and ESD performance.



Level translating I²C-bus repeater

2. Features

- 2 channel, bidirectional buffer isolates capacitance and allows 400 pF on either side of the device
- Voltage level translation from 0.9 V to 5.5 V and from 2.7 V to 5.5 V
- Footprint and functional replacement for PCA9515/15A
- I²C-bus and SMBus compatible
- Active HIGH repeater enable input
- Open-drain input/outputs
- Lock-up free operation
- Supports arbitration and clock stretching across the repeater
- Accommodates Standard-mode and Fast-mode I²C-bus devices and multiple masters
- Powered-off high-impedance I²C-bus pins
- Port A operating supply voltage range of 0.9 V to 5.5 V
- Port B operating supply voltage range of 2.7 V to 5.5 V
- 5 V tolerant I²C-bus and enable pins
- 0 Hz to 400 kHz clock frequency (the maximum system operating frequency may be less than 400 kHz because of the delays added by the repeater)
- ESD protection exceeds 5500 V HBM per JESD22-A114, 450 V MM per JESD22-A115, and 1000 V CDM per JESD22-C101
- Latch-up testing is done to JEDEC Standard JESD78 which exceeds 100 mA
- Packages offered: SO8 and TSSOP8

3. Ordering information

Table 2. Ordering information

Type number	Topside	Package	3				
	mark	Name	Description	Version			
PCA9517AD	PA9517A	SO8	plastic small outline package; 8 leads; body width 3.9 mm	SOT96-1			
PCA9517ADP	9517A	TSSOP8 ^[1]	plastic thin shrink small outline package; 8 leads; body width 3 mm $$	SOT505-1			

[1] Also known as MSOP8.

Level translating I²C-bus repeater

4. Functional diagram



5. Pinning information

5.1 Pinning



5.2 Pin description

Table 3.	Pin description	
Symbol	Pin	Description
V _{CC(A)}	1	port A supply voltage (0.9 V to 5.5 V)
SCLA	2	serial clock port A bus
SDAA	3	serial data port A bus
GND	4	supply ground (0 V)
EN	5	active HIGH repeater enable input
SDAB	6	serial data port B bus
SCLB	7	serial clock port B bus
V _{CC(B)}	8	port B supply voltage (2.7 V to 5.5 V)

6. Functional description

Refer to Figure 1 "Functional diagram of PCA9517A".

The PCA9517A enables I²C-bus or SMBus translation down to $V_{CC(A)}$ as low as 0.9 V without degradation of system performance. The PCA9517A contains two bidirectional open-drain buffers specifically designed to support up-translation/down-translation between the low voltage (as low as 0.9 V) and a 3.3 V or 5 V I²C-bus or SMBus. All inputs and I/Os are overvoltage tolerant to 5.5 V even when the device is unpowered ($V_{CC(B)}$ and/or $V_{CC(A)} = 0$ V). The PCA9517A includes a power-up circuit that keeps the output drivers turned off until $V_{CC(B)}$ is above 2.5 V and the $V_{CC(A)}$ is above 0.8 V. $V_{CC(B)}$ and V_{CC(A)} can be applied in any sequence at power-up. After power-up and with the enable (EN) HIGH, a LOW level on port A (below 0.3V_{CC(A)}) turns the corresponding port B driver (either SDA or SCL) on and drives port B down to about 0.5 V. When port A rises above 0.3V_{CC(A)}, the port B pull-down driver is turned off and the external pull-up resistor pulls the pin HIGH. When port B falls first and goes below $0.3V_{CC(B)}$ the port A driver is turned on and port A pulls down to 0 V. The port B pull-down is not enabled unless the port B voltage goes below 0.4 V. If the port B low voltage does not go below 0.5 V, the port A driver will turn off when port B voltage is above 0.7V_{CC(B)}. If the port B low voltage goes below 0.4 V, the port B pull-down driver is enabled and port B will only be able to rise to 0.5 V until port A rises above 0.3V_{CC(A)}, then port B will continue to rise being pulled up by the external pull-up resistor. The $V_{CC(A)}$ is only used to provide the $0.3V_{CC(A)}$ reference to the port A input comparators and for the power good detect circuit. The PCA9517A logic and all I/Os are powered by the V_{CC(B)} pin.

6.1 Enable

The EN pin is active HIGH with an internal pull-up to $V_{CC(B)}$ and allows the user to select when the repeater is active. This can be used to isolate a badly behaved slave on power-up until after the system power-up reset. It should never change state during an I²C-bus operation because disabling during a bus operation will hang the bus and enabling part way through a bus cycle could confuse the I²C-bus parts being enabled.

The enable pin should only change state when the global bus and the repeater port are in an idle state to prevent system failures.

6.2 I²C-bus systems

As with the standard I²C-bus system, pull-up resistors are required to provide the logic HIGH levels on the buffered bus (standard open-collector configuration of the I²C-bus). The size of these pull-up resistors depends on the system, but each side of the repeater must have a pull-up resistor. This part designed to work with Standard mode and Fast mode I²C-bus devices in addition to SMBus devices. Standard mode I²C-bus devices only specify 3 mA output drive; this limits the termination current to 3 mA in a generic I²C-bus system where Standard-mode devices and multiple masters are possible. Under certain conditions higher termination currents can be used.

Please see Application Note *AN255, I²C/SMBus Repeaters, Hubs and Expanders* for additional information on sizing resistors and precautions when using more than one PCA9517A in a system or using the PCA9517A in conjunction with other bus buffers.

7. Application design-in information

A typical application is shown in Figure 4. In this example, the system master is running on a 3.3 V I^2 C-bus while the slave is connected to a 1.2 V bus. Both buses run at 400 kHz. Master devices can be placed on either bus.



The PCA9517A is 5 V tolerant, so it does not require any additional circuitry to translate between 0.9 V to 5.5 V bus voltages and 2.7 V to 5.5 V bus voltages.

When port A of the PCA9517A is pulled LOW by a driver on the I²C-bus, a comparator detects the falling edge when it goes below $0.3V_{CC(A)}$ and causes the internal driver on port B to turn on, causing port B to pull down to about 0.5 V. When port B of the PCA9517A falls, first a CMOS hysteresis type input detects the falling edge and causes the internal driver on port A to turn on and pull the port A pin down to ground. In order to illustrate what would be seen in a typical application, refer to Figure 8 and Figure 9. If the bus master in Figure 4 were to write to the slave through the PCA9517A, waveforms shown in Figure 8 would be observed on the A bus. This looks like a normal I²C-bus transmission except that the HIGH level may be as low as 0.9 V, and the turn on and turn off of the acknowledge signals are slightly delayed.

On the B bus side of the PCA9517A, the clock and data lines would have a positive offset from ground equal to the V_{OL} of the PCA9517A. After the 8th clock pulse, the data line will be pulled to the V_{OL} of the slave device which is very close to ground in this example. At the end of the acknowledge, the level rises only to the LOW level set by the driver in the PCA9517A for a short delay while the A bus side rises above $0.3V_{CC(A)}$ then it continues HIGH. It is important to note that any arbitration or clock stretching events require that the LOW level on the B bus side at the input of the PCA9517A (V_{IL}) be at or below 0.4 V to be recognized by the PCA9517A and then transmitted to the A bus side.

Multiple PCA9517A port A sides can be connected in a star configuration (Figure 5), allowing all nodes to communicate with each other.

Multiple PCA9517As can be connected in series (Figure 6) as long as port A is connected to port B. I²C-bus slave devices can be connected to any of the bus segments. The number of devices that can be connected in series is limited by repeater delay/time-of-flight considerations on the maximum bus speed requirements.

Level translating I²C-bus repeater





Product data sheet

Level translating l²C-bus repeater









Level translating I²C-bus repeater

8. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
V _{CC(B)}	supply voltage port B	2.7 V to 5.5 V	-0.5	+7	V
V _{CC(A)}	supply voltage port A	adjustable	-0.5	+7	V
V _{I/O}	voltage on an input/output pin	port B; enable pin (EN)	-0.5	+7	V
I _{I/O}	input/output current	port A; port B	-	50	mA
l _l	input current	$EN,V_{CC(A)},V_{CC(B)},GND$	-	50	mA
P _{tot}	total power dissipation		-	100	mW
T _{stg}	storage temperature		-55	+125	°C
T _{amb}	ambient temperature	operating in free air	-40	+85	°C
Тj	junction temperature		-	+125	°C

9. Static characteristics

Table 5. Static characteristics

 V_{CC} = 2.7 V to 5.5 V; GND = 0 V; T_{amb} = -40 °C to +85 °C; unless otherwise specified.

Symbol	Parameter	Conditions		Min	Тур	Max	Unit
Supplies							
V _{CC(B)}	supply voltage port B			2.7	-	5.5	V
V _{CC(A)}	supply voltage port A		<u>[1]</u>	0.9	-	5.5	V
I _{CC(VCC(A))}	supply current on pin $V_{CC(A)}$			-	-	1	mA
I _{CCH}	HIGH-level supply current	both channels HIGH; V _{CC} = 5.5 V; SDAn = SCLn = V _{CC}		-	1.5	5	mA
I _{CCL}	LOW-level supply current	both channels LOW; $V_{CC} = 5.5 V$; one SDA and one SCL = GND; other SDA and SCL open		-	1.5	5	mA
I _{CC(A)c}	contention port A supply current	$V_{CC} = 5.5 V;$ SDAn = SCLn = V_{CC}		-	1.5	5	mA
Input and	output SDAB and SCLB						
V _{IH}	HIGH-level input voltage			$0.7V_{CC(B)}$	-	5.5	V
V _{IL}	LOW-level input voltage		[2]	-0.5	-	$+0.3V_{CC(B)}$	V
V _{ILc}	contention LOW-level input voltage			-0.5	0.4	-	V
V _{IK}	input clamping voltage	$I_{I} = -18 \text{ mA}$		-	-	-1.2	V
I _{LI}	input leakage current	V _I = 3.6 V		-	-	±1	μΑ
IIL	LOW-level input current	SDA, SCL; $V_I = 0.2 V$		-	-	10	μΑ
V _{OL}	LOW-level output voltage	I_{OL} = 100 μ A or 6 mA		0.47	0.52	0.6	V
V _{OL} -V _{ILc}	difference between LOW-level output and LOW-level input voltage contention	guaranteed by design		-	-	70	mV
I _{LOH}	HIGH-level output leakage current	V _O = 3.6 V		-	-	10	μA
Cio	input/output capacitance	$V_I = 3 V \text{ or } 0 V; V_{CC} = 3.3 V$		-	6	7	pF
		$V_I = 3 V \text{ or } 0 V; V_{CC} = 0 V$		-	6	7	pF
Input and	output SDAA and SCLA						
V _{IH}	HIGH-level input voltage			0.7V _{CC(A)}	-	5.5	V
V _{IL}	LOW-level input voltage		[3]	-0.5	-	+0.3V _{CC(A)}	V
V _{IK}	input clamping voltage	I _I = -18 mA		-	-	-1.2	V
ILI	input leakage current	V _I = 3.6 V		-	-	±1	μΑ
IIL	LOW-level input current	SDA, SCL; $V_I = 0.2 V$		-	-	10	μΑ
V _{OL}	LOW-level output voltage	I _{OL} = 6 mA		-	0.1	0.2	V
I _{LOH}	HIGH-level output leakage current	V _O = 3.6 V		-	-	10	μA
Cio	input/output capacitance	V_I = 3 V or 0 V; V_{CC} = 3.3 V		-	6	7	pF
		$V_I = 3 V \text{ or } 0 V; V_{CC} = 0 V$		-	6	7	pF

Level translating I²C-bus repeater

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Symbol	Parameter	Conditions	Min	Тур	Max	Unit
Enable						
V _{IL}	LOW-level input voltage		-0.5	-	+0.3V _{CC(B)}	V
V _{IH}	HIGH-level input voltage		0.7V _{CC(B)}	-	5.5	V
I _{IL(EN)}	LOW-level input current on pin EN	V_{I} = 0.2 V, EN; V_{CC} = 3.6 V	-	-10	-30	μA
ILI	input leakage current		-1	-	+1	μΑ
Ci	input capacitance	$V_{I} = 3.0 V \text{ or } 0 V$	-	6	7	pF
· · · · · · · · · · · · · · · · · · ·						

Table 5. Static characteristics ...continued

 V_{CC} = 2.7 V to 5.5 V; GND = 0 V; T_{amb} = -40 °C to +85 °C; unless otherwise specified.

[1] LOW-level supply voltage.

[2] V_{IL} specification is for the first LOW level seen by the SDAB/SCLB lines. V_{ILc} is for the second and subsequent LOW levels seen by the SDAB/SCLB lines.

[3] V_{IL} for port A with envelope noise must be below $0.3V_{CC(A)}$ for stable performance.

10. Dynamic characteristics

Table 6.Dynamic characteristics

 $V_{CC} = 2.7 \text{ V}$ to 5.5 V; GND = 0 V; $T_{amb} = -40 \text{ °C}$ to +85 °C; unless otherwise specified.[1][2]

Symbol	Parameter	Conditions		Min	Typ <mark>[3]</mark>	Max	Unit
t _{PLH}	LOW-to-HIGH propagation delay	port B to port A; Figure 12	[4]	100	170	250	ns
t _{PHL}	HIGH-to-LOW propagation delay	port B to port A; Figure 10					
		$V_{CC(A)} \leq 2.7 \text{ V}$	[5]	30	80	110	ns
		$V_{CC(A)} \ge 3 V$		10	66	300	ns
t _{TLH}	LOW to HIGH output transition time	port A; Figure 10		10	20	30	ns
t _{THL}	HIGH to LOW output transition time	port A; Figure 10					
		$V_{CC(A)} \le 2.7 V$	[5]	1	77	105	ns
		$V_{CC(A)} \ge 3 V$		20	70	175	ns
t _{PLH}	LOW-to-HIGH propagation delay	port A to port B; Figure 11	[6]	25	53	110	ns
t _{PHL}	HIGH-to-LOW propagation delay	port A to port B; Figure 11	[6]	60	79	230	ns
t _{TLH}	LOW to HIGH output transition time	port B; Figure 11		120	140	170	ns
t _{THL}	HIGH to LOW output transition time	port B; Figure 11		30	48	90	ns
t _{su}	set-up time	EN HIGH before START condition	[7]	100	-	-	ns
t _h	hold time	EN HIGH after STOP condition	[7]	100	-	-	ns

[1] Times are specified with loads of 1.35 kΩ pull-up resistance and 57 pF load capacitance on port B, and 167 Ω pull-up resistance and 57 pF load capacitance on port A. Different load resistance and capacitance will alter the RC time constant, thereby changing the propagation delay and transition times.

[2] Pull-up voltages are $V_{CC(A)}$ on port A and $V_{CC(B)}$ on port B.

[3] Typical values were measured with V_{CC(A)} = 3.3 V at T_{amb} = 25 °C, unless otherwise noted.

[4] The t_{PLH} delay data from port B to port A is measured at 0.5 V on port B to 0.5V_{CC(A)} on port A when V_{CC(A)} is less than 2 V, and 1.5 V on port A if V_{CC(A)} is greater than 2 V.

[5] Typical value measured with $V_{CC(A)} = 2.7$ V at $T_{amb} = 25$ °C.

[6] The proportional delay data from port A to port B is measured at $0.3V_{CC(A)}$ on port A to 1.5 V on port B.

[7] The enable pin, EN, should only change state when the global bus and the repeater port are in an idle state.

Level translating I²C-bus repeater

10.1 AC waveforms



11. Test information



Level translating I²C-bus repeater

12. Package outline



Fig 14. Package outline SOT96-1 (SO8) PCA9517A_2

Level translating I²C-bus repeater



Fig 15. Package outline SOT505-1 (TSSOP8)

13. Soldering of SMD packages

This text provides a very brief insight into a complex technology. A more in-depth account of soldering ICs can be found in Application Note *AN10365 "Surface mount reflow soldering description"*.

13.1 Introduction to soldering

Soldering is one of the most common methods through which packages are attached to Printed Circuit Boards (PCBs), to form electrical circuits. The soldered joint provides both the mechanical and the electrical connection. There is no single soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and Surface Mount Devices (SMDs) are mixed on one printed wiring board; however, it is not suitable for fine pitch SMDs. Reflow soldering is ideal for the small pitches and high densities that come with increased miniaturization.

13.2 Wave and reflow soldering

Wave soldering is a joining technology in which the joints are made by solder coming from a standing wave of liquid solder. The wave soldering process is suitable for the following:

- Through-hole components
- Leaded or leadless SMDs, which are glued to the surface of the printed circuit board

Not all SMDs can be wave soldered. Packages with solder balls, and some leadless packages which have solder lands underneath the body, cannot be wave soldered. Also, leaded SMDs with leads having a pitch smaller than ~0.6 mm cannot be wave soldered, due to an increased probability of bridging.

The reflow soldering process involves applying solder paste to a board, followed by component placement and exposure to a temperature profile. Leaded packages, packages with solder balls, and leadless packages are all reflow solderable.

Key characteristics in both wave and reflow soldering are:

- Board specifications, including the board finish, solder masks and vias
- · Package footprints, including solder thieves and orientation
- The moisture sensitivity level of the packages
- Package placement
- Inspection and repair
- Lead-free soldering versus SnPb soldering

13.3 Wave soldering

Key characteristics in wave soldering are:

- Process issues, such as application of adhesive and flux, clinching of leads, board transport, the solder wave parameters, and the time during which components are exposed to the wave
- · Solder bath specifications, including temperature and impurities

13.4 Reflow soldering

Key characteristics in reflow soldering are:

- Lead-free versus SnPb soldering; note that a lead-free reflow process usually leads to higher minimum peak temperatures (see <u>Figure 16</u>) than a SnPb process, thus reducing the process window
- Solder paste printing issues including smearing, release, and adjusting the process window for a mix of large and small components on one board
- Reflow temperature profile; this profile includes preheat, reflow (in which the board is heated to the peak temperature) and cooling down. It is imperative that the peak temperature is high enough for the solder to make reliable solder joints (a solder paste characteristic). In addition, the peak temperature must be low enough that the packages and/or boards are not damaged. The peak temperature of the package depends on package thickness and volume and is classified in accordance with Table 7 and 8

Table 7. SnPb eutectic process (from J-STD-020C)

Package thickness (mm)	Package reflow temperature (°C)			
	Volume (mm ³)			
	< 350	≥ 350		
< 2.5	235	220		
≥ 2.5	220	220		

Table 8. Lead-free process (from J-STD-020C)

Package thickness (mm)	Package reflow temperature (°C)				
	Volume (mm ³)				
	< 350	350 to 2000	> 2000		
< 1.6	260	260	260		
1.6 to 2.5	260	250	245		
> 2.5	250	245	245		

Moisture sensitivity precautions, as indicated on the packing, must be respected at all times.

Studies have shown that small packages reach higher temperatures during reflow soldering, see Figure 16.

PCA9517A 2

Level translating I²C-bus repeater



For further information on temperature profiles, refer to Application Note AN10365 "Surface mount reflow soldering description".

14. Abbreviations

Table 9.	Abbreviations
Acronym	Description
CDM	Charged-Device Model
CMOS	Complementary Metal-Oxide Silicon
ESD	ElectroStatic Discharge
HBM	Human Body Model
I ² C-bus	Inter Integrated Circuit bus
MM	Machine Model
RC	Resistor-Capacitor network
SMBus	System Management Bus

15. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes			
PCA9517A_2	20080505	Product data sheet	-	PCA9517A_			
Modifications:	• Table 1 "PCA	9517 and PCA9517A compar	ison":				
	 – changed H 	 changed HBM for PCA9517A from "> 6.5 kV" to ">5.5 kV" 					
	 changed MM for PCA9517A from "> 550 V" to "> 450 V" 						
	 Table note 	- Table note [1] re-written					
	 added Tab 	le note [2] and its reference a	at column heading "PCA9	9517A"			
	Section 2 "Fe	• Section 2 "Features", 15 th bullet:					
	 changed from "6500 V HBM" to "5500 V HBM" 						
	 changed f 	rom "550 V MM" to "450 V MM	И"				
	 Updated SME) package soldering informati	on				
PCA9517A 1	20080222	Product data sheet	-	-			

16. Legal information

16.1 Data sheet status

Document status[1][2]	Product status ^[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

[3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL http://www.nxp.com.

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Level translating I²C-bus repeater

18. Contents

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1	General description 1
2	Features 2
3	Ordering information 2
4	Functional diagram 3
5	Pinning information 3
5.1	Pinning
5.2	Pin description 3
6	Functional description 4
6.1	Enable 4
6.2	I ² C-bus systems 4
7	Application design-in information 5
8	Limiting values 8
9	Static characteristics
10	Dynamic characteristics 10
10.1	AC waveforms 11
11	Test information 11
12	Package outline 12
13	Soldering of SMD packages 14
13.1	Introduction to soldering 14
13.2	Wave and reflow soldering 14
13.3	Wave soldering 14
13.4	Reflow soldering 15
14	Abbreviations 16
15	Revision history 17
16	Legal information 18
16.1	Data sheet status 18
16.2	Definitions
16.3	Disclaimers
16.4	Trademarks
17	Contact information 18
18	Contents

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