National Semiconductor

LMV821 Single/ LMV822 Dual/ LMV824 Quad Low Voltage, Low Power, R-to-R Output, 5 MHz Op Amps

General Description

The LMV821/LMV822/LMV824 bring performance and economy to low voltage / low power systems. With a 5 MHz unity-gain frequency and a guaranteed 1.4 V/µs slew rate, the quiescent current is only 220 µA/amplifier (2.7 V). They provide rail-to-rail (R-to-R) output swing into heavy loads (600 Ω Guarantees). The input common-mode voltage range includes ground, and the maximum input offset voltage is 3.5mV (Guaranteed). They are also capable of comfortably driving large capacitive loads (refer to the application notes section).

The LMV821 (single) is available in the ultra tiny SC70-5 package, which is about half the size of the previous title holder, the SOT23-5.

Overall, the LMV821/LMV822/LMV824 (Single/Dual/Quad) are low voltage, low power, performance op amps, that can be designed into a wide range of applications, at an economical price.

Features

(For Typical, 5 V Supply Values; Unless Otherwise Noted) Ultra Tiny, SC70-5 Package 2.0 x 2.0 x 1.0 mm



- Maximum VOS 3.5 mV (Guaranteed)
- VOS Temp. Drift 1 uV/° C
- GBW product @ 2.7 V 5 MHz
- I_{Supply} @ 2.7 V 220 µA/Amplifier

August 1999

85 dB

- Minimum SR 1.4 V/us (Guaranteed) CMRR 90 dB
- PSRR
- Rail-to-Rail (R-to-R) Output Swing 160 mV from rail – @600 Ω Load
 - @10 kΩ Load 55 mV from rail
- -0.3 V to 4.3 V ■ V_{CM} @ 5 V
- Stable with High Capacitive Loads (Refer to Application Section)

Applications

- Cordless Phones
- Cellular Phones
- Laptops
- PDAs
- PCMCIA



	Temperature Range				
Package	Industrial	Packaging Marking	Transport Media	NSC Drawing	
	-40°C to +85°C				
5-Pin SC-70-5	LMV821M7	A15	1k Units Tape and Reel	MAA05	
	LMV821M7X	A15	3k Units Tape and Reel		
5-Pin SOT23-5	LMV821M5	A14	1k UnitsTape and Reel	MA05B	
	LMV821M5X	A14	3k Units Tape and Reel		
8-Pin SO	LMV822M	LMV822M	Rails	M08A	
	LMV822MX	LMV822M	2.5k Units Tape and Reel		
8-Pin MSOP	LMV822MM	LMV822	1k Units Tape and Reel	MUA08A	
	LMV822MMX	LMV822	3.5k Units Tape and Reel		
14-Pin SO	LMV824M	LMV824M	Rails	M14A	
	LMV824MX	LMV824M	2.5k Units Tape and Reel		
14-Pin TSSOP	LMV824MT	LMV824MT	Rails	MTC14	
	LMV824MTX	LMV824MT	2.5k Units Tape and Reel		

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Absolute Maximum Ratings (Note 1)

ESD Tolerance (Note 2) Machine Model

Human Body Model LMV822/824

Differential Input Voltage

Supply Voltage (V+-V -)

Soldering Information

Output Short Circuit to V^+ (Note 3) Output Short Circuit to V^- (Note 3)

Infrared or Convection (20 sec) Storage Temperature Range

Junction Temperature (Note 4)

LMV821

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

Operating Ratings (Note 1)

Supply Voltage	2.5V to 5.5V
Temperature Range	
LMV821, LMV822, LMV824	–40°C ≤T _J ≤85°C
Thermal Resistance (θ_{JA})	
Ultra Tiny SC70-5 Package	440 °C/W
5-Pin Surface Mount	
Tiny SOT23-5 Package 5-Pin	265 °C/W
Surface Mount	
SO Package, 8-Pin Surface	100 1011
Mount	190 °C/W
MSOP Package, 8-Pin Mini Surface Mount	235 °C/W
editate inediti	235 0/00
SO Package, 14-Pin Surface Mount	145 °C/W
TSSOP Package, 14-Pin	155 °C/W
1330F Fachage, 14-FIII	155 C/W

2.7V DC Electrical Characteristics

Unless otherwise specified, all limits guaranteed for $T_J = 25^{\circ}C$. V⁺ = 2.7V, V⁻ = 0V, V_{CM} = 1.0V, V_O = 1.35V and R_L > 1 M Ω . Boldface limits apply at the temperature extremes.

100V

2000V

1500V

5.5V

235°C

150°C

-65°C to 150°C

± Supply Voltage

Symbol	Parameter	Condition	Typ (Note 5)	LMV821/822/824 Limit (Note 6)	Units
V _{os}	Input Offset Voltage		1	3.5	mV
				4	max
TCV _{OS}	Input Offset Voltage Average Drift		1		µV/°C
I _B	Input Bias Current		30	90	nA
				140	max
l _{os}	Input Offset Current		0.5	30	nA
				50	max
CMRR	Common Mode Rejection Ratio	$0V \le V_{CM} \le 1.7V$	85	70	dB
				68	min
+PSRR	Positive Power Supply	$1.7V \le V^+ \le 4V, V^- = 1V, V_O =$	85	75	dB
Rejection Ratio	Rejection Ratio	0V, V _{CM} = 0V		70	min
-PSRR	Negative Power Supply	$-1.0V \le V^- \le -3.3V, V^+ = 1.7V,$	85	73	dB
	Rejection Ratio	V_{O} = 0V, V_{CM} = 0V		70	min
V _{CM}	Input Common-Mode Voltage	For CMRR ≥ 50dB	-0.3	-0.2	V
	Range				max
			2.0	1.9	V
					min
Av	Large Signal Voltage Gain	Sourcing, R_L =600 Ω to 1.35V,	100	90	dB
		V _O =1.35V to 2.2V		85	min
		Sinking, R_L =600 Ω to 1.35V,	90	85	dB
		V _O =1.35V to 0.5V		80	min
		Sourcing, $R_L=2k\Omega$ to 1.35V,	100	95	dB
		V _O =1.35V to 2.2V		90	min
		Sinking, $R_L=2k\Omega$ to 1.35,	95	90	dB
		V _O =1.35 to 0.5V		85	min

Symbol	Parameter	Condition	Typ (Note 5)	LMV821/822/824 Limit (Note 6)	Units
V _o	Output Swing	$V^+=2.7V, R_L=600\Omega$ to 1.35V	2.58	2.50	V
				2.40	min
			0.13	0.20	V
				0.30	max
		V ⁺ =2.7V, R_L = 2k Ω to 1.35V	2.66	2.60	V
				2.50	mir
			0.08	0.120	V
				0.200	ma
С	Output Current	Sourcing, V _O =0V	16	12	mA
					mir
		Sinking, V _O =2.7V	26	12	mA
					mir
5	Supply Current	LMV821 (Single)	0.22	0.3	mA
				0.5	ma
		LMV822 (Dual)	0.45	0.6	mA
				0.8	ma
		LMV824 (Quad)	0.72	1.0	mA
				1.2	max

2.5V DC Electrical Characteristics

Unless otherwise specified, all limits guaranteed for $T_J = 25^{\circ}C$. V⁺ = 2.5V, V⁻ = 0V, V_{CM} = 1.0V, V_O = 1.25V and R_L > 1 M Ω . Boldface limits apply at the temperature extremes.

Symbol	Parameter	Condition	Typ (Note 5)	LMV821/822/824 Limit (Note 6)	Units
Vos	Input Offset Voltage		1	3.5	mV
				4	max
Vo	Output Swing	V ⁺ =2.5V, R_L = 600 Ω to 1.25V	2.37	2.30	V
				2.20	min
			0.13	0.20	V
				0.30	max
		V ⁺ =2.5V, R_L = 2k Ω to 1.25V	2.46	2.40	V
				2.30	min
			0.08	0.12	V
				0.20	max

2.7V AC Electrical Characteristics

Unless otherwise specified, all limits guaranteed for $T_J = 25^{\circ}C$. V⁺ = 2.7V, V⁻ = 0V, V_{CM} = 1.0V, V_O = 1.35V and R_L > 1 M Ω . Boldface limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Typ (Note 5)	LMV821/822/824 Limit (Note 6)	Units
SR	Slew Rate	(Note 7)	1.5		V/µs
GBW	Gain-Bandwdth Product		5		MHz
Φ_{m}	Phase Margin		61		Deg.
G _m	Gain Margin		10		dB
	Amp-to-Amp Isolation	(Note 8)	135		dB
e _n	Input-Related Voltage Noise	$f = 1 \text{ kHz}, V_{CM} = 1V$	28		<u>nV</u> √Hz

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2.7V	AC	Electrical	Characteristics	(Continued)
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Unless otherwise specified, all limits guaranteed for $T_J = 25^{\circ}C$. V⁺ = 2.7V, V⁻ = 0V, V_{CM} = 1.0V, V_O = 1.35V and R_L > 1 M Ω . Boldface limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Typ (Note 5)	LMV821/822/824 Limit (Note 6)	Units
i _n	Input-Referred Current Noise	f = 1 kHz	0.1		<u>pA</u> √Hz
THD	Total Harmonic Distortion	$ f = 1 \text{ kHz}, \text{A}_{\text{V}} = -2, \\ \text{R}_{\text{L}} = 10 \text{k}\Omega, \text{V}_{\text{O}} = 4.1 \text{V}_{\text{PP}} $	0.01		%

5V DC Electrical Characteristics

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Unless otherwise specified, all limits guaranteed for T_J = 25°C. V⁺ = 5V, V⁻ = 0V, V_{CM} = 2.0V, V_O = 2.5V and R $_{L}$ > 1 MΩ. Boldface limits apply at the temperature extremes.

Symbol	Parameter	Condition	Typ (Note 5)	LMV821/822/824 Limit (Note 6)	Units
Vos	Input Offset Voltage		1	3.5	mV
				4.0	max
TCV _{os}	Input Offset Voltage Average Drift		1		µV/°C
I _B	Input Bias Current		40	100	nA
				150	max
l _{os}	Input Offset Current		0.5	30	nA
				50	max
CMRR	Common Mode Rejection Ratio	$0V \le V_{CM} \le 4.0V$	90	72	dB
				70	min
+PSRR	Positive Power Supply	$1.7V \le V^+ \le 4V, V^- = 1V, V_O =$	85	75	dB
	Rejection Ratio	$0V, V_{CM} = 0V$		70	min
-PSRR	Negative Power Supply	$-1.0V \le V^- \le -3.3V, V^+ = 1.7V,$	85	73	dB
	Rejection Ratio	$V_{O} = 0V, V_{CM} = 0V$		70	min
V _{CM}	Input Common-Mode Voltage	For CMRR ≥ 50dB	-0.3	-0.2	V
	Range				max
			4.3	4.2	V
					min
A _V	Large Signal Voltage Gain	Sourcing, R_L =600 Ω to 2.5V,	105	95	dB
		V _O =2.5 to 4.5V		90	min
		Sinking, R_L =600 Ω to 2.5V,	105	95	dB
		V _O =2.5 to 0.5V		90	min
		Sourcing, $R_L=2k\Omega$ to 2.5V,	105	95	dB
		V _O =2.5 to 4.5V		90	min
		Sinking, $R_L=2k\Omega$ to 2.5,	105	95	dB
		V _O =2.5 to 0.5V		90	min
Vo	Output Swing	$V^{+}=5V, R_{L}=600\Omega$ to 2.5V	4.84	4.75	V
				4.70	min
			0.17	0.250	V
				.30	max
		V ⁺ =5V, R_L =2k Ω to 2.5V	4.90	4.85	V
				4.80	min
			0.10	0.15	V
				0.20	max

5V DC Electrical Characteristics (Continued)

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Unless otherwise specified, all limits guaranteed for $T_J = 25^{\circ}C$. V⁺ = 5V, V⁻ = 0V, V_{CM} = 2.0V, V_O = 2.5V and R_L > 1 M Ω . Boldface limits apply at the temperature extremes.

Symbol	Parameter	Condition	Typ (Note 5)	LMV821/822/824 Limit (Note 6)	Units
lo	Output Current	Sourcing, V _O =0V	45	20	mA
				15	min
		Sinking, V _O =5V	40	20	mA
				15	min
Is	Supply Current	LMV821 (Single)	0.30	0.4	mA
				0.6	max
		LMV822 (Dual)	0.5	0.7	mA
				0.9	max
		LMV824 (Quad)	1.0	1.3	mA
				1.5	max

5V AC Electrical Characteristics

Unless otherwise specified, all limits guaranteed for $T_J = 25^{\circ}C$. V⁺ = 5V, V⁻ = 0V, V_{CM} = 2V, V_O = 2.5V and R_L > 1 M Ω . Boldface limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Typ (Note 5)	LMV821/822/824 Limit (Note 6)	Units
SR	Slew Rate	(Note 7)	2.0	1.4	V/µs min
GBW	Gain-Bandwdth Product		5.6		MHz
Φ_{m}	Phase Margin		67		Deg.
G _m	Gain Margin		15		dB
	Amp-to-Amp Isolation	(Note 8)	135		dB
e _n	Input-Related Voltage Noise	$f = 1 \text{ kHz}, V_{CM} = 1 \text{V}$	24		<u>nV</u> √Hz
i _n	Input-Referred Current Noise	f = 1 kHz	0.25		<u>pA</u> √Hz
THD	Total Harmonic Distortion	$ f = 1 \text{ kHz}, \text{A}_{\text{V}} = -2, \\ \text{R}_{\text{L}} = 10 \text{k}\Omega, \text{V}_{\text{O}} = 4.1 \text{V}_{\text{PP}} $	0.01		%

Note 1: Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not guaranteed. For guaranteed specifications and the test conditions, see the Electrical Characteristics. Note 2: Human body model, 1.5 kΩ in series wth 100 pF. Machine model, 200Ω in series with 100 pF.

Note 2: Human body model, 1.5 ks2 in series with 100 pr. Machine model, 2002 in series with 100 pr.

Note 3: Applies to both single-supply and split-supply operation. Continuous short circuit operation at elevated ambient temperature can result in exceeding the maximum allowed junction temperature of 150°C. Output currents in excess of 45 mA over long term may adversely affect reliability.

Note 4: The maximum power dissipation is a function of $T_{J(max)}$, θ_{JA} , and T_A . The maximum allowable power dissipation at any ambient temperature is $P_D = (T_{J^-} (max) - T_A)/\theta_{JA}$. All numbers apply for packages soldered directly into a PC board.

Note 5: Typical Values represent the most likely parametric norm.

Note 6: All limits are guaranteed by testing or statistical analysis.

Note 7: V* = 5V. Connected as voltage follower with 3V step input. Number specified is the slower of the positive and negative slew rates.

Note 8: Input referred, V⁺ = 5V and R_L = 100 k Ω connected to 2.5V. Each amp excited in turn with 1 kHz to produce V $_{O}$ = 3 V_{PP}.





8





APPLICATION NOTE

This application note is divided into two sections: design considerations and Application Circuits.

1.0 Design Considerations

- This section covers the following design considerations:
- 1. Frequency and Phase Response Considerations
- 2. Unity-Gain Pulse Response Considerations
- 3. Input Bias Current Considerations

1.1 Frequency and Phase Response Considerations

The relationship between open-loop frequency response and open-loop phase response determines the closed-loop stability performance (negative feedback). The open-loop phase response causes the feedback signal to shift towards becoming positive feedback, thus becoming unstable. The further the output phase angle is from the input phase angle, the more stable the negative feedback will operate. Phase Margin (ϕ_m) specifies this output-to-input phase relationship at the unity-gain crossover point. Zero degrees of phasemargin means that the input and output are completely in phase with each other and will sustain oscillation at the unity-gain requency.

The AC tables show ϕ_m for a no load condition. But ϕ_m changes with load. The Gain and Phase margin vs Frequency plots in the curve section can be used to graphically determine the ϕ_m for various loaded conditions. To do this, examine the phase angle portion of the plot, find the phase margin point at the unity-gain frequency, and determine how far this point is from zero degree of phase-margin. The larger the phase-margin, the more stable the circuit operation.

The bandwidth is also affected by load. The graphs of *Figure 1* and *Figure 2* provide a quick look at how various loads affect the ϕ_m and the bandwidth of the LMV821/822/824 family. These graphs show capacitive loads reducing both ϕ_m and bandwidth, while resistive loads reduce the bandwidth but increase the ϕ_m . Notice how a 600 Ω resistor can be added in parallel with 220 picofarads capacitance, to increase the ϕ_m 20° (approx.), but at the price of about a 100 kHz of bandwidth.

Overall, the LMV821/822/824 family provides good stability for loaded condition.







FIGURE 2. Unity-Gain Frequency vs Common Mode Voltage for Various Loads

1.2 Unity Gain Pulse Response Considerations

A pull-up resistor is well suited for increasing unity-gain, pulse response stability. For example, a 600 Ω pull-up resistor reduces the overshoot voltage by about 50%, when driving a 220 pF load. *Figure 3* shows how to implement the pull-up resistor for more pulse response stability.



FIGURE 3. Using a Pull-up Resistor at the Output for Stabilizing Capacitive Loads

Higher capacitances can be driven by decreasing the value of the pull-up resistor, but its value shouldn't be reduced beyond the sinking capability of the part. An alternate approach is to use an isolation resistor as illustrated in *Figure 4*.

Figure 5 shows the resulting pulse response from a LMV824, while driving a 10,000pF load through a 20 Ω isolation resistor.



FIGURE 4. Using an Isolation Resistor to Drive Heavy Capacitive Loads



FIGURE 5. Pulse Response per Figure 4

1.3 Input Bias Current Consideration

Input bias current (I_B) can develop a somewhat significant offset voltage. This offset is primarily due to I_B flowing through the negative feedback resistor, R_F. For example, if I_B is 90nA (max room) and R_F is 100 kΩ, then an offset of 9 mV will be developed (V_{OS}=I_Bx R_F).Using a compensation resistor (R_C), as shown in *Figure 6*, cancels out this affect. But the input offset current (I_{OS}) will still contribute to an offset voltage in the same manner - typically 0.05 mV at room temp.



FIGURE 6. Canceling the Voltage Offset Effect of Input Bias Current

2.0 APPLICATION CIRCUITS

This section covers the following application circuits:

- 1. Telephone-Line Transceiver
- 2. "Simple" Mixer (Amplitude Modulator)
- 3. Dual Amplifier Active Filters (DAAFs)
- a. Low-Pass Filter (LPF)
- b. High-Pass Filter (HPF)
- 5. Tri-level Voltage Detector

2.1 Telephone-Line Transceiver

The telephone-line transceiver of *Figure 7* provides a fullduplexed connection through a PCMCIA, miniature transformer. The differential configuration of receiver portion (UR), cancels reception from the transmitter portion (UT). Note that the input signals for the differential configuration of UR, are the transmit voltage (Vt) and Vt/2. This is because R_{match} is chosen to match the coupled telephone-line impedance; therefore dividing Vt by two (assuming R1 >> R_{match}). The differential configuration of UR has its resistors chosen to cancel the Vt and Vt/2 inputs according to the following equation:

$$V_{0} = V_{T} \left(\frac{R_{3}}{R_{3} + R_{4}} \right) \left(1 + \frac{R_{2}}{R_{1}} \right) - \frac{V_{T}}{2} \left(\frac{R_{2}}{R_{1}} \right) = V_{T} \frac{1}{3} \left(3 \right) - \frac{V_{T}}{2} \left(2 \right) = 0$$



FIGURE 7. Telephone-line Transceiver for a PCMCIA Modem Card

Note that Cr is included for canceling out the inadequacies of the lossy, miniature transformer. Refer to application note AN-397 for detailed explanation.

2.2"Simple" Mixer (Amplitude Modulator)

The mixer of *Figure 8* is simple and provides a unique form of amplitude modulation. Vi is the modulation frequency ($F_{\rm M}$), while a +3V square-wave at the gate of Q1, induces a carrier frequency ($F_{\rm C}$). Q1 switches (toggles) U1 between inverting and non-inverting unity gain configurations. Offsetting a sine wave above ground at Vi results in the oscillosscope photo of *Figure 9*.

The simple mixer can be applied to applications that utilize the Doppler Effect to measure the velocity of an object. The difference frequency is one of its output frequency components. This difference frequency magnitude $(/F_{M}-F_{C}/)$ is the key factor for determining an object's velocity per the Doppler Effect. If a signal is transmitted to a moving object, the reflected frequency will be a different frequency. This difference in transmit and receive frequency is directly proportional to an object's velocity.





FIGURE 9. Output signal per the Circuit of Figure 8

2.4 Dual Amplifier Active Filters (DAAFs)

The LMV822/24 bring economy and performance to DAAFs. The low-pass and the high-pass filters of *Figure 10* and *Figure 11* (respectively), offer one key feature: excellent sensitivity performance. Good sensitivity is when deviations in component values cause relatively small deviations in a filfier active filters like the Sallen-Key provide relatively poor sensitivity performance that sometimes cause problems for high production runs; their parameters are much more likely to deviate out of specification than a DAAF would. The DAAFs of *Figure 10* and *Figure 11* are well suited for high volume production.



FIGURE 10. Dual Amplifier, 3 kHz Low-Pass Active Filter with a Butterworth Response and a Pass Band Gain of Times Two





Table 1 provides sensitivity measurements for a 10 M Ω load condition. The left column shows the passive components for the 3 kHz low-pass DAAF. The third column shows the components for the 300 Hz high-pass DAAF. Their respective sensitivity measurements are shown to the right of each component column. Their values consists of the percent change in cutoff frequency (Fc) divided by the percent change in component value. The lower the sensitivity value, the better the performance.

Each resistor value was changed by about 10 percent, and this measured change was divided into the measured change in Fc. A positive or negative sign in front of the measured value, represents the direction Fc changes relative to components' direction of change. For example, a sensitivity value of negative 1.2, means that for a 1 percent increase in component value, Fc decreases by 1.2 percent.

Note that this information provides insight on how to fine tune the cutoff frequency, if necessary. It should be also noted that R_4 and R_5 of each circuit also caused variations in

the pass band gain. Increasing R₄ by ten percent, increased the gain by 0.4 dB, while increasing R₅ by ten percent, decreased the gain by 0.4 dB.

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TABLE 1.

Component (LPF)	Sensitivity (LPF)	Component (HPF)	Sensitivity (HPF)
R _a	-1.2	C _a	-0.7
C ₁	-0.1	R _b	-1.0
R ₂	-1.1	R ₁	+0.1
R ₃	+0.7	C ₂	-0.1
C ₃	-1.5	R ₃	+0.1
R ₄	-0.6	R ₄	-0.1
R ₅	+0.6	R ₅	+0.1

Active filters are also sensitive to an op amp's parameters -Gain and Bandwidth, in particular. The LMV822/24 provide a large gain and wide bandwidth. And DAAFs make excellent use of these feature specifications.

Single Amplifier versions require a large open-loop to closed-loop gain ratio - approximately 50 to 1, at the Fc of the filter response. *Figure 12* shows an impressive photograph of a network analyzer measurement (hp3577A). The measurement was taken from a 300kHz version of *Figure 10*. At 300 kHz, the open-loop to closed-loop gain ratio @ Fc is about 5 to 1. This is 10 times lower than the 50 to 1 "rule of thumb" for Single Amplifier Active Filters.



FIGURE 12. 300 kHz, Low-Pass Filter, Butterworth Response as Measured by the HP3577A Network Analyzer

In addition to performance, DAAFs are relatively easy to design and implement. The design equations for the low-pass and high-pass DAAFs are shown below. The first two equation calculate the Fc and the circuit Quality Factor (Q) for the LPF (*Figure 10*). The second two equations calculate the Fc and Q for the HPF (*Figure 11*).

$$(LPF) \qquad F_{C} = \frac{\sqrt{R_{5}}}{2\pi\sqrt{R_{a}}\cdot\sqrt{R_{2}}\cdot\sqrt{R_{4}}\cdot\sqrt{C_{1}}\cdot\sqrt{C_{3}}}$$

$$Q = 2\pi F_{C}\sqrt{C_{1}}\cdot\sqrt{C_{3}}$$

$$(HPF) \qquad F_{C} = \frac{\sqrt{R_{4}}}{2\pi\sqrt{R_{1}}\cdot\sqrt{R_{3}}\cdot\sqrt{R_{5}}\cdot\sqrt{C_{a}}\cdot\sqrt{C_{2}}}$$

$$Q = 2\pi F_{C}\sqrt{C_{a}}\cdot\sqrt{C_{2}}$$

To simplify the design process, certain components are set equal to each other. Refer to *Figure 10* and *Figure 11*. These equal component values help to simplify the design equations as follows:

(LPF)
$$R_{a} = R_{2} = \frac{1}{2\pi F_{C}\sqrt{C_{1}} \cdot \sqrt{C_{3}}}$$
$$R_{3} = \frac{Q}{2\pi F_{C}\sqrt{C_{1}} \cdot \sqrt{C_{3}}}$$
$$(HPF) \qquad R_{1} = R_{3} = \frac{1}{2\pi F_{C}\sqrt{C_{a}} \cdot \sqrt{C_{2}}}$$
$$R_{b} = \frac{Q}{2\pi F_{C}\sqrt{C_{a}} \cdot \sqrt{C_{2}}}$$

To illustrate the design process/implementation, a 3 kHz, Butterworth response, low-pass filter DAAF (*Figure 10*) is designed as follows:

1. Choose $C_1 = C_3 = C = 1 \text{ nF}$

2. Choose $R_4 = R_5 = 1 k\Omega$

3. Calculate R_a and R_2 for the desired Fc as follows:

$$R_{a} = R_{2} = \frac{1}{2\pi(F_{C})C}$$
$$= \frac{1}{2\pi(3 \text{ kHz}) \ln F}$$
$$= 53.1 \text{ k}\Omega$$
$$\cong 53.6 \text{ k}\Omega \text{ (Practice)}$$

≅ 53.6 kΩ (Practical Value)

4. Calculate $\rm R_3$ for the desired Q. The desired Q for a Butterworth (Maximally Flat) response is 0.707 (45 degrees into the s-plane). $\rm R_3$ calculates as follows:

$$R_{3} = \frac{Q}{2\pi(F_{C})C}$$
$$= \frac{0.707}{2\pi(3 \text{ kHz}) 1 \text{ nF}}$$
$$= 37.5 \text{ k}\Omega$$
$$\cong 37.4 \text{ k}\Omega (Practical Value)$$

Notice that R_3 could also be calculated as 0.707 of R_a or $R_2.$ The circuit was implemented and its cutoff frequency measured. The cutoff frequency measured at 2.92 kHz.

The circuit also showed good repeatability. Ten different LMV822 samples were placed in the circuit. The corresponding change in the cutoff frequency was less than a percent.

2.5 Tri-level Voltage Detector

The tri-level voltage detector of *Figure 13* provides a type of window comparator function. It detects three different input voltage ranges: Min-range, Mid-range, and Max-range. The output voltage (V_O) is at V_{cC} for the Min-range. V_O is clamped at GND for the Mid-range. For the Max-range, V_O is at V_{ee}. *Figure 14* shows a V_O vs. V_I oscilloscope photo per the circuit of *Figure 13*.

Its operation is as follows: V_I deviating from GND, causes the diode bridge to absorb I_{IN} to maintain a clamped condition (V_G= 0V). Eventually, I_{IN} reaches the bias limit of the diode bridge. When this limit is reached, the clamping effect



FIGURE 13. Tri-level Voltage Detector

stops and the op amp responds open loop. The design equation directly preceding *Figure 14*, shows how to determine the clamping range. The equation solves for the input voltage band on each side GND. The mid-range is twice this voltage band.

$$\Delta V = \frac{R}{R_1} (V_{CC} - V_{Diode})$$







SOT-23-5 Tape and Reel Specification

Tape Format

Tape Section	# Cavities	Cavity Status	Cover Tape Status
Leader	0 (min)	Empty	Sealed
(Start End)	75 (min)	Empty	Sealed
Carrier	3000	Filled	Sealed
	250	Filled	Sealed
Trailer	125 (min)	Empty	Sealed
(Hub End)	0 (min)	Empty	Sealed

















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